

ATL02 Product Data Dictionary

Date Generated : 2020-02-03T22:47:57

| Group: / | | |
|-----------------------------------|-------------|---|
| Conventions | (Attribute) | CF-1.6 |
| citation | (Attribute) | SET_BY_META |
| contributor_name | (Attribute) | Thomas E Neumann (thomas.neumann@nasa.gov), Thorsten Markus (thorsten.markus@nasa.gov), Suneel Bhardwaj (suneel.bhardwaj@nasa.gov) David W Hancock III (david.w.hancock@nasa.gov) |
| contributor_role | (Attribute) | Instrument Engineer, Investigator, Principle Investigator, Data Producer, Data Producer |
| creator_name | (Attribute) | SET_BY_META |
| data_rate | (Attribute) | Data within this group pertain to the granule in its entirety. |
| date_created | (Attribute) | SET_BY_PGE |
| date_type | (Attribute) | UTC |
| description | (Attribute) | Science unit converted time ordered telemetry calibrated for instrument effects. All photon events per channel per transmit pulse. Includes Atmosphere raw profiles. Contains s/c location data. |
| featureType | (Attribute) | trajectory |
| geospatial_lat_max | (Attribute) | 0.0 |
| geospatial_lat_min | (Attribute) | 0.0 |
| geospatial_lat_units | (Attribute) | degrees_north |
| geospatial_lon_max | (Attribute) | 0.0 |
| geospatial_lon_min | (Attribute) | 0.0 |
| geospatial_lon_units | (Attribute) | degrees_east |
| granule_type | (Attribute) | ATL02 |
| hdfversion | (Attribute) | SET_BY_PGE |
| history | (Attribute) | SET_BY_PGE |
| identifier_file_uuid | (Attribute) | SET_BY_PGE |
| identifier_product_doi | (Attribute) | 10.5067/ATLAS/ATL02.001 |
| identifier_product_doi_authority | (Attribute) | http://dx.doi.org |
| identifier_product_format_version | (Attribute) | SET_BY_PGE |
| identifier_product_type | (Attribute) | ATL02 |
| institution | (Attribute) | SET_BY_META |
| instrument | (Attribute) | SET_BY_META |
| keywords | (Attribute) | SET_BY_META |
| keywords_vocabulary | (Attribute) | SET_BY_META |
| level | (Attribute) | L1B |
| license | (Attribute) | Data may not be reproduced or distributed without including the citation for this product included in this metadata. Data may not be distributed in an altered form without the written permission of the ICESat-2 Science Project Office at NASA/GSFC. |
| naming_authority | (Attribute) | http://dx.doi.org |
| platform | (Attribute) | SET_BY_META |
| processing_level | (Attribute) | L1B |
| project | (Attribute) | SET_BY_META |
| publisher_email | (Attribute) | SET_BY_META |
| publisher_name | (Attribute) | SET_BY_META |
| publisher_url | (Attribute) | SET_BY_META |
| references | (Attribute) | SET_BY_META |
| short_name | (Attribute) | ATL02 |

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|-------------------------------|-----------------------|---|--|---|
| source | (Attribute) | SET_BY_META | | |
| spatial_coverage_type | (Attribute) | Horizontal | | |
| standard_name_vocabulary | (Attribute) | CF-1.6 | | |
| summary | (Attribute) | SET_BY_META | | |
| time_coverage_duration | (Attribute) | SET_BY_PGE | | |
| time_coverage_end | (Attribute) | SET_BY_PGE | | |
| time_coverage_start | (Attribute) | SET_BY_PGE | | |
| time_type | (Attribute) | CCSDS UTC-A | | |
| title | (Attribute) | SET_BY_META | | |
| Group: /ancillary_data | | | | |
| Description | (Attribute) | Contains information ancillary to the data product. This may include product characteristics, instrument characteristics and/or processing constants. | | |
| data_rate | (Attribute) | Data within this group pertain to the granule in its entirety. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| atlas_sdp_gps_epoch COMPACT | DOUBLE (1) | ATLAS Epoch Offset | seconds since 1980-01-06T00:00:00.000000Z Operations | Number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS Standard Data Product (SDP) epoch (2018-01-01:T00.00.00.000000 UTC). Add this value to delta time parameters to compute full gps_seconds (relative to the GPS epoch) for each data point. |
| control CONTIGUOUS | STRING (1) | Control File | 1 Operations | PGE-specific control file used to generate this granule. To re-use, replace breaks (BR) with linefeeds. |
| data_end_utc COMPACT | STRING (1) | End UTC Time of Granule (CCSDS-A, Actual) | 1 Derived | UTC (in CCSDS-A format) of the last data point within the granule. |
| data_start_utc COMPACT | STRING (1) | Start UTC Time of Granule (CCSDS-A, Actual) | 1 Derived | UTC (in CCSDS-A format) of the first data point within the granule. |
| end_cycle COMPACT | INTEGER (1) | Ending Cycle | 1 Derived | The ending cycle number associated with the data contained within this granule. The cycle number is the counter of the number of 91-day repeat cycles completed by the mission. |
| end_delta_time COMPACT | DOUBLE (1) | ATLAS End Time (Actual) time | seconds since 2018-01-01 Derived | Number of GPS seconds since the ATLAS SDP epoch at the last data point in the file. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| end_geoseg COMPACT | INTEGER (1) | Ending Geolocation Segment | 1 Derived | The ending geolocation segment number associated with the data contained within this granule. ICESat granule geographic regions are further refined by geolocation segments. During the geolocation process, a geolocation segment is created approximately every 20m from the start of the orbit to the end. The geolocation segments help align the ATLAS strong a weak beams and provide a common segment length for the L2 and higher products. The geolocation segment indices differ slightly from orbit-to-orbit because of the irregular shape of the Earth. The geolocation segment indices on ATL01 and ATL02 are only approximate because beams have not been aligned at the time of their creation. |
| end_gpssow COMPACT | DOUBLE (1) | Ending GPS SOW of Granule (Actual) | seconds Derived | GPS seconds-of-week of the last data point in the granule. |
| end_gpsweek COMPACT | INTEGER (1) | Ending GPSWeek of Granule (Actual) | weeks from 1980-01-06 Derived | GPS week number of the last data point in the granule. |
| end_orbit COMPACT | INTEGER (1) | Ending Orbit Number | 1 Derived | The ending orbit number associated with the data contained within this granule. The orbit number increments each time the spacecraft completes a full orbit of the Earth. |
| end_region COMPACT | INTEGER (1) | Ending Region | 1 Derived | The ending product-specific region number associated with the data contained within this granule. ICESat-2 data products are separated by geographic regions. The data contained within a specific region are the same for ATL01 and ATL02. ATL03 regions differ slightly because of different geolocation segment locations caused by the irregular shape of the Earth. The region indices for other products are completely independent. |
| end_rgt COMPACT | INTEGER (1) | Ending Reference Groundtrack | 1 Derived | The ending reference groundtrack (RGT) number associated with the data contained within this granule. There are 1387 reference groundtrack in the ICESat-2 repeat orbit. The reference groundtrack increments each time the spacecraft completes a full orbit of the Earth and resets to 1 each time the spacecraft completes a full cycle. |
| granule_end_utc COMPACT | STRING (1) | End UTC Time of Granule (CCSDS-A, Requested) | 1 Derived | Requested end time (in UTC CCSDS-A) of this granule. |
| granule_start_utc COMPACT | STRING (1) | Start UTC Time of Granule (CCSDS-A, Requested) | 1 Derived | Requested start time (in UTC CCSDS-A) of this granule. |

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| | | Requested) | | |
| qa_at_interval COMPACT | DOUBLE (1) | QA Along-Track Interval | 1 control | Statistics time interval for along-track QA data. |
| release COMPACT | STRING (1) | Release Number | 1 Operations | Release number of the granule. The release number is incremented when the software or ancillary data used to create the granule has been changed. |
| start_cycle COMPACT | INTEGER (1) | Starting Cycle | 1 Derived | The starting cycle number associated with the data contained within this granule. The cycle number is the counter of the number of 91-day repeat cycles completed by the mission. |
| start_delta_time COMPACT | DOUBLE (1) | ATLAS Start Time (Actual) time | seconds since 2018-01-01 Derived | Number of GPS seconds since the ATLAS SDP epoch at the first data point in the file. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| start_geoseg COMPACT | INTEGER (1) | Starting Geolocation Segment | 1 Derived | The starting geolocation segment number associated with the data contained within this granule. ICESat granule geographic regions are further refined by geolocation segments. During the geolocation process, a geolocation segment is created approximately every 20m from the start of the orbit to the end. The geolocation segments help align the ATLAS strong a weak beams and provide a common segment length for the L2 and higher products. The geolocation segment indices differ slightly from orbit-to-orbit because of the irregular shape of the Earth. The geolocation segment indices on ATL01 and ATL02 are only approximate because beams have not been aligned at the time of their creation. |
| start_gpssow COMPACT | DOUBLE (1) | Start GPS SOW of Granule (Actual) | seconds Derived | GPS seconds-of-week of the first data point in the granule. |
| start_gpsweek COMPACT | INTEGER (1) | Start GPSWeek of Granule (Actual) | weeks from 1980-01-06 Derived | GPS week number of the first data point in the granule. |
| start_orbit COMPACT | INTEGER (1) | Starting Orbit Number | 1 Derived | The starting orbit number associated with the data contained within this granule. The orbit number increments each time the spacecraft completes a full orbit of the Earth. |
| start_region COMPACT | INTEGER (1) | Starting Region | 1 Derived | The starting product-specific region number associated with the data contained within this granule. ICESat-2 data products are separated by geographic regions. The data contained within a specific region are the same for ATL01 and ATL02. ATL03 regions differ slightly because of different geolocation segment locations caused by the irregular shape of the Earth. The region indices for other products are completely independent. |
| start_rgt COMPACT | INTEGER (1) | Starting Reference Groundtrack | 1 Derived | The starting reference groundtrack (RGT) number associated with the data contained within this granule. There are 1387 reference groundtrack in the ICESat-2 repeat orbit. The reference groundtrack increments each time the spacecraft completes a full orbit of the Earth and resets to 1 each time the spacecraft completes a full cycle. |
| version COMPACT | STRING (1) | Version | 1 Operations | Version number of this granule within the release. It is a sequential number corresponding to the number of times the granule has been reprocessed for the current release. |
| Group: /ancillary_data/calibrations | | | | |
| Description | (Attribute) | This group contains calibrations derived from the ATLAS CAL products. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| ds_channel CONTIGUOUS | INTEGER_1 (20) | Channel | 1 | Dimension scale for ATLAS PCE channels (1-16=strong, 17-20=weak) |
| ds_fine_counts CONTIGUOUS | INTEGER_1 (75) | Fine Counts | 1 | Dimension scale for ATLAS Time-of-flight fine counts. |
| Group: /ancillary_data/calibrations/dead_time | | | | |
| Description | (Attribute) | CAL42 - Dead-time. Estimates dead time for each ATLAS receiver channel accompanied by an estimated standard deviation for that measurement. photoelectrons/spot/shot, channel-to-channel basis. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal42_product COMPACT | STRING (1) | CAL Product Name | 1 CAL42 | Name of ATLAS CAL Product containing the calibration data |
| side COMPACT | INTEGER (1) | Detector Bank Side | 1 CAL42 | A or B side of the detector bank Flag Values: ['1', '2'] Flag Meanings: ['A', 'B'] |
| temperature COMPACT | FLOAT (1) | Temperature | degreesC CAL42 | Temperature for which calibrations are provided. |
| Group: /ancillary_data/calibrations/dead_time/pcex | | | | |
| Description | (Attribute) | CAL42 - Dead-time. Estimates dead time for each ATLAS receiver channel accompanied by an estimated standard deviation for that measurement. photoelectrons/spot/shot, channel-to-channel basis. | | |
| Label | Datatype | long_name | units | description |

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| (Layout) | (Dimensions) | (standard_name) | source | |
| dead_time COMPACT | DOUBLE (20) | DeadTime | seconds CAL42 | Dead Time (channel) |
| sigma COMPACT | DOUBLE (20) | Sigma | seconds CAL42 | Sigma (channel) |
| Group: /ancillary_data/calibrations/dead_time_radiometric_signal_loss | | | | |
| Description | (Attribute) | CAL34 - Dead-time Radiometric Signal Loss. Contains a table of radiometric corrections versus apparent return strength and width for several dead-time values. Correction is to be multiplied by raw return strength to get corrected return strength | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal34_product CHUNKED | STRING (:) | CAL Product Name | 1 CAL34 | Name of ATLAS CAL Products containing the calibration data |
| dead_time CHUNKED | FLOAT (:) | Dead Time | ns CAL34 | Dead time value |
| rad_corr CHUNKED | DOUBLE (: x : x :) | Radiometric Correction | 1 CAL34 | Radiometric Correction (width, strength, deadtime) |
| strength_strong CHUNKED | DOUBLE (: x :) | Strong Beam Strength | events/shot CAL34 | Strong spot strength in events/shot (strength, deadtime) |
| strength_weak CHUNKED | DOUBLE (: x :) | Weak Beam Strength | events/shot CAL34 | Weak spot strength in events/shot (strength, deadtime) |
| width CHUNKED | DOUBLE (: x :) | Apparent Width | ns CAL34 | Apparent width (width, deadtime) |
| Group: /ancillary_data/calibrations/effective_cell_delay | | | | |
| Description | (Attribute) | CAL17 - PCE Effective Cell Delay. Calibration product for PCE Unit Cell Delay -- a matrix of effective fine counts as a function of temperature, voltage, PCE card, channel, and event edge (rising, falling). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal17_product CHUNKED | STRING (:) | CAL Product Name | 1 CAL17 | Name of ATLAS CAL Product containing the calibration data |
| Group: /ancillary_data/calibrations/effective_cell_delay/pcex | | | | |
| Description | (Attribute) | CAL17 - PCE Effective Cell Delay. Calibration product for PCE Unit Cell Delay -- a matrix of effective fine counts as a function of temperature, voltage, PCE card, channel, and event edge (rising, falling). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal_fall CHUNKED | FLOAT (:) | Call Falling | 1 CAL17 | Cal_fall value which calibrations are provided (indexed by raw_cal_fall/256) |
| cal_rise CHUNKED | FLOAT (:) | Call Rising | 1 CAL17 | Cal_rise value which calibrations are provided (index to raw_cal_rise/256) |
| efc_fall CHUNKED | FLOAT (: x 20 x 75) | EFC Falling | counts CAL17 | Effective Rx falling fine cell count (cell, channel, temp) |
| efc_ll CHUNKED | FLOAT (: x 75) | EFC LL | counts CAL17 | Effective Tx fine cell count for leading lower (cell, temp) |
| efc_ot CHUNKED | FLOAT (: x 75) | EFC Other | counts CAL17 | Effective Tx fine cell count for other (cell, temp) |
| efc_rise CHUNKED | FLOAT (: x 20 x 75) | EFC Rising | counts CAL17 | Effective rising Rx fine cell count (cell, channel, temp) |
| temperature CHUNKED | FLOAT (:) | Temperature | degreesC CAL17 | Temperature for which calibrations are provided. |
| Group: /ancillary_data/calibrations/first_photon_bias | | | | |
| Description | (Attribute) | CAL19 -First Photon Bias. Provides a correction for first photon bias. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal19_product CHUNKED | STRING (:) | CAL Product Name | 1 Derived | Name of ATLAS CAL Products containing the calibration data |
| dead_time | FLOAT | Dead Time | ns | Dead time value |

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| CHUNKED | (:) | | Derived | |
| ffb_corr CHUNKED | DOUBLE (: x : x :) | FFB Correction | 1 Derived | First Photon Bias Correction (width, strength, deadtime) |
| strength_strong CHUNKED | DOUBLE (: x :) | Strong Beam Strength | events/shot Derived | Strong spot strength in events/shot (strength, deadtime) |
| strength_weak CHUNKED | DOUBLE (: x :) | Weak Beam Strength | events/shot Derived | Weak spot strength in events/shot (strength, deadtime) |
| width CHUNKED | DOUBLE (: x :) | Apparent Width | ns Derived | Apparent width (width, deadtime) |

Group: /ancillary_data/calibrations/hv_bias_receiver_radiometric_sensitivity

| Description | (Attribute) | CAL46 - Relationship describing detector responsivity as the PMT high voltage deviates from nominal high voltage setting (V0). | | |
|--------------------------|--------------------------|--|-----------------|--|
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal46_product COMPACT | STRING (1) | CAL Product Name | 1 CAL46 | Name of ATLAS CAL Product containing the calibration data |
| side COMPACT | INTEGER (1) | Detector Bank Side | 1 CAL46 | A or B side of the detector bank Flag Values: ['1', '2'] Flag Meanings: ['A', 'B'] |

Group: /ancillary_data/calibrations/hv_bias_receiver_radiometric_sensitivity/pcex

| Description | (Attribute) | CAL46 - Per-PCE. | | |
|-----------------------------|--------------------------|------------------------------|-----------------|------------------------------------|
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| b_strong COMPACT | FLOAT (1) | b_strong | 1/v CAL46 | Strong spot coefficient b |
| b_weak COMPACT | FLOAT (1) | b_weak | 1/v CAL46 | Weak spot coefficient b |
| c_strong COMPACT | FLOAT (1) | c_strong | 1/v^2 CAL46 | Strong spot coefficient c |
| c_weak COMPACT | FLOAT (1) | c_weak | 1/v^2 CAL46 | Weak spot coefficient c |
| npoints_strong COMPACT | FLOAT (1) | npoints_strong | 1 CAL46 | Strong spot number of points |
| npoints_weak COMPACT | FLOAT (1) | npoints_weak | 1 CAL46 | Weak spot number of points |
| rnom_strong COMPACT | FLOAT (1) | r_nom | 1 CAL46 | Strong spot Rnom |
| rnom_weak COMPACT | FLOAT (1) | r_nom | 1 CAL46 | Weak spot Rnom |
| sigma_b_strong COMPACT | FLOAT (1) | sigma_b_strong | 1/v CAL46 | Strong spot sigma of coefficient b |
| sigma_b_weak COMPACT | FLOAT (1) | sigma_b_weak | 1/v CAL46 | Weak spot sigma of coefficient b |
| sigma_c_strong COMPACT | FLOAT (1) | sigma_c_strong | 1/v^2 CAL46 | Strong spot sigma of coefficient c |
| sigma_c_weak COMPACT | FLOAT (1) | sigma_c_weak | 1/v^2 CAL46 | Weak spot sigma of coefficient c |
| sigma_fit_strong COMPACT | FLOAT (1) | sigma_fit_strong | 1 CAL46 | Strong spot sigma of fit |
| sigma_fit_weak COMPACT | FLOAT (1) | sigma_fit_weak | 1 CAL46 | Weak spot sigma of fit |
| vnom_strong COMPACT | FLOAT (1) | v_nom | v CAL46 | Strong spot nominal voltage |
| vnom_weak | FLOAT | v_nom | v | Weak spot nominal voltage |

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| COMPACT | (1) | | CAL46 | |
| Group: /ancillary_data/calibrations/laser_energy_conversion | | | | |
| Description | (Attribute) | Contains CAL54 - absolute, energy monitor | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| base_temp COMPACT | FLOAT (1) | Base Temperature | degC CAL54 | Base temperature coefficient. |
| cal54_product COMPACT | STRING (1) | CAL File Name | 1 CAL54 | Name of source file containing the calibration data |
| internal COMPACT | DOUBLE (8) | Laser Internal Coeffs | 1 CAL54 | Internal laser monitor coefficients (a_(J),b0_(J/count),b1_(J/degC_count),c0_(J/count^2),c1_(J/degC_count^2),d_(J/count^3),e_(J/count^4),std_of_residuals) |
| lrs COMPACT | DOUBLE (8) | LRS Coeffs | 1 CAL54 | LRS coefficients a_(J),b0_(J/count),b1_(J/degC_count),c0_(J/count^2),c1_(J/degC_count^2),d_(J/count^3),e_(J/count^4),std_of_residuals |
| spd COMPACT | DOUBLE (8) | SPD Coeffs | 1 CAL54 | SPD laser monitor coefficients a_(J),b0_(J/count),b1_(J/degC_count),c0_(J/count^2),c1_(J/degC_count^2),d_(J/count^3),e_(J/count^4),std_of_residuals |
| Group: /ancillary_data/calibrations/laser_energy_fraction | | | | |
| Description | (Attribute) | Contains CAL45 data - Transmit Energy Fraction per Beam | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal45_product COMPACT | STRING (1) | CAL File Name | 1 CAL45 | Name of source file containing the calibration data |
| energy_fract COMPACT | FLOAT (6) | Energy Fraction | 1 CAL45 | Energy Fraction, Per Spot |
| optics_throughput COMPACT | FLOAT (3) | Optics Throughput | 1 CAL45 | Optics Throughput, Per PCE |
| Group: /ancillary_data/calibrations/low_link_impulse_response | | | | |
| Description | (Attribute) | CAL20 - System low link impulse response. Calibrates receiver impulse response, including optical and electrically introduced reflections. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| bin_width COMPACT | FLOAT (1) | Bin Width | seconds CAL20 | Histogram bin width |
| cal20_product COMPACT | STRING (1) | CAL Product Name | 1 CAL20 | Name of ATLAS CAL Product containing the calibration data |
| hist_x CONTIGUOUS | DOUBLE (2000) | Histogram Bin X Values | 1 CAL20 | Histogram bin x-values |
| laser COMPACT | INTEGER (1) | Laser | 1 CAL20 | Laser Number |
| mode COMPACT | INTEGER (1) | Laser Power Setting | 1 CAL20 | Laser Power Setting |
| num_bins COMPACT | INTEGER (1) | Number of Bins | 1 CAL20 | Number of bins in the histogram |
| return_source COMPACT | INTEGER (1) | Return Source | 1 CAL20 | Source of the events from which the data are derived. Flag Values: ['0', '1', '2', '3'] Flag Meanings: ['none', 'tep', 'maat', 'echo'] |
| side COMPACT | INTEGER (1) | A_or_B | 1 CAL20 | A or B Side Component Flag Values: ['1', '2'] Flag Meanings: ['A', 'B'] |
| temperature COMPACT | FLOAT (1) | Temperature | degreesC CAL20 | Temperature for which calibrations are provided. |
| Group: /ancillary_data/calibrations/low_link_impulse_response/pdex | | | | |
| Description | (Attribute) | CAL20 - System low link impulse response. Calibrates receiver impulse response, including optical and electrically introduced reflections. | | |
| Label | Datatype | long_name | units | description |

| (Layout) | (Dimensions) | (standard_name) | source | |
|---|--------------------------|---|----------------------|--|
| hist CONTIGUOUS | DOUBLE (20 x 2000) | Histogram | 1 CAL20 | Per-Channel Histogram |
| total_events COMPACT | INTEGER_8 (20) | Total Events | 1 CAL20 | Number of events used in constructing the per-channel histogram |
| Group: /ancillary_data/calibrations/nominal_rx_sensitivity | | | | |
| Description | (Attribute) | CAL30 - Nominal Rx Sensitivity. Receiver radiometric sensitivity, in an absolute measurement, with all variables (temperature, bias, alignment) set to nominal values. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal30_product COMPACT | STRING (1) | CAL Product Name | 1 CAL30 | Name of ATLAS CAL Product containing the calibration data |
| side COMPACT | INTEGER (1) | Detector Bank Side | 1 CAL30 | A or B side of the detector bank Flag Values: ['1', '2'] Flag Meanings: ['A', 'B'] |
| Group: /ancillary_data/calibrations/nominal_rx_sensitivity/pcex | | | | |
| Description | (Attribute) | CAL30 - Nominal Rx Sensitivity. Receiver radiometric sensitivity, in an absolute measurement, with all variables (temperature, bias, alignment) set to nominal values. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| rms_resid_strong COMPACT | DOUBLE (1) | RMS Residual | 1 CAL30 | Strong spot RMS Residual fraction |
| rms_resid_weak COMPACT | DOUBLE (1) | RMS Residual | 1 CAL30 | Weak spot RMS Residual fraction |
| sdev_strong COMPACT | DOUBLE (1) | sdev_strong | counts/s/pW CAL30 | Strong spot standard deviation |
| sdev_weak COMPACT | DOUBLE (1) | sdev_weak | counts/s/pW CAL30 | Weak spot standard deviation |
| slope_strong COMPACT | DOUBLE (1) | Slope | counts/s/pW CAL30 | Strong spot Slope |
| slope_weak COMPACT | DOUBLE (1) | Slope | counts/s/pW CAL30 | Weak spot Slope |
| Group: /ancillary_data/calibrations/receiver_channel_skews | | | | |
| Description | (Attribute) | CAL49 - Receiver Channel Skews. Timing skews for every rising/fall channel on ATLAS. | | |
| Group: /ancillary_data/calibrations/receiver_channel_skews/pcex | | | | |
| Description | (Attribute) | CAL49 - Receiver Channel Skews. Timing skews for every rising/fall channel on ATLAS. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal49_product COMPACT | STRING (1) | CAL Product Name | 1 CAL49 | Name of ATLAS CAL Product containing the calibration data |
| side COMPACT | INTEGER (1) | Primary_Redundant | 1 CAL49 | Primary or Redundant Component Flag Values: ['1', '2'] Flag Meanings: ['PRIM', 'REDU'] |
| skew_fall COMPACT | FLOAT (20) | Skew_Fall | seconds CAL49 | Per-channel skew (Fall) |
| skew_fall_stderr COMPACT | FLOAT (20) | Skew_Fall StdErr | seconds CAL49 | Standard error of the calculated skew (Fall) |
| skew_rise CONTIGUOUS | FLOAT (20) | Skew_Rise | seconds CAL49 | Per-channel skew (Rise) |
| skew_rise_stderr COMPACT | FLOAT (20) | Skew_Rise StdErr | seconds CAL49 | Standard error of the calculated skew (Rise) |
| temperature COMPACT | FLOAT (1) | Temperature | degreesC CAL49 | Temperature for which calibrations are retrieved. |
| Group: /ancillary_data/calibrations/rx_sensitivity_to_misalignment | | | | |

| Description | (Attribute) | CAL47 - Provides a calibration for Receiver Sensitivity as a function of Transmit-to-Receiver Beam Misalignment. | | |
|--|-----------------------|--|---------------------------|--|
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| azimuth CHUNKED | DOUBLE (:) | Azimuth | microradians CAL47_IMG | Azimuth |
| azimuth_grid_range COMPACT | FLOAT (2) | Azimuth Grid Range | microradians CAL47_IMG | Azimuth Grid Range |
| cal47_product COMPACT | STRING (6) | CAL Product Name | 1 CAL47_IMG | Name of ATLAS CAL Product containing the calibration data |
| elevation CHUNKED | DOUBLE (:) | Elevation | microradians CAL47_IMG | Elevation |
| elevation_grid_range COMPACT | FLOAT (2) | Elevation Grid Range | microradians CAL47_IMG | Elevation Grid Range |
| grid_spacing COMPACT | FLOAT (1) | Grid Spacing | microradians CAL47_IMG | GridSpacing |
| temperature COMPACT | FLOAT (1) | Temperature | degC CAL47_IMG | Reference temperature within the CAL47 product. |
| Group: /ancillary_data/calibrations/rx_sensitivity_to_misalignment/pcex | | | | |
| Description | (Attribute) | CAL47 - Rx Sensitivity as a function of TX-to-IFOV Misalignments. Correlates the residual misalignment of the total 6 beams (given the single BSM AZ/EI mirror) interspersed among AMCS calibrations, to apparent shifts in signal gain. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| rel_intensity_strong CHUNKED | DOUBLE (: x :) | Relative intensity | 1 CAL47_IMG | Strong spot relative intensity |
| rel_intensity_weak CHUNKED | DOUBLE (: x :) | Relative intensity | 1 CAL47_IMG | Weak spot relative intensity |
| Group: /ancillary_data/calibrations/rx_sensitivity_vs_wtom | | | | |
| Description | (Attribute) | CAL61 - Rx Sensitivity vs. WTOM Ratio. Provides parameter values, for each spot, for the fit of Relative Sensitivity based on the reported WTEM through a quadratic curve. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal61_product COMPACT | STRING (1) | CAL Product Name | 1 CAL61 | Name of ATLAS CAL Product containing the calibration data |
| laser COMPACT | INTEGER (1) | Laser | 1 CAL61 | Laser Number |
| mode COMPACT | INTEGER (1) | Laser Power Setting | 1 CAL61 | Laser Power Setting |
| side COMPACT | INTEGER (1) | Detector Bank Side | 1 CAL61 | A or B side of the detector bank Flag Values: ['1', '2'] Flag Meanings: ['A', 'B'] |
| temperature COMPACT | FLOAT (1) | Temperature | degreesC CAL61 | Temperature for which calibrations are provided. |
| Group: /ancillary_data/calibrations/rx_sensitivity_vs_wtom/pcex | | | | |
| Description | (Attribute) | CAL61 - Rx Sensitivity vs. WTOM Ratio. Calibration of receiver throughput as a function of the WTOM/WTEM diode signals (D1, D2) to indicate quality of the spectral tuning of the OFMs (etalons) for each receiver IFOV. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| h_strong COMPACT | DOUBLE (1) | h_strong | 1 CAL61 | h_strong; used in Eqn 5-17. |
| h_weak COMPACT | DOUBLE (1) | h_weak | 1 CAL61 | h_weak; used in Eqn 5-17. |
| rms_of_fit_strong COMPACT | DOUBLE (1) | rms_of_fit_strong | 1 CAL61 | rms_of_fit_strong |
| rms_of_fit_weak | DOUBLE | rms_of_fit_weak | 1 | rms_of_fit_weak |

| | | | | |
|------------------------------|---------------|-------------------|-------------------|---------------------------------|
| COMPACT | (1) | | CAL61 | |
| sdev_h_strong COMPACT | DOUBLE (1) | sdev_h_strong | 1 CAL61 | sdev_h_strong |
| sdev_h_weak COMPACT | DOUBLE (1) | sdev_h_weak | 1 CAL61 | sdev_h_weak |
| sdev_xpeak_strong COMPACT | DOUBLE (1) | sdev_xpeak_strong | 1 CAL61 | sdev_xpeak_strong |
| sdev_xpeak_weak COMPACT | DOUBLE (1) | sdev_xpeak_weak | 1 CAL61 | sdev_xpeak_weak |
| sdev_ypeak_strong COMPACT | DOUBLE (1) | sdev_ypeak_strong | counts/s CAL61 | sdev_ypeak_strong |
| sdev_ypeak_weak COMPACT | DOUBLE (1) | sdev_ypeak_weak | counts/s CAL61 | sdev_ypeak_weak |
| xpeak_strong COMPACT | DOUBLE (1) | xpeak_strong | 1 CAL61 | xpeak_strong; used in Eqn 5-17. |
| xpeak_weak COMPACT | DOUBLE (1) | xpeak_weak | 1 CAL61 | xpeak_weak; used in Eqn 5-17. |
| ypeak_strong COMPACT | DOUBLE (1) | ypeak_strong | counts/s CAL61 | ypeak_strong |
| ypeak_weak COMPACT | DOUBLE (1) | ypeak_weak | counts/s CAL61 | ypeak_weak |

Group: /ancillary_data/calibrations/start_timing_skews

| | | | | |
|--------------------------|--------------------------|--|-------------------|---|
| Description | (Attribute) | CAL44 - Start Timing Skews. Produces START pulse timing skews within & among PCEs to properly align all start pulse timing channels. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal44_product CHUNKED | STRING (:) | CAL Product Name | 1 CAL44 | Name of ATLAS CAL Product containing the calibration data |
| ll1 CHUNKED | FLOAT (:) | LL1 | seconds CAL44 | Leading Lower Skew, PCE1 |
| ll2_ll1 CHUNKED | FLOAT (:) | LL2-LL1 | seconds CAL44 | LL2-LL1 |
| ll3_ll1 CHUNKED | FLOAT (:) | LL3-LL1 | seconds CAL44 | LL3-LL1 |
| lu_ll1 CHUNKED | FLOAT (:) | LU-LL1 | seconds CAL44 | LU-LL1 |
| side COMPACT | INTEGER (1) | SPD Side | 1 CAL44 | A or B side of the Start Pulse Detector Flag Values: ['1', '2'] Flag Meanings: ['A', 'B'] |
| spd_temp CHUNKED | FLOAT (:) | SPD_Temp | degreesC CAL44 | SPD Temperature |
| tl_ll3 CHUNKED | FLOAT (:) | TL-LL3 | seconds CAL44 | TL-LL3 |
| tu_ll2 CHUNKED | FLOAT (:) | TU-LL2 | seconds CAL44 | TU-LL2 |

Group: /ancillary_data/housekeeping

| | | | | |
|-------------------------|--------------------------|--|------------------------|---|
| Description | (Attribute) | Constants and calibrations related to ATLAS housekeeping data. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| det_ab_flag COMPACT | INTEGER (1) | Detector Side, A or B | 1 Derived, L1B ATBD | Indicates if the active detector (DET) is side A (1) or side B (2). Flag Values: ['1', '2'] Flag Meanings: ['a', 'b'] |
| hvpc_ab_flag COMPACT | INTEGER (1) | HVPC Side, A or B | 1 Derived, L1B ATBD | Indicates if the active High Voltage Power Converter (HVPC) is side A (1) or side B (2). |

| | | | | |
|--------------------------|----------------|--------------------|------------------------|---|
| | | | | Flag Values: ['1', '2'] Flag Meanings: ['a', 'b'] |
| laser_12_flag COMPACT | INTEGER (1) | Laser 1 or Laser 2 | 1 Derived, L1B ATBD | Indicates if the active Laser is laser 1 or laser 2. Flag Values: ['1', '2'] Flag Meanings: ['1', '2'] |
| lrs_ab_flag COMPACT | INTEGER (1) | LRS Side A or B | 1 Derived, L1B ATBD | Indicates if the active LRS is side A (1) or side B (2). Flag Values: ['1', '2'] Flag Meanings: ['a', 'b'] |
| pdu_ab_flag COMPACT | INTEGER (1) | PDU Side A or B | 1 Derived, L1B ATBD | Indicates if the active PDU is side a (1) or side b (2). Flag Values: ['1', '2'] Flag Meanings: ['a', 'b'] |
| spd_ab_flag COMPACT | INTEGER (1) | SPD A or B | 1 Derived, L1B ATBD | Indicates if the active Start Pulse Detector (SPD) is side a (1) or side b (2). Flag Values: ['1', '2'] Flag Meanings: ['a', 'b'] |
| tams_ab_flag COMPACT | INTEGER (1) | TAMS Side A or B | 1 Derived, L1B ATBD | Indicates if the active TAMS is side a (1) or side b (2). Flag Values: ['1', '2'] Flag Meanings: ['a', 'b'] |

Group: /ancillary_data/isf

| Description | (Attribute) | Constants and calibrations provided by the ICESat-2 Instrument Support Facility (via ANC27) | | |
|-------------------------------|--------------------------|---|---|---|
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| bias_offset_x COMPACT | DOUBLE (2) | AMCS Bias Offset X | microradians ANC27 (ATBD Section 5.3.3.1) | Zero is center of BSM range: (x,y)=(8000,8000). Used in Eqn 5-13 to generate coordinates that are used in Eqn 5-11 to interpolate CAL 47, which has 1 R grid spacing. |
| bias_offset_y COMPACT | DOUBLE (2) | AMCS Bias Offset Y | microradians ANC27 (ATBD Section 5.3.3.1) | Zero is center of BSM range: (x,y)=(8000,8000). Used in Eqn 5-13 to generate coordinates that are used in Eqn 5-11 to interpolate CAL 47, which has 1 R grid spacing. |
| bias_rate COMPACT | DOUBLE (1) | AMCS bias rate | microradians/undefined_time ANC27 (ATBD Section 5.3.3.1) | Currently a placeholder, not used in calculations. |
| bias_time COMPACT | DOUBLE (2) | AMCS Bias Time | seconds since 2018-01-01 ANC27 (ATBD Section 5.3.3.1) | Times of surrounding AMCS bias corrections |
| cal46_aging COMPACT | DOUBLE (1) | CAL46 Aging Factor | 1 ANC27 (ATBD Section 5.3.14) | CAL46 Aging correction factor |
| start_time_coef COMPACT | DOUBLE (8 x 4) | Start Time Coefficients | ns ANC27 (ATBD Section 3.5.6) | Start time coefficients for TOF center correction (coefficient x scenario) |
| uso_freq_dev COMPACT | DOUBLE (1) | USO Frequency Deviation | hz ANC27 | USO frequency deviation; Used in Eqn 2-4. |
| wtom_alt_tune_corr COMPACT | DOUBLE (1) | WTOM Alt Tuning Correction | 1 ANC27 (ATBD Section 5.3.3.2) | W" in Eqn 5-15. Used only for alternate tuning; method for calculating not defined. |
| wtom_lambda_off COMPACT | DOUBLE (1) | WTOM Wavelength Offset | 1 ANC27 (ATBD Section 5.3.3.2) | WTOM Wavelength Offset. Currently zero. An "off-tuning" value to be used with alternate tuning; method for calculating not defined. |
| wtom_tune_flag COMPACT | INTEGER (1) | WTOM Tuning Flag | 1 ANC27 (ATBD Section 5.3.3.2) | WTOM Tuning Flag (1=standard method, 2=alternate method) Flag Values: ['1', '2'] Flag Meanings: ['std', 'alt'] |

Group: /ancillary_data/tep

| Description | (Attribute) | Contains ancillary values related to TEP detection. | | |
|---------------------------|--------------------------|---|---------------------|--|
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| tep_check_pce1 COMPACT | INTEGER (1) | TEP flag for PCE1. | 1 ATLAS L1B ATBD | Flag indicating that the PCE1 strong channels should be checked for TEP events. Default value is 1 (indicating that TEP is possible on PCE1). A value of 0 indicates that PCE1 data are not examined for TEP. Flag Values: ['0', '1'] Flag Meanings: ['do_not_check', 'check'] |
| tep_check_pce2 | INTEGER | TEP flag for PCE2. | 1 | Flag indicating that the PCE2 strong channels should be checked for TEP events. Default value is 1 (indicating that TEP is |

| | | | | |
|---------------------------|----------------|-----------------------|---------------------------|---|
| COMPACT | (1) | | ATLAS L1B ATBD | possible on PCE2). A value of 0 indicates that PCE2 data are not examined for TEP. Flag Values: ['0', '1'] Flag Meanings: ['do_not_check', 'check'] |
| tep_check_pce3 COMPACT | INTEGER (1) | TEP flag for PCE3. | 1 ATLAS L1B ATBD | Flag indicating that the PCE3 strong channels should be checked for TEP events. Default value is 0 (indicating that TEP is not possible on PCE3). A value of 1 indicates that PCE3 data are examined for TEP (even though the hardware does not support this possibility). Flag Values: ['0', '1'] Flag Meanings: ['do_not_check', 'check'] |
| thres_tep_max COMPACT | DOUBLE (1) | TEP Detection Maximum | seconds ATLAS L1B ATBD | Maximum value used to classify TEP photons. Default value per ATBD is 100ns. (100e-9 sec) |
| thres_tep_min COMPACT | DOUBLE (1) | TEP Detection Minimum | seconds ATLAS L1B ATBD | Minimum value used to classify TEP photons. Default value per ATBD is 0ns. (0e-9 sec) |

Group: /ancillary_data/tod_tof

| | | | | |
|---------------------------------|--------------------------|--|--|---|
| Description | (Attribute) | Contains ancillary parameters related to Time-of-Flight and/or Time-of-Day calculations. | | |
| data_rate | (Attribute) | Data within this group pertain to the granule in its entirety. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal_risefall_box_int COMPACT | DOUBLE (1) | cal_risefall boxcar interval | counts ATLAS L1B ATBD | Boxcar averaging interval for cal_risefall averaging, in major-frame counts. Boxcar averages are using to generate 1D spline coefficients. The spline coefficients are used to create smoothed, interpolated cal_risefall values at the full data rate. |
| cal_uso_scale COMPACT | DOUBLE (1) | Calibration value for USO | 1 ATLAS L1B ATBD | Calibration value for the Ultra Stable Oscillator (USO). Computed using the number of coarse clock ticks measurement generated by the USO between sequential 1PPS time stamps from the on-orbit GPS to estimate the coarse clock ruler scale factor. |
| corr_rx_coarse_pce1 COMPACT | INTEGER (20) | Correction value for PCE1 Rx coarse clock offset | counts ATLAS L1B ATBD | Correction for the PCE1 Receive coarse clock offset. This corrects for the offset between the actual number of coarse clock cycles and the reported number of coarse clock cycles (for each channel). Default value is -1. |
| corr_rx_coarse_pce2 COMPACT | INTEGER (20) | Correction value for PCE2 Rx coarse clock offset | counts ATLAS L1B ATBD | Correction for the PCE2 Receive coarse clock offset. This corrects for the offset between the actual number of coarse clock cycles and the reported number of coarse clock cycles (for each channel). Default value is -1. |
| corr_rx_coarse_pce3 COMPACT | INTEGER (20) | Correction value for PCE3 Rx coarse clock offset | counts ATLAS L1B ATBD | Correction for the PCE3 Receive coarse clock offset. This corrects for the offset between the actual number of coarse clock cycles and the reported number of coarse clock cycles (for each channel). Default value is -1. |
| corr_tx_coarse_pce1 COMPACT | INTEGER (1) | Correction value for PCE1 Tx coarse clock offset | counts ATLAS L1B ATBD | Correction for the PCE1 Transmit coarse clock offset. This corrects for the offset between the actual number of coarse clock cycles and the reported number of coarse clock cycles. Default value is -1. |
| corr_tx_coarse_pce2 COMPACT | INTEGER (1) | Correction value for PCE2 Tx coarse clock offset | counts ATLAS L1B ATBD | Correction for the PCE2 Transmit coarse clock offset. This corrects for the offset between the actual number of coarse clock cycles and the reported number of coarse clock cycles. Default value is -1. |
| corr_tx_coarse_pce3 COMPACT | INTEGER (1) | Correction value for PCE3 Tx coarse clock offset | counts ATLAS L1B ATBD | Correction for the PCE3 Transmit coarse clock offset. This corrects for the offset between the actual number of coarse clock cycles and the reported number of coarse clock cycles. Default value is -1. |
| dt_imet COMPACT | DOUBLE (1) | IMET Clock Tick | seconds/count ATLAS L1B ATBD, Section 4.2.1 | IMET clock tick. |
| dt_t0 COMPACT | DOUBLE (1) | T0 Clock Tick | seconds/count ATLAS L1B ATBD, Section 4.2.1 | T0 clock tick. |
| dt_uso COMPACT | DOUBLE (1) | USO (AMET) Clock Tick | seconds/count ATLAS L1B ATBD, Section 4.2.1 | The AMET clock tick |
| lrs_clock COMPACT | DOUBLE (1) | LRS Clock Rate | seconds/count ATLAS L1B ATBD | The nominal rate of the LRS internal 27 MHz oscillator (divided by 32). |

Group: /atlas

| | | |
|-------------|-------------|---|
| Description | (Attribute) | Group contains the ATLAS EU-converted data |
| data_rate | (Attribute) | Data within this group are stored at the nominal rate of the corresponding ATLAS APIDs (varies per APID). |

Group: /atlas/housekeeping

| | | |
|-------------|-------------|---|
| Description | (Attribute) | Group contains the ATLAS EU-converted housekeeping data |
| data_rate | (Attribute) | Data within this group are stored at the nominal rate of the corresponding ATLAS APIDs (varies per APID). |

| Group: /atlas/housekeeping/laser_energy_internal | | | | |
|--|-----------------------|--|--|--|
| Description | (Attribute) | Internal laser energy from APID 1032 SLA_HK. Packet Frequency is 1 Hertz. | | |
| data_rate | (Attribute) | Data within this group are provided at the packet rate of 1hz. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. The timestamp is computed based on the housekeeping design to sample laser near the asc 1pps internal pulse. (See the L1B ATBD section 5 Radiometric Corrections) |
| e_tx CHUNKED | FLOAT (:) | total laser energy | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Total laser energy derived from the internal laser energy monitor (APID 1032). |
| e_tx_pce1_s CHUNKED | FLOAT (:) | Spot laser energy for PCE1, strong | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE1 strong spot, derived from the internal laser energy monitor and split by calibration. |
| e_tx_pce1_w CHUNKED | FLOAT (:) | Spot laser energy for PCE1, weak | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE1 weak spot, derived from the internal laser energy monitor and split by calibration. |
| e_tx_pce2_s CHUNKED | FLOAT (:) | Spot laser energy for PCE2, strong | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE2 strong spot, derived from the internal laser energy monitor and split by calibration. |
| e_tx_pce2_w CHUNKED | FLOAT (:) | Spot laser energy for PCE2, weak | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE2 weak spot, derived from the internal laser energy monitor and split by calibration. |
| e_tx_pce3_s CHUNKED | FLOAT (:) | Spot laser energy for PCE3, strong | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE3 strong spot, derived from the internal laser energy monitor and split by calibration. |
| e_tx_pce3_w CHUNKED | FLOAT (:) | Spot laser energy for PCE3, weak | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE3 weak spot, derived from the internal laser energy monitor and split by calibration. |
| laser_mode CHUNKED | INTEGER_1 (:) | Laser Mode Setting | 1 ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser Mode setting reported in A_SLA_HK (APID 1032). |
| laser_temp CHUNKED | FLOAT (:) | Laser Temperature | degreesC ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser Temperature. From SLA_HK Telemetry packet (APID 1032, Laser Cmd Code 0xFE LAS-14, raw_lem_temp). |
| Group: /atlas/housekeeping/laser_energy_lrs | | | | |
| Description | (Attribute) | Laser energy derived from LRS Centroid Magnitudes. Packet Frequency is 50 Hertz. | | |
| data_rate | (Attribute) | Data within this group are provided at the packet rate of 50hz. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. The timestamp is computed based on the housekeeping design to sample laser near the asc 1pps internal pulse. (See the L1B ATBD section 5 Radiometric Corrections) |
| e_tx CHUNKED | FLOAT (:) | total laser energy | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Total laser energy from derived from LRS laser centroid magnitudes. |
| e_tx_pce1_s CHUNKED | FLOAT (:) | Spot laser energy for PCE1, strong | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE1 strong spot, derived from LRS laser centroids and split by calibration. |
| e_tx_pce1_w CHUNKED | FLOAT (:) | Spot laser energy for PCE1, weak | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE1 weak spot, derived from LRS laser centroids and split by calibration. |

| | | | | |
|------------------------|--------------|------------------------------------|--|---|
| e_tx_pce2_s CHUNKED | FLOAT (:) | Spot laser energy for PCE2, strong | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE2 strong spot, derived from LRS laser centroids and split by calibration. |
| e_tx_pce2_w CHUNKED | FLOAT (:) | Spot laser energy for PCE2, weak | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE2 weak spot, derived from LRS laser centroids and split by calibration. |
| e_tx_pce3_s CHUNKED | FLOAT (:) | Spot laser energy for PCE3, strong | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE3 strong spot, derived from LRS laser centroids and split by calibration. |
| e_tx_pce3_w CHUNKED | FLOAT (:) | Spot laser energy for PCE3, weak | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE3 weak spot, derived from LRS laser centroids and split by calibration. |
| lrs_temp CHUNKED | FLOAT (:) | Laser Temperature | degreesC ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | LRS Temperature. From A_HKT_C Telemetry packet |

Group: /atlas/housekeeping/laser_energy_spd

| Description | (Attribute) | Laser energy from APID 1063 Analog HK Telemetry. Packet Frequency is 1 Hertz. | | |
|------------------------|--------------------------|---|--|--|
| data_rate | (Attribute) | Data within this group are provided at the packet rate of 1hz. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. The timestamp is computed based on the housekeeping design to sample laser near the asc 1pps internal pulse. (See the L1B ATBD section 5 Radiometric Corrections) |
| ds_10 CONTIGUOUS | INTEGER_1 (10) | DS for 10 measurements | 1 | Dimension scale for 10 measurements. |
| e_tx CHUNKED | FLOAT (: x 10) | total laser energy | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Total laser energy from Analog HK Telemetry packet E (APID 1063). |
| e_tx_pce1_s CHUNKED | FLOAT (: x 10) | Spot laser energy for PCE1, strong | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE1 strong spot, derived from the analog HK telemetry and split by calibration. |
| e_tx_pce1_w CHUNKED | FLOAT (: x 10) | Spot laser energy for PCE1, weak | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE1 weak spot derived from the analog HK telemetry and split by calibration. |
| e_tx_pce2_s CHUNKED | FLOAT (: x 10) | Spot laser energy for PCE2, strong | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE2 strong spot, derived from the analog HK telemetry and split by calibration. |
| e_tx_pce2_w CHUNKED | FLOAT (: x 10) | Spot laser energy for PCE2, weak | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE2 weak spot, derived from the analog HK telemetry and split by calibration. |
| e_tx_pce3_s CHUNKED | FLOAT (: x 10) | Spot laser energy for PCE3, strong | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE3 strong spot, derived from the analog HK telemetry and split by calibration. |
| e_tx_pce3_w CHUNKED | FLOAT (: x 10) | Spot laser energy for PCE3, weak | joules ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser energy for the PCE3 weak spot, derived from the analog HK telemetry and split by calibration. |
| edge_xmtnc CHUNKED | FLOAT (:) | SPD Edge | mV ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | edge_xmtnc. From Analog HK Telemetry packet E (APID 1063). |
| laser_temp CHUNKED | FLOAT (:) | Laser Temperature | degreesC ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Laser Temperature. From A_HKT_C PRIMARY SPD THERMISTOR MED_34 chan[74] or REDUNDANT SPD THERMISTOR MED_35 chan[81] |
| peak_xmtnc CHUNKED | FLOAT (:) | SPD Peak | mV ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | peak_xmtnc. From Analog HK Telemetry packet E (APID 1063). |
| thrhi_rdbk | FLOAT | SPD Upper Thres | volts | Start Pulse Detector (SPD) upper threshold readback value. Reported as an analog voltage whose nominal setting puts |

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|--|--------------------------|---|--|---|
| CHUNKED | (:) | | ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | the threshold at 80% of full laser energy. From Analog HK Telemetry packet E (APID 1063). |
| thrl0_rdbk CHUNKED | FLOAT (:) | SPD Lower Thres | volts ICESat-2 L1B ATBD, Section 5.2, Transmitted Energy | Start Pulse Detector (SPD) lower threshold readback value. Reported as an analog voltage whose nominal setting puts the threshold at 20% of full laser energy. From Analog HK Telemetry packet E (APID 1063). |
| Group: /atlas/housekeeping/mce_position | | | | |
| Description | (Attribute) | MCE Position A/D Packet. Packet Frequency is 200 in Hertz. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source APID. (Nominally 200HZ). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_50 CONTIGUOUS | INTEGER_1 (50) | DS for 50 measurements | 1 | Dimension scale for 50 measurements. |
| mce_az CHUNKED | FLOAT (: x 50) | A MCE AZ | microradians ATL01/atlas/a_mce_pos_1057 and L1B ATBD section MCE | MCE azimuth values. |
| mce_el CHUNKED | FLOAT (: x 50) | MCE EL | microradians ATL01/atlas/a_mce_pos_1057 and L1B ATBD section MCE | MCE elevation values. |
| mce_total_cycles CHUNKED | UINT_4_LE (:) | A MCE total cycles | counts ATL01/atlas/a_mce_pos_1057 | MCE reported total number of cycles |
| Group: /atlas/housekeeping/meb | | | | |
| Description | (Attribute) | Data from APID 1062 Analog HK Telemetry. Packet Frequency is 1 in Hertz. Voltage and current data | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source APID. (Nominally 1HZ). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| hkt_ground_check CHUNKED | FLOAT (:) | Ground check | counts ATL01/atlas/a_hkt_d_1062 converted | Ground check - A_HKT_D.chan[30] |
| hkt_meb_1p5v_asc_v CHUNKED | FLOAT (:) | 1P5VTLM-ASC | volts ATL01/atlas/a_hkt_d_1062 converted | 1P5VTLM-ASC - A_HKT_D.chan[22] |
| hkt_meb_1p5v_mon_v CHUNKED | FLOAT (:) | HKT 1.5V Monitor | volts ATL01/atlas/a_hkt_d_1062 converted | HKT 1.5V Monitor - A_HKT_D.chan[5] |
| hkt_meb_1p5va_pce1_v CHUNKED | FLOAT (:) | 1P5VATLM-PCE1 | volts ATL01/atlas/a_hkt_d_1062 converted | 1P5VATLM-PCE1 - A_HKT_D.chan[23] |
| hkt_meb_1p5va_pce2_v CHUNKED | FLOAT (:) | 1P5VATLM-PCE2 | volts ATL01/atlas/a_hkt_d_1062 converted | 1P5VATLM-PCE2 - A_HKT_D.chan[16] |
| hkt_meb_1p5va_pce3_v CHUNKED | FLOAT (:) | 1P5VATLM-PCE3 | volts ATL01/atlas/a_hkt_d_1062 converted | 1P5VATLM-PCE3 - A_HKT_D.chan[17] |
| hkt_meb_1p5vb_pce1_v CHUNKED | FLOAT (:) | 1P5VBTLM-PCE1 | volts ATL01/atlas/a_hkt_d_1062 converted | 1P5VBTLM-PCE1 - A_HKT_D.chan[24] |
| hkt_meb_1p5vb_pce2_v CHUNKED | FLOAT (:) | 1P5VBTLM-PCE2 | volts ATL01/atlas/a_hkt_d_1062 converted | 1P5VBTLM-PCE2 - A_HKT_D.chan[25] |
| hkt_meb_1p5vb_pce3_v CHUNKED | FLOAT (:) | 1P5VBTLM-PCE3 | volts ATL01/atlas/a_hkt_d_1062 converted | 1P5VBTLM-PCE3 - A_HKT_D.chan[18] |
| hkt_meb_2p5v_pce1_v CHUNKED | FLOAT (:) | 2P5VTLM-PCE1 | volts ATL01/atlas/a_hkt_d_1062 converted | 2P5VTLM-PCE1 - A_HKT_D.chan[19] |
| hkt_meb_2p5v_pce2_v CHUNKED | FLOAT (:) | 2P5VTLM-PCE2 | volts ATL01/atlas/a_hkt_d_1062 converted | 2P5VTLM-PCE2 - A_HKT_D.chan[26] |

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| hkt_meb_2p5v_pce3_v CHUNKED | FLOAT (:) | 2P5VTLM-PCE3 | volts ATL01/atlas/a_hkt_d_1062 converted | 2P5VTLM-PCE3 - A_HKT_D.chan[27] |
| hkt_meb_3p3i_lvpc_i CHUNKED | FLOAT (:) | 3P3ITLM-LVPC | amps ATL01/atlas/a_hkt_d_1062 converted | 3P3ITLM-LVPC - A_HKT_D.chan[12] |
| hkt_meb_3p3v_mon_v CHUNKED | FLOAT (:) | 3.3V Monitor | volts ATL01/atlas/a_hkt_d_1062 converted | 3.3V Monitor - A_HKT_D.chan[6] |
| hkt_meb_5p0i_lvpc_i CHUNKED | FLOAT (:) | 5P0ITLM-LVPC | amps ATL01/atlas/a_hkt_d_1062 converted | 5P0ITLM-LVPC - A_HKT_D.chan[13] |
| hkt_meb_5p0i_sbc_i CHUNKED | FLOAT (:) | 5P0I_SBC_TLM | amps ATL01/atlas/a_hkt_d_1062 converted | 5P0I_SBC_TLM - A_HKT_D.chan[28] |
| hkt_meb_5p0v_sbc_v CHUNKED | FLOAT (:) | 5P0V_SBC_TLM | volts ATL01/atlas/a_hkt_d_1062 converted | 5P0V_SBC_TLM - A_HKT_D.chan[29] |
| hkt_meb_cal_n35p9_t CHUNKED | FLOAT (:) | CAL -35.9 | degreesC ATL01/atlas/a_hkt_d_1062 converted | CAL -35.9 - A_HKT_D.chan[3] |
| hkt_meb_cal_n62p5_t CHUNKED | FLOAT (:) | CAL -62.5 | degreesC ATL01/atlas/a_hkt_d_1062 converted | CAL -62.5 - A_HKT_D.chan[4] |
| hkt_meb_cal_n6p6_t CHUNKED | FLOAT (:) | CAL -6.6 | degreesC ATL01/atlas/a_hkt_d_1062 converted | CAL -6.6 - A_HKT_D.chan[2] |
| hkt_meb_cal_p25_t CHUNKED | FLOAT (:) | CAL +25 | degreesC ATL01/atlas/a_hkt_d_1062 converted | CAL +25 - A_HKT_D.chan[1] |
| hkt_meb_cal_p65p3_t CHUNKED | FLOAT (:) | CAL +65.3 | degreesC ATL01/atlas/a_hkt_d_1062 converted | CAL +65.3 - A_HKT_D.chan[0] |
| hkt_meb_i_uso_i CHUNKED | FLOAT (:) | ITLM-USO | amps ATL01/atlas/a_hkt_d_1062 converted | ITLM-USO - A_HKT_D.chan[15] |
| hkt_meb_n15p0i_lvpc_i CHUNKED | FLOAT (:) | 15P0I_NEG_TLM-LVPC | amps ATL01/atlas/a_hkt_d_1062 converted | 15P0I_NEG_TLM-LVPC - A_HKT_D.chan[21] |
| hkt_meb_n15v_mon_v CHUNKED | FLOAT (:) | -15V Monitor | volts ATL01/atlas/a_hkt_d_1062 converted | -15V Monitor - A_HKT_D.chan[10] |
| hkt_meb_n5a_mon_v CHUNKED | FLOAT (:) | HKT -5A Monitor | volts ATL01/atlas/a_hkt_d_1062 converted | HKT -5A Monitor - A_HKT_D.chan[11] |
| hkt_meb_p15p0i_lvpc_i CHUNKED | FLOAT (:) | 15P0I_POS_TLM-LVPC | amps ATL01/atlas/a_hkt_d_1062 converted | 15P0I_POS_TLM-LVPC - A_HKT_D.chan[20] |
| hkt_meb_p15v_mon_v CHUNKED | FLOAT (:) | +15V Monitor | volts ATL01/atlas/a_hkt_d_1062 converted | +15V Monitor - A_HKT_D.chan[9] |
| hkt_meb_p5a_mon_v CHUNKED | FLOAT (:) | HKT +5A Monitor | volts ATL01/atlas/a_hkt_d_1062 converted | HKT +5A Monitor - A_HKT_D.chan[8] |
| hkt_meb_p5d_mon_v CHUNKED | FLOAT (:) | +5D Monitor | volts ATL01/atlas/a_hkt_d_1062 converted | +5D Monitor - A_HKT_D.chan[7] |
| hkt_meb_v_uso_v CHUNKED | FLOAT (:) | VTLM-USO | volts ATL01/atlas/a_hkt_d_1062 converted | VTLM-USO - A_HKT_D.chan[14] |

Group: /atlas/housekeeping/pdu

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|-----------------------|--------------------------|--|--|---|
| Description | (Attribute) | PDU Analog HK Telemetry. The PDU analog telemetry digitized by the HKT card and collected by the SBC Thermal Control Task. Packet Frequency is 1 in Hertz. Data is from the APID 1059 (Primary) or APID 1060 (Redundant) HK packets. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source APID. (Nominally 1HZ). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP GPS Epoch. This is computed based on the housekeeping design to sample a measurement every 0.003125 seconds from the internal ASC 1PPS . The time for this packet is set as the time of the lowest software channel number in this telemetry packet. If the specific time is needed add to it the difference of its actual ATLAS hardware channel number from the lowest software channel number times the 0.003125 seconds. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| hvpc_mod_1 CHUNKED | FLOAT (:) | HVPC Module 1 | counts ATL01/atlas/a_hkt_a_1059 converted | HVPC Module 1 - A_HKT.chan[70] |

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| hvpc_mod_2 CHUNKED | FLOAT (:) | HVPC Module 2 | counts ATL01/atlas/a_hkt_a_1059 converted | HVPC Module 2 - A_HKT.chan[71] |
| hvpc_mod_3 CHUNKED | FLOAT (:) | HVPC Module 3 | counts ATL01/atlas/a_hkt_a_1059 converted | HVPC Module 3 - A_HKT.chan[72] |
| hvpc_mod_4 CHUNKED | FLOAT (:) | HVPC Module 4 | counts ATL01/atlas/a_hkt_a_1059 converted | HVPC Module 4 - A_HKT.chan[73] |
| hvpc_mod_5 CHUNKED | FLOAT (:) | HVPC Module 5 | counts ATL01/atlas/a_hkt_a_1059 converted | HVPC Module 5 - A_HKT.chan[74] |
| hvpc_mod_6 CHUNKED | FLOAT (:) | HVPC Module 6 | counts ATL01/atlas/a_hkt_a_1059 converted | HVPC Module 6 - A_HKT.chan[75] |
| hvpc_tlm_6 CHUNKED | FLOAT (:) | HVPC TLM 6 | volts ATL01/atlas/a_hkt_a_1059 converted | HVPC TLM 6 - A_HKT.chan[76] |
| hvpc_tlm_7 CHUNKED | FLOAT (:) | HVPC TLM 7 | volts ATL01/atlas/a_hkt_a_1059 converted | HVPC TLM 7 - A_HKT.chan[77] |
| pdu_daa_opts_htr_i CHUNKED | FLOAT (:) | PDU DAA OPTS HTR I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU DAA OPTS HTR I - A_HKT.chan[46] |
| pdu_det_i CHUNKED | FLOAT (:) | PDU DET I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU DET I - A_HKT.chan[23] |
| pdu_det_v CHUNKED | FLOAT (:) | PDU DET V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU DET V - A_HKT.chan[17] |
| pdu_hvpc_i CHUNKED | FLOAT (:) | PDU HVPC I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU HVPC I - A_HKT.chan[24] |
| pdu_laser_1_i CHUNKED | FLOAT (:) | PDU LASER 1 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU LASER 1 I - A_HKT.chan[21] |
| pdu_laser_1_v CHUNKED | FLOAT (:) | PDU LASER 1 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU LASER 1 V - A_HKT.chan[14] |
| pdu_laser_2_i CHUNKED | FLOAT (:) | PDU LASER 2 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU LASER 2 I - A_HKT.chan[22] |
| pdu_laser_2_v CHUNKED | FLOAT (:) | PDU LASER 2 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU LASER 2 V - A_HKT.chan[15] |
| pdu_lhp1_i CHUNKED | FLOAT (:) | PDU LHP1 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU LHP1 I - A_HKT.chan[43] |
| pdu_lhp2_i CHUNKED | FLOAT (:) | PDU LHP2 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU LHP2 I - A_HKT.chan[44] |
| pdu_lhp_startup_htr_i CHUNKED | FLOAT (:) | PDU LHP STARTUP HTR I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU LHP STARTUP HTR I - A_HKT.chan[42] |
| pdu_lrs_i CHUNKED | FLOAT (:) | PDU LRS I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU LRS I - A_HKT.chan[25] |
| pdu_lrs_opts_heater_i CHUNKED | FLOAT (:) | PDU LRS OPTS HEATER I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU LRS OPTS HEATER I - A_HKT.chan[45] |
| pdu_meb_lvpc_i CHUNKED | FLOAT (:) | PDU MEB LVPC I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU MEB LVPC I - A_HKT.chan[26] |
| pdu_meb_lvpc_v CHUNKED | FLOAT (:) | PDU MEB LVPC V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU MEB LVPC V - A_HKT.chan[16] |
| pdu_n3v_dem1_i CHUNKED | FLOAT (:) | PDU N3V DEM1 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU N3V DEM1 I - A_HKT.chan[52] |
| pdu_n3v_dem1_v CHUNKED | FLOAT (:) | PDU N3V DEM1 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU N3V DEM1 V - A_HKT.chan[2] |
| pdu_n3v_dem2_i CHUNKED | FLOAT (:) | PDU N3V DEM2 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU N3V DEM2 I - A_HKT.chan[63] |
| pdu_n3v_dem2_v CHUNKED | FLOAT (:) | PDU N3V DEM2 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU N3V DEM2 V - A_HKT.chan[5] |
| pdu_n3v_dem3_i CHUNKED | FLOAT (:) | PDU N3V DEM3 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU N3V DEM3 I - A_HKT.chan[55] |
| pdu_n3v_dem3_v CHUNKED | FLOAT (:) | PDU N3V DEM3 V | volts | PDU N3V DEM3 V - A_HKT.chan[8] |

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| CHUNKED | (:) | | ATL01/atlas/a_hkt_a_1059 converted | |
| pdu_n3v_dem4_i CHUNKED | FLOAT (:) | PDU N3V DEM4 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU N3V DEM4 I - A_HKT.chan[66] |
| pdu_n3v_dem5_i CHUNKED | FLOAT (:) | PDU N3V DEM5 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU N3V DEM5 I - A_HKT.chan[58] |
| pdu_n3v_dem5_v CHUNKED | FLOAT (:) | PDU N3V DEM5 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU N3V DEM5 V - A_HKT.chan[11] |
| pdu_n3v_dem6_i CHUNKED | FLOAT (:) | PDU N3V DEM6 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU N3V DEM6 I - A_HKT.chan[69] |
| pdu_ofa_n12v_v CHUNKED | FLOAT (:) | PDU OFA N12V V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU OFA N12V V - A_HKT.chan[13] |
| pdu_ofa_p12v_i CHUNKED | FLOAT (:) | PDU OFA P12V I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU OFA P12V I - A_HKT.chan[59] |
| pdu_ofa_p12v_v CHUNKED | FLOAT (:) | PDU OFA P12V V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU OFA P12V V - A_HKT.chan[12] |
| pdu_p3p3v_dem1_i CHUNKED | FLOAT (:) | PDU P3P3V DEM1 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM1 I - A_HKT.chan[51] |
| pdu_p3p3v_dem1_v CHUNKED | FLOAT (:) | PDU P3P3V DEM1 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM1 V - A_HKT.chan[1] |
| pdu_p3p3v_dem2_i CHUNKED | FLOAT (:) | PDU P3P3V DEM2 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM2 I - A_HKT.chan[62] |
| pdu_p3p3v_dem2_v CHUNKED | FLOAT (:) | PDU P3P3V DEM2 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM2 V - A_HKT.chan[4] |
| pdu_p3p3v_dem3_i CHUNKED | FLOAT (:) | PDU P3P3V DEM3 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM3 I - A_HKT.chan[54] |
| pdu_p3p3v_dem3_v CHUNKED | FLOAT (:) | PDU P3P3V DEM3 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM3 V - A_HKT.chan[7] |
| pdu_p3p3v_dem4_i CHUNKED | FLOAT (:) | PDU P3P3V DEM4 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM4 I - A_HKT.chan[65] |
| pdu_p3p3v_dem5_i CHUNKED | FLOAT (:) | PDU P3P3V DEM5 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM5 I - A_HKT.chan[57] |
| pdu_p3p3v_dem5_v CHUNKED | FLOAT (:) | PDU P3P3V DEM5 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM5 V - A_HKT.chan[10] |
| pdu_p3p3v_dem6_i CHUNKED | FLOAT (:) | PDU P3P3V DEM6 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P3P3V DEM6 I - A_HKT.chan[68] |
| pdu_p5v_dem1_i CHUNKED | FLOAT (:) | PDU P5V DEM1 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM1 I - A_HKT.chan[50] |
| pdu_p5v_dem1_v CHUNKED | FLOAT (:) | PDU P5V DEM1 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM1 V - A_HKT.chan[0] |
| pdu_p5v_dem2_i CHUNKED | FLOAT (:) | PDU P5V DEM2 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM2 I - A_HKT.chan[61] |
| pdu_p5v_dem2_v CHUNKED | FLOAT (:) | PDU P5V DEM2 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM2 V - A_HKT.chan[3] |
| pdu_p5v_dem3_i CHUNKED | FLOAT (:) | PDU P5V DEM3 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM3 I - A_HKT.chan[53] |
| pdu_p5v_dem3_v CHUNKED | FLOAT (:) | PDU P5V DEM3 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM3 V - A_HKT.chan[6] |
| pdu_p5v_dem4_i CHUNKED | FLOAT (:) | PDU P5V DEM4 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM4 I - A_HKT.chan[64] |
| pdu_p5v_dem5_i CHUNKED | FLOAT (:) | PDU P5V DEM5 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM5 I - A_HKT.chan[56] |
| pdu_p5v_dem5_v CHUNKED | FLOAT (:) | PDU P5V DEM5 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM5 V - A_HKT.chan[9] |
| pdu_p5v_dem6_i CHUNKED | FLOAT (:) | PDU P5V DEM6 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU P5V DEM6 I - A_HKT.chan[67] |

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| pdu_pwm_tlsp_pri_i CHUNKED | FLOAT (:) | PDU PWM TLSP PRI I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU PWM TLSP PRI I - A_HKT.chan[39] |
| pdu_pwm_tlsp_sec_i CHUNKED | FLOAT (:) | PDU PWM TLSP SEC I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU PWM TLSP SEC I - A_HKT.chan[40] |
| pdu_pwm_tlsp_tower_i CHUNKED | FLOAT (:) | PDU PWM TLSP TOWER I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU PWM TLSP TOWER I - A_HKT.chan[41] |
| pdu_spare_1_v CHUNKED | FLOAT (:) | PDU SPARE 1 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU SPARE 1 V - A_HKT.chan[27] |
| pdu_spare_2_v CHUNKED | FLOAT (:) | PDU SPARE 2 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU SPARE 2 V - A_HKT.chan[28] |
| pdu_spare_3_v CHUNKED | FLOAT (:) | PDU SPARE 3 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU SPARE 3 V - A_HKT.chan[29] |
| pdu_spare_4_v CHUNKED | FLOAT (:) | PDU SPARE 4 V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU SPARE 4 V - A_HKT.chan[30] |
| pdu_spare_5_v CHUNKED | FLOAT (:) | A PDU SPARE 5V | counts ATL01/atlas/a_hkt_a_1059 converted | A_PDU_SPARE_5_V - HKT.chan[60] |
| pdu_spd_n5v_i CHUNKED | FLOAT (:) | PDU SPD N5V I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU SPD N5V I - A_HKT.chan[48] |
| pdu_spd_n5v_v CHUNKED | FLOAT (:) | PDU SPD N5V V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU SPD N5V V - A_HKT.chan[19] |
| pdu_spd_p3p3v_i CHUNKED | FLOAT (:) | PDU SPD P3P3V I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU SPD P3P3V I - A_HKT.chan[49] |
| pdu_spd_p3p3v_v CHUNKED | FLOAT (:) | PDU SPD P3P3V V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU SPD P3P3V V - A_HKT.chan[20] |
| pdu_spd_p5v_i CHUNKED | FLOAT (:) | PDU SPD P5V I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU SPD P5V I - A_HKT.chan[47] |
| pdu_spd_p5v_v CHUNKED | FLOAT (:) | PDU SPD P5V V | volts ATL01/atlas/a_hkt_a_1059 converted | PDU SPD P5V V - A_HKT.chan[18] |
| pdu_tams_i CHUNKED | FLOAT (:) | PDU TAMS I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU TAMS I - A_HKT.chan[31] |
| pdu_tcs_ofa_htr1_i CHUNKED | FLOAT (:) | PDU TCS OFA HTR1 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU TCS OFA HTR1 I - A_HKT.chan[32] |
| pdu_tcs_ofa_htr2_i CHUNKED | FLOAT (:) | PDU TCS OFA HTR2 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU TCS OFA HTR2 I - A_HKT.chan[33] |
| pdu_tcs_ofa_htr3_i CHUNKED | FLOAT (:) | PDU TCS OFA HTR3 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU TCS OFA HTR3 I - A_HKT.chan[34] |
| pdu_tcs_ofa_htr4_i CHUNKED | FLOAT (:) | PDU TCS OFA HTR4 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU TCS OFA HTR4 I - A_HKT.chan[35] |
| pdu_tcs_ofa_htr5_i CHUNKED | FLOAT (:) | PDU TCS OFA HTR5 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU TCS OFA HTR5 I - A_HKT.chan[36] |
| pdu_tcs_ofa_htr6_i CHUNKED | FLOAT (:) | PDU TCS OFA HTR6 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU TCS OFA HTR6 I - A_HKT.chan[37] |
| pdu_tcs_ofa_htr7_i CHUNKED | FLOAT (:) | PDU TCS OFA HTR7 I | amps ATL01/atlas/a_hkt_a_1059 converted | PDU TCS OFA HTR7 I - A_HKT.chan[38] |

Group: /atlas/housekeeping/pointing

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|-----------------------|--------------------------|--|--|---|
| Description | (Attribute) | APID 1138 ATLAS Pointing Message- Spacecraft Attitude and Rates Packet - Relayed to SSR. Packet Frequency is by command. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source APIDs. (only downlinked on command). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| q_sc_i2b_1 CHUNKED | DOUBLE (:) | q_sc_i2b_1 | 1 ATL01/atlas/a_sc_pon_1138 | SC Inertial to ATLAS Body Frame quaternion 1 |

| | | | | |
|-------------------------------|------------------|--------------------|---|---|
| q_sc_i2b_2 CHUNKED | DOUBLE (:) | q_sc_i2b_2 | 1 ATL01/atlas/a_sc_pon_1138 | SC Inertial to ATLAS Body Frame quaternion 2 |
| q_sc_i2b_3 CHUNKED | DOUBLE (:) | q_sc_i2b_3 | 1 ATL01/atlas/a_sc_pon_1138 | SC Inertial to ATLAS Body Frame quaternion 3 |
| q_sc_i2b_4 CHUNKED | DOUBLE (:) | q_sc_i2b_4 | 1 ATL01/atlas/a_sc_pon_1138 | SC Inertial to ATLAS Body Frame quaternion 4 |
| sc_solution_sec CHUNKED | UINT_4_LE (:) | sc_solution_sec | seconds ATL01/atlas/a_sc_pon_1138 | Recorded time of the pointing solution in seconds from the spacecraft epoch |
| sc_solution_subsec CHUNKED | UINT_4_LE (:) | sc_solution_subsec | subseconds ATL01/atlas/a_sc_pon_1138 | Spacecraft recorded time counts - 24 bits, 100 ns per count |
| x_sc_body_rate CHUNKED | DOUBLE (:) | x_sc_body_rate | radians/second ATL01/atlas/a_sc_pon_1138 | SC body rate as measured about the X axis in the ATLAS frame |
| y_sc_body_rate CHUNKED | DOUBLE (:) | y_sc_body_rate | radians/second ATL01/atlas/a_sc_pon_1138 | SC body rate as measured about the Y axis in the ATLAS frame |
| z_sc_body_rate CHUNKED | DOUBLE (:) | z_sc_body_rate | radians/second ATL01/atlas/a_sc_pon_1138 | SC body rate as measured about the Z axis in the ATLAS frame |

Group: /atlas/housekeeping/position_velocity

| Description | (Attribute) | APID 1137 ATLAS Position Message-Spacecraft Position and Velocity Packet - Relayed to SSR. Packet Frequency is in Hertz. | | |
|-------------------------------|--------------------------|--|--|---|
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source APIDs. (only downlinked on command). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| sc_solution_sec CHUNKED | UINT_4_LE (:) | sc_solution_sec | seconds ATL01/atlas/a_sc_pos_1137 | Recorded time of the position/velocity solution in seconds from the spacecraft epoch |
| sc_solution_subsec CHUNKED | UINT_4_LE (:) | sc_solution_subsec | seconds ATL01/atlas/a_sc_pos_1137 | Spacecraft recorded time counts - 24 bits, 100 ns per count |
| x_sc_eci_pos CHUNKED | DOUBLE (:) | x_sc_eci_pos | meters ATL01/atlas/a_sc_pos_1137 | Spacecraft Earth-Centered-Inertial Position: X axis |
| x_sc_eci_vel CHUNKED | DOUBLE (:) | x_sc_eci_vel | meters/second ATL01/atlas/a_sc_pos_1137 | Spacecraft Earth-Centered-Inertial Velocity: X axis |
| y_sc_eci_pos CHUNKED | DOUBLE (:) | y_sc_eci_pos | meters ATL01/atlas/a_sc_pos_1137 | Spacecraft Earth-Centered-Inertial Position: Y axis |
| y_sc_eci_vel CHUNKED | DOUBLE (:) | y_sc_eci_vel | meters/second ATL01/atlas/a_sc_pos_1137 | Spacecraft Earth-Centered-Inertial Velocity: Y axis |
| z_sc_eci_pos CHUNKED | DOUBLE (:) | z_sc_eci_pos | meters ATL01/atlas/a_sc_pos_1137 | Spacecraft Earth-Centered-Inertial Position: Z axis |
| z_sc_eci_vel CHUNKED | DOUBLE (:) | z_sc_eci_vel | meters/second ATL01/atlas/a_sc_pos_1137 | Spacecraft Earth-Centered-Inertial Velocity: Z axis |

Group: /atlas/housekeeping/radiometry

| Description | (Attribute) | The radiometry group contains background and receiver sensitivity | | |
|----------------------------------|--------------------------|---|-------------------------------------|---|
| data_rate | (Attribute) | Data within this group are stored at the data rate of one hertz. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| bg_sensitivity_pce1_s CHUNKED | FLOAT (:) | PCE1 Strong background sensitivity | events/s/Watt ATBD Section 5.5.2 | PCE1, Strong spot - receiver response per watt of continuous illumination in the passband from a diffuse source larger than the field of view, in the absence of any dead time effects. |
| bg_sensitivity_pce1_w CHUNKED | FLOAT (:) | PCE1 Weak background sensitivity | events/s/Watt ATBD Section 5.5.2 | PCE1, Weak spot - receiver response per watt of continuous illumination in the passband from a diffuse source larger than the field of view, in the absence of any dead time effects. |
| bg_sensitivity_pce2_s CHUNKED | FLOAT (:) | PCE2 Strong background sensitivity | events/s/Watt ATBD Section 5.5.2 | PCE2, Strong spot - receiver response per watt of continuous illumination in the passband from a diffuse source larger than the field of view, in the absence of any dead time effects. |
| bg_sensitivity_pce2_w CHUNKED | FLOAT (:) | PCE2 Weak background sensitivity | events/s/Watt ATBD Section 5.5.2 | PCE2, Weak spot - receiver response per watt of continuous illumination in the passband from a diffuse source larger than the field of view, in the absence of any dead time effects. |

| | | | | |
|-----------------------------------|---------------|---------------------------------------|--|--|
| bg_sensitivity_pce3_s CHUNKED | FLOAT (:) | PCE3 Strong background sensitivity | events/s/Watt ATBD Section 5.5.2 | PCE3, Strong spot - receiver response per watt of continuous illumination in the passband from a diffuse source larger than the field of view, in the absence of any dead time effects. |
| bg_sensitivity_pce3_w CHUNKED | FLOAT (:) | PCE3 Weak background sensitivity | events/s/Watt ATBD Section 5.5.2 | PCE3, Weak spot - receiver response per watt of continuous illumination in the passband from a diffuse source larger than the field of view, in the absence of any dead time effects. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via L1B ATBD | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. The timestamp is computed based on the housekeeping design to sample laser near the asc 1pps internal pulse. (See the L1B ATBD section 5 Radiometric Corrections) |
| ret_sensitivity_pce1_s CHUNKED | FLOAT (:) | PCE1 Strong return sensitivity | events/s/Watt ATBD Section 5.5.3 | PCE1, Strong spot - receiver response per joule/return pulse in the field of view, in the absence of any deadtime effects. |
| ret_sensitivity_pce1_w CHUNKED | FLOAT (:) | PCE1 Weak return sensitivity | events/s/Watt ATBD Section 5.5.3 | PCE1, Weak spot - receiver response per joule/return pulse in the field of view, in the absence of any deadtime effects. |
| ret_sensitivity_pce2_s CHUNKED | FLOAT (:) | PCE2 Strong return sensitivity | events/s/Watt ATBD Section 5.5.3 | PCE2, Strong spot - receiver response per joule/return pulse in the field of view, in the absence of any deadtime effects. |
| ret_sensitivity_pce2_w CHUNKED | FLOAT (:) | PCE2 Weak return sensitivity | events/s/Watt ATBD Section 5.5.3 | PCE2, Weak spot - receiver response per joule/return pulse in the field of view, in the absence of any deadtime effects. |
| ret_sensitivity_pce3_s CHUNKED | FLOAT (:) | PCE3 Strong return sensitivity | events/s/Watt ATBD Section 5.5.3 | PCE3, Strong spot - receiver response per joule/return pulse in the field of view, in the absence of any deadtime effects. |
| ret_sensitivity_pce3_w CHUNKED | FLOAT (:) | PCE3 Weak return sensitivity | events/s/Watt ATBD Section 5.5.3 | PCE3, Weak spot - receiver response per joule/return pulse in the field of view, in the absence of any deadtime effects. |

Group: /atlas/housekeeping/status

| Description | (Attribute) | Flags parsed from HKT Status Registers Housekeeping Packet. Packet Frequency is 1 in Hertz. | | |
|-------------------------|--------------------------|---|--|---|
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source APID. (Nominally 1HZ). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| pdua_daa_opt CHUNKED | INTEGER_1 (:) | PDUA_DAA_OPT status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_DAA_OPT status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_det_ps CHUNKED | INTEGER_1 (:) | PDUA_DET_PS status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_DET_PS status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_hvpc CHUNKED | INTEGER_1 (:) | PDUA_HVPC status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_HVPC status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_laser_1 CHUNKED | INTEGER_1 (:) | PDUA_LASER_1 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_LASER_1 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_laser_2 CHUNKED | INTEGER_1 (:) | PDUA_LASER_2 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_LASER_2 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_lhp1 CHUNKED | INTEGER_1 (:) | PDUA_LHP1 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_LHP1 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_lhp2 CHUNKED | INTEGER_1 (:) | PDUA_LHP2 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_LHP2 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |

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| pdua_lhp_startup CHUNKED | INTEGER_1 (:) | PDUA_LHP_STARTUP status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_LHP_STARTUP status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_lrs CHUNKED | INTEGER_1 (:) | PDUA_LRS status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_LRS status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_lrs_opt CHUNKED | INTEGER_1 (:) | PDUA_LRS_OPT status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_LRS_OPT status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_ofa1 CHUNKED | INTEGER_1 (:) | PDUA_OFA1 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_OFA1 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_ofa2 CHUNKED | INTEGER_1 (:) | PDUA_OFA2 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_OFA2 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_ofa3 CHUNKED | INTEGER_1 (:) | PDUA_OFA3 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_OFA3 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_ofa4 CHUNKED | INTEGER_1 (:) | PDUA_OFA4 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_OFA4 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_ofa5 CHUNKED | INTEGER_1 (:) | PDUA_OFA5 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_OFA5 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_ofa6 CHUNKED | INTEGER_1 (:) | PDUA_OFA6 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_OFA6 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_ofa7 CHUNKED | INTEGER_1 (:) | PDUA_OFA7 status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_OFA7 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_ofa_ps CHUNKED | INTEGER_1 (:) | PDUA_OFA_PS status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_OFA_PS status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_pri_mir CHUNKED | INTEGER_1 (:) | PDUA_PRI_MIR status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_PRI_MIR status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_sec_mir CHUNKED | INTEGER_1 (:) | PDUA_SEC_MIR status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_SEC_MIR status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_spare_sig CHUNKED | INTEGER_1 (:) | PDUA_SPARE_SIG status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_SPARE_SIG status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_spd_ps CHUNKED | INTEGER_1 (:) | PDUA_SPD_PS status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_SPD_PS status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_tams_ls CHUNKED | INTEGER_1 (:) | PDUA_TAMS_LS status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_TAMS_LS status flag. 0=ON, 1=OFF |

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| | | | | Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdua_tower CHUNKED | INTEGER_1 (:) | PDUA_TOWER status flag | counts ATL01/atlas/a_hkt_status_1065 converted | PDUA_TOWER status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_daa_opt CHUNKED | INTEGER_1 (:) | PDUB_DAA_OPT status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_DAA_OPT status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_det_ps CHUNKED | INTEGER_1 (:) | PDUB_DET_PS status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_DET_PS status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_hvpc CHUNKED | INTEGER_1 (:) | PDUB_HVPC status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_HVPC status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_laser_1 CHUNKED | INTEGER_1 (:) | PDUB_LASER_1 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_LASER_1 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_laser_2 CHUNKED | INTEGER_1 (:) | PDUB_LASER_2 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_LASER_2 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_lhp1 CHUNKED | INTEGER_1 (:) | PDUB_LHP1 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_LHP1 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_lhp2 CHUNKED | INTEGER_1 (:) | PDUB_LHP2 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_LHP2 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_lhp_startup CHUNKED | INTEGER_1 (:) | PDUB_LHP_STARTUP status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_LHP_STARTUP status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_lrs CHUNKED | INTEGER_1 (:) | PDUB_LRS status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_LRS status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_lrs_opt CHUNKED | INTEGER_1 (:) | PDUB_LRS_OPT status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_LRS_OPT status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_ofa1 CHUNKED | INTEGER_1 (:) | PDUB_OFA1 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_OFA1 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_ofa2 CHUNKED | INTEGER_1 (:) | PDUB_OFA2 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_OFA2 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_ofa3 CHUNKED | INTEGER_1 (:) | PDUB_OFA3 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_OFA3 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_ofa4 CHUNKED | INTEGER_1 (:) | PDUB_OFA4 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_OFA4 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |

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|---------------------------|------------------|-------------------------------|--|--|
| pdub_ofa5 CHUNKED | INTEGER_1 (:) | PDUB_OFA5 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_OFA5 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_ofa6 CHUNKED | INTEGER_1 (:) | PDUB_OFA6 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_OFA6 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_ofa7 CHUNKED | INTEGER_1 (:) | PDUB_OFA7 status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_OFA7 status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_ofa_ps CHUNKED | INTEGER_1 (:) | PDUB_OFA_PS status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_OFA_PS status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_pri_mir CHUNKED | INTEGER_1 (:) | PDUB_PRI_MIR status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_PRI_MIR status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_sec_mir CHUNKED | INTEGER_1 (:) | PDUB_SEC_MIR status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_SEC_MIR status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_spare_sig CHUNKED | INTEGER_1 (:) | PDUB_SPARE_SIG status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_SPARE_SIG status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_spd_ps CHUNKED | INTEGER_1 (:) | PDUB_SPD_PS status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_SPD_PS status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_tams_ls CHUNKED | INTEGER_1 (:) | PDUB_TAMS_LS status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_TAMS_LS status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| pdub_tower CHUNKED | INTEGER_1 (:) | PDUB_TOWER status flag | 1 ATL01/atlas/a_hkt_status_1065 converted | PDUB_TOWER status flag. 0=ON, 1=OFF Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |

Group: /atlas/housekeeping/thermal

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|-----------------------------|--------------------------|---|--|--|
| Description | (Attribute) | Thermal data from APID 1061 Analog HK Telemetry. Packet Frequency is 1 in Hertz. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source APID. (Nominally 1HZ). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. This is computed based on the housekeeping design to sample a measurement every 0.003125 seconds from the internal ASC 1PPS . The time for this packet is set as the time of the lowest channel number in this telemetry packet.. If the specific time is needed use the channel number from the lowest channel in packet. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| hkt_a_beam_px_t CHUNKED | FLOAT (:) | HKT_BEAMX_PX_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | A_HKT_BEAMX_PX_T A_HKT_C.chan[62] |
| hkt_beamx_t CHUNKED | FLOAT (:) | HKT BEAMX T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Beam Expander I/F mTTCS-21 or 30 A_HKT_C.chan[82] |
| hkt_bsm_t CHUNKED | FLOAT (:) | HKT BSM T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT BSM I/F T TCS-20 - A_HKT_C.chan[33] |
| hkt_cchp_adiab_t CHUNKED | FLOAT (:) | HKT CCHP ADIAB T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Laser CCHP Adiabatic Section T TCS-12 A_HKT_C.chan[55] |

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| hkt_cchp_las1_t CHUNKED | FLOAT (:) | HKT CCHP LAS1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Laser 1 I/F T TCS-14 A_HKT_C.chan[59] |
| hkt_dem1_t1_eb_t CHUNKED | FLOAT (:) | HKT_DEM1_T1_EB_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 74 - DEM1_TH_B-MEB-37 External Bottom T A_HKT_C.chan[38] |
| hkt_dem1_t2_it_t CHUNKED | FLOAT (:) | HKT_DEM1_T2_IT_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 76 - DEM1_TH_D-MEB-39 Internal Top T A_HKT_C.chan[40] |
| hkt_dem1_t3_ib_t CHUNKED | FLOAT (:) | HKT_DEM1_T3_IB_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 75 - DEM1_TH_C-MEB-38 Internal Bottom T A_HKT_C.chan[39] |
| hkt_dem1_t4_et_t CHUNKED | FLOAT (:) | HKT_DEM1_T4_ET_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 73 - DEM1_TH_A-MEB-36 External Top T A_HKT_C.chan[37] |
| hkt_dem2_t CHUNKED | FLOAT (:) | HKT_DEM2_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 77 - DEM2_TH_A-MEB-40 External Bottom T A_HKT_C.chan[41] |
| hkt_dem3_t1_eb_t CHUNKED | FLOAT (:) | HKT_DEM3_T1_EB_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 79 - DEM3_TH_B-MEB-42 External Bottom T A_HKT_C.chan[43] |
| hkt_dem3_t2_it_t CHUNKED | FLOAT (:) | HKT_DEM3_T2_IT_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 81 - DEM3_TH_D-MEB-44 Internal Top T A_HKT_C.chan[45] |
| hkt_dem3_t3_ib_t CHUNKED | FLOAT (:) | HKT_DEM3_T3_IB_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 80 - DEM3_TH_C-MEB-43 Internal Bottom T A_HKT_C.chan[44] |
| hkt_dem3_t4_et_t CHUNKED | FLOAT (:) | HKT_DEM3_T4_ET_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 78 - DEM3_TH_A-MEB-41 External Top T A_HKT_C.chan[42] |
| hkt_dem4_t CHUNKED | FLOAT (:) | HKT_DEM4_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 82 - DEM4_TH_A-MEB-45 External Bottom T A_HKT_C.chan[46] |
| hkt_dem5_t1_eb_t CHUNKED | FLOAT (:) | HKT_DEM5_T1_EB_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 84 - DEM5_TH_B-MEB-47 External Bottom T A_HKT_C.chan[48] |
| hkt_dem5_t2_it_t CHUNKED | FLOAT (:) | HKT_DEM5_T2_IT_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 86 - DEM5_TH_D-MEB-49 Internal Top T A_HKT_C.chan[50] |
| hkt_dem5_t3_ib_t CHUNKED | FLOAT (:) | HKT_DEM5_T3_IB_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 85 - DEM5_TH_C-MEB-48 Internal Bottom T A_HKT_C.chan[49] |
| hkt_dem5_t4_et_t CHUNKED | FLOAT (:) | HKT_DEM5_T4_ET_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 83 - DEM5_TH_A-MEB-46 External Top T A_HKT_C.chan[47] |
| hkt_dem6_t CHUNKED | FLOAT (:) | HKT_DEM6_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT A/D Ch 87 - DEM6_TH_A-MEB-50 External Bottom T A_HKT_C.chan[51] |
| hkt_dom_rad1_t CHUNKED | FLOAT (:) | HKT DOM RAD1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT DAA DOM Radiator T (Pri) TCS-47 - A_HKT_C.chan[36] |
| hkt_dom_rad2_t CHUNKED | FLOAT (:) | HKT DOM RAD2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT DAA DOM Radiator T (Red) TCS-48 - A_HKT_C.chan[34] |
| hkt_foldm_t CHUNKED | FLOAT (:) | HKT FOLDM T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Fold Mirror I/F I TCS-22 A_HKT_C.chan[83] |
| hkt_imsc_myflex_t CHUNKED | FLOAT (:) | HKT IMSC MYFLEX T | degreesC ATL01/atlas/a_hkt_c_1061 converted | IMSC Flexure 1 T TCS-28 A_HKT_C.chan[88] |
| hkt_imsc_mzflex_t CHUNKED | FLOAT (:) | HKT IMSC MZFLEX T | degreesC ATL01/atlas/a_hkt_c_1061 converted | IMSC Flexure 2 T TCS-29 A_HKT_C.chan[89] |
| hkt_lasrad_t CHUNKED | FLOAT (:) | HKT LASRAD T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Laser LHP Radiator T TCS_54 A_HKT_C.chan[61] |
| hkt_lhp_evap_t CHUNKED | FLOAT (:) | HKT LHP EVAP T | degreesC ATL01/atlas/a_hkt_c_1061 converted | LHP Evaporator T TCS-15 A_HKT_C.chan[54] |
| hkt_lhp_liqline_t CHUNKED | FLOAT (:) | HKT LHP LIQLINE T | degreesC ATL01/atlas/a_hkt_c_1061 converted | LHP Liquid Line T TCS-16 A_HKT_C.chan[60] |
| hkt_lhp_res1_t CHUNKED | FLOAT (:) | HKT LHP RES1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | LHP Compensation Chamber T (Pri) TCS-10 A_HKT_C.chan[52] |
| hkt_lhp_res2_t CHUNKED | FLOAT (:) | HKT LHP RES2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | LHP Compensation Chamber T (Red) TCS-11 A_HKT_C.chan[53] |
| hkt_lhp_vapline_t CHUNKED | FLOAT (:) | HKT LHP VAPLINE T | degreesC ATL01/atlas/a_hkt_c_1061 converted | A_HKT_LHP_VAPLINE_T TCS-17 A_HKT_C.chan[90] |
| hkt_lrs_orad1_t | FLOAT | HKT LRS ORAD1 T | degreesC | LRS Optics RadiatorT (Pri) TCS-08 A_HKT_C.chan[56] |

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| CHUNKED | (:) | | ATL01/atlas/a_hkt_c_1061 converted | |
| hkt_lrs_orad2_t CHUNKED | FLOAT (:) | HKT LRS ORAD2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | LRS Optics Radiator T (Red) TCS-09 A_HKT_C.chan[57] |
| hkt_lrs_ss_t CHUNKED | FLOAT (:) | HKT LRS SS T | degreesC ATL01/atlas/a_hkt_c_1061 converted | LRS Sunshade I/F T TCS-13 A_HKT_C.chan[58] |
| hkt_ltr_tams_t CHUNKED | FLOAT (:) | HKT LTR TAMS T | degreesC ATL01/atlas/a_hkt_c_1061 converted | TAMS LTR T TCS-18 A_HKT_C.chan[94] |
| hkt_ltr_trans_t CHUNKED | FLOAT (:) | HKT LTR TRANS T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Transmitter LTR T TCS_19 A_HKT_C.chan[102] |
| hkt_meb_asc1_t CHUNKED | FLOAT (:) | HKT MEB ASC1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB ASC1 T MEB-01F - A_HKT_C.chan[0] |
| hkt_meb_asc2_t CHUNKED | FLOAT (:) | HKT MEB ASC2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB ASC2 T MEB-02 - A_HKT_C.chan[1] |
| hkt_meb_hkt_t CHUNKED | FLOAT (:) | HKT MEB HKT T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB HKT T MEB-21 - A_HKT_C.chan[2] |
| hkt_meb_lvpc1_t CHUNKED | FLOAT (:) | HKT MEB LVPC1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB LVPC1 T MEB-03 - A_HKT_C.chan[3] |
| hkt_meb_lvpc2_t CHUNKED | FLOAT (:) | HKT MEB LVPC2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB LVPC2 T MEB-04 - A_HKT_C.chan[4] |
| hkt_meb_mce1_t CHUNKED | FLOAT (:) | HKT MEB MCE1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB MCE1 T MEB-07 - A_HKT_C.chan[5] |
| hkt_meb_mce2_t CHUNKED | FLOAT (:) | HKT MEB MCE2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB MCE2 T MEB-08 - A_HKT_C.chan[6] |
| hkt_meb_mce3_t CHUNKED | FLOAT (:) | HKT MEB MCE3 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB MCE3 T MEB-09 - A_HKT_C.chan[7] |
| hkt_meb_mce4_t CHUNKED | FLOAT (:) | HKT MEB MCE4 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB MCE4 T MEB-10 - A_HKT_C.chan[8] |
| hkt_meb_pce1_1_t CHUNKED | FLOAT (:) | HKT MEB PCE1 1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB PCE1 1 T MEB-11 - A_HKT_C.chan[9] |
| hkt_meb_pce1_2_t CHUNKED | FLOAT (:) | HKT MEB PCE1 2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB PCE1 2 T MEB-12 - A_HKT_C.chan[10] |
| hkt_meb_pce2_1_t CHUNKED | FLOAT (:) | HKT MEB PCE2 1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB PCE2 1 T MEB-13 - A_HKT_C.chan[11] |
| hkt_meb_pce2_2_t CHUNKED | FLOAT (:) | HKT MEB PCE2 2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB PCE2 2 T MEB-14 - A_HKT_C.chan[12] |
| hkt_meb_pce3_1_t CHUNKED | FLOAT (:) | HKT MEB PCE3 1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB PCE3 1 T MEB-15 - A_HKT_C.chan[13] |
| hkt_meb_pce3_2_t CHUNKED | FLOAT (:) | HKT MEB PCE3 2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB PCE3 2 T MEB-16 - A_HKT_C.chan[14] |
| hkt_meb_sbc1_t CHUNKED | FLOAT (:) | HKT MEB SBC1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB SBC1 T MEB-17 - A_HKT_C.chan[15] |
| hkt_meb_sbc2_t CHUNKED | FLOAT (:) | HKT MEB SBC2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB SBC2 T MEB-18 - A_HKT_C.chan[16] |
| hkt_meb_uso1_t CHUNKED | FLOAT (:) | HKT MEB USO1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB USO1 T MEB-19 - A_HKT_C.chan[17] |
| hkt_meb_uso2_t CHUNKED | FLOAT (:) | HKT MEB USO2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT MEB USO2 T MEB-20 - A_HKT_C.chan[18] |
| hkt_ob_mz1_t CHUNKED | FLOAT (:) | HKT OB MZ1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Optical Bench, -Z Side T TCS-23 A_HKT_C.chan[65] |
| hkt_ob_mz2_t CHUNKED | FLOAT (:) | HKT OB MZ2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Optical Bench, -Z Side T TCS-24 A_HKT_C.chan[66] |
| hkt_ob_mz3_t CHUNKED | FLOAT (:) | HKT OB MZ3 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Optical Bench, -Z Side T TCS-25 A_HKT_C.chan[67] |
| hkt_ob_pz1_t CHUNKED | FLOAT (:) | HKT OB PZ1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Optical Bench, +Z Side T TCS-26 A_HKT_C.chan[63] |

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| hkt_ob_pz2_t CHUNKED | FLOAT (:) | HKT OB PZ2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Optical Bench, +Z Side T TCS-27 A_HKT_C.chan[64] |
| hkt_ob_pz3_t CHUNKED | FLOAT (:) | HKT_OB_PZ3_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Optical Bench +z3 T TCS_31 A_HKT_C.chan[103] |
| hkt_ob_pz4_t CHUNKED | FLOAT (:) | HKT_OB_PZ4_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Optical Bench +z4 T TCS_32 A_HKT_C.chan[105] |
| hkt_ofa1_et_t CHUNKED | FLOAT (:) | HKT_OFA1_ET_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | OFA1 ETALON T TCS_58 A_HKT_C.chan[104] |
| hkt_ofa1_pri_t CHUNKED | FLOAT (:) | HKT OFA1 PRI T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-33 OFA1 PRI T - A_HKT_C.chan[19] |
| hkt_ofa1_red_t CHUNKED | FLOAT (:) | HKT OFA1 RED T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-34 OFA1 RED T - A_HKT_C.chan[26] |
| hkt_ofa2_pri_t CHUNKED | FLOAT (:) | HKT OFA2 PRI T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-35 OFA2 PRI T - A_HKT_C.chan[20] |
| hkt_ofa2_red_t CHUNKED | FLOAT (:) | HKT OFA2 RED T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-36 OFA2 RED T - A_HKT_C.chan[27] |
| hkt_ofa3_pri_t CHUNKED | FLOAT (:) | HKT OFA3 PRI T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-37 OFA3 PRI T - A_HKT_C.chan[21] |
| hkt_ofa3_red_t CHUNKED | FLOAT (:) | HKT OFA3 RED T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-38 OFA3 RED T - A_HKT_C.chan[28] |
| hkt_ofa4_pri_t CHUNKED | FLOAT (:) | HKT OFA4 PRI T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-39 OFA4 PRI T - A_HKT_C.chan[22] |
| hkt_ofa4_red_t CHUNKED | FLOAT (:) | HKT OFA4 RED T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-40 OFA4 RED T - A_HKT_C.chan[29] |
| hkt_ofa5_pri_t CHUNKED | FLOAT (:) | HKT OFA5 PRI T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-41 OFA5 PRI T - A_HKT_C.chan[23] |
| hkt_ofa5_red_t CHUNKED | FLOAT (:) | HKT OFA5 RED T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-42 OFA5 RED T - A_HKT_C.chan[30] |
| hkt_ofa6_pri_t CHUNKED | FLOAT (:) | HKT OFA6 PRI T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-43 OFA6 PRI T - A_HKT_C.chan[24] |
| hkt_ofa6_red_t CHUNKED | FLOAT (:) | HKT OFA6 RED T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-44 OFA6 RED T - A_HKT_C.chan[31] |
| hkt_ofa7_et_t CHUNKED | FLOAT (:) | HKT_OFA7_ET_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | OFA7 ETALON T TCS_59 A_HKT_C.chan[106] |
| hkt_ofa7_pri_t CHUNKED | FLOAT (:) | HKT OFA7 PRI T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-45 OFA7 PRI T - A_HKT_C.chan[25] |
| hkt_ofa7_red_t CHUNKED | FLOAT (:) | HKT OFA7 RED T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT TCS-46 OFA7 RED T - A_HKT_C.chan[32] |
| hkt_scif_myflex_t CHUNKED | FLOAT (:) | HKT SCIF MYFLEX T | degreesC ATL01/atlas/a_hkt_c_1061 converted | -Y S/C Flexure T A_HKT_C.chan[93] |
| hkt_scif_pxflex_t CHUNKED | FLOAT (:) | HKT SCIF PXFLEX T | degreesC ATL01/atlas/a_hkt_c_1061 converted | +X S/C Flexure T TCS-51 A_HKT_C.chan[87] |
| hkt_scif_pyflex_t CHUNKED | FLOAT (:) | HKT SCIF PYFLEX T | degreesC ATL01/atlas/a_hkt_c_1061 converted | +Y S/C Flexure T TCS-53 A_HKT_C.chan[101] |
| hkt_spd_t CHUNKED | FLOAT (:) | HKT SPD T | degreesC ATL01/atlas/a_hkt_c_1061 converted | SPD I/F T TCS-50 A_HKT_C.chan[85] |
| hkt_struc_my_t CHUNKED | FLOAT (:) | HKT STRUC MY T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Structure Y Panel T TCS_55 A_HKT_C.chan[91] |
| hkt_struc_mz_t CHUNKED | FLOAT (:) | HKT STRUC MZ T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Structure Z Panel T TCS_57 A_HKT_C.chan[92] |
| hkt_sunshade_t CHUNKED | FLOAT (:) | HKT_SUNSHADE_T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Structure +Z Panel T A_HKT_C.chan[86] |
| hkt_tel_pri1_t CHUNKED | FLOAT (:) | HKT TEL PRI1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Telescope, Primary Mirror T (Pri) TCS-05 A_HKT_C.chan[95] |
| hkt_tel_pri2_t | FLOAT | HKT TEL PRI2 T | degreesC | Telescope, Primary Mirror T (Red) TCS-06 A_HKT_C.chan[96] |

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| CHUNKED | (:) | | ATL01/atlas/a_hkt_c_1061 converted | |
| hkt_tel_pri3_t CHUNKED | FLOAT (:) | HKT TEL PRI3 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | HKT Telescope, Primary Mirror T TCS-07 - A_HKT_C.chan[35] |
| hkt_tel_sec1_t CHUNKED | FLOAT (:) | HKT TEL SEC1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Telescope, Secondary Mirror T (Pri) TCS-01 A_HKT_C.chan[97] |
| hkt_tel_sec2_t CHUNKED | FLOAT (:) | HKT TEL SEC2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Telescope, Secondary Mirror T (Red) TCS-02 A_HKT_C.chan[98] |
| hkt_tel_tow1_t CHUNKED | FLOAT (:) | HKT TEL TOW1 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Telescope, Tower T (Pri) TCS-03 A_HKT_C.chan[99] |
| hkt_tel_tow2_t CHUNKED | FLOAT (:) | HKT TEL TOW2 T | degreesC ATL01/atlas/a_hkt_c_1061 converted | Telescope, Tower T (Red) TCS-04 A_HKT_C.chan[100] |
| hkt_wtem_t CHUNKED | FLOAT (:) | HKT WTEM T | degreesC ATL01/atlas/a_hkt_c_1061 converted | OFA WTEM I/F T TCS-49 A_HKT_C.chan[84] |
| hvpca_therm_a_t CHUNKED | FLOAT (:) | HVPCTHERM T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PRIMARY HVPC THERMISTOR A MEB-30 A_HKT_C.chan[68] |
| hvpca_therm_b_t CHUNKED | FLOAT (:) | HVPCTHERM B T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PRIMARY HVPC THERMISTOR B MEB-32 A_HKT_C.chan[69] |
| hvpcb_therm_a_t CHUNKED | FLOAT (:) | HVPCB THERM T | degreesC ATL01/atlas/a_hkt_c_1061 converted | REDUNDANT HVPC THERMISTOR A MEB-31 A_HKT_C.chan[75] |
| hvpcb_therm_b_t CHUNKED | FLOAT (:) | HVPCB THERM B T | degreesC ATL01/atlas/a_hkt_c_1061 converted | REDUNDANT HVPC THERMISTOR B MEB-33 A_HKT_C.chan[76] |
| pdua_therm_ct_t CHUNKED | FLOAT (:) | PDUTHERM CT T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PDU CT BOARD A T-MEB-24 A_HKT_C.chan[70] |
| pdua_therm_dlv_a_t CHUNKED | FLOAT (:) | PDUTHERM DLV T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PDU LOW VOLTAGE 1A T-MEB-26 A_HKT_C.chan[71] |
| pdua_therm_dlv_b_t CHUNKED | FLOAT (:) | PDUTHERM DLV B T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PDU LOW VOLTAGE 2A T -MEB-28 A_HKT_C.chan[72] |
| pdua_therm_mi_t CHUNKED | FLOAT (:) | PDUTHERM MI T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PDU MAIN PWR BOARD A T-MEB_22 A_HKT_C.chan[73] |
| pdeb_therm_ct_t CHUNKED | FLOAT (:) | PDUB THERM CT T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PDU CT BOARD B T -MEB-25 A_HKT_C.chan[77] |
| pdeb_therm_dlv_a_t CHUNKED | FLOAT (:) | PDUB THERM DLV T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PDU LOW VOLTAGE 1B T -MEB-27 A_HKT_C.chan[78] |
| pdeb_therm_dlv_b_t CHUNKED | FLOAT (:) | PDUB THERM DLV B T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PDU LOW VOLTAGE 2B T -MEB-29 A_HKT_C.chan[79] |
| pdeb_therm_mi_t CHUNKED | FLOAT (:) | PDUB THERM MI T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PDU MAIN PWR BOARD B T -MEB_23 A_HKT_C.chan[80] |
| spda_therm_t CHUNKED | FLOAT (:) | SPDTHERM T | degreesC ATL01/atlas/a_hkt_c_1061 converted | PRIMARY SPD THERMISTOR MEB-34 A_HKT_C.chan[74] |
| spdb_therm_t CHUNKED | FLOAT (:) | SPDB THERM T | degreesC ATL01/atlas/a_hkt_c_1061 converted | REDUNDANT SPD THERMISTOR MEB-35 A_HKT_C.chan[81] |

Group: /atlas/housekeeping/time_at_the_tone

| | | | | |
|----------------------------|--------------------------|---|--|---|
| Description | (Attribute) | APID 1136 Spacecraft Time at the Tone Packet - Relayed to SSR. Packet Frequency is by command. ATLAS Time-At-The-Tone-Was Message | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source APIDs. (only downlinked on command). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| gps_1pps_sec CHUNKED | UINT_4_LE (:) | gps 1pps | seconds since January 6, 1980 ATL01/APIID 1136 Byte 0014-0017 | GPS reported seconds. |
| gps_1pps_subsec CHUNKED | UINT_4_LE (:) | gps 1pps subsec | milliseconds ATL01/APIID 1136 Byte 0014-0017 | GPS reported subseconds |

| | | | | |
|---|--------------------------|---|--|--|
| sc_time_1pps_sec CHUNKED | UINT_4_LE (:) | SC time at 1 pps | seconds since January 6, 1980 ATL01/APIID 1136 Byte 0014-0017 | SC time at the reception of the last 1PPS signal from the GPSR. |
| sc_time_1pps_subsec CHUNKED | UINT_4_LE (:) | SC time at 1 pps (subsec) | 100 nanoseconds ATL01/APIID 1136 Byte 0014-0017 | Subsecond portion of the SC time at the reception of the last 1PPS signal from the GPSR (seconds since SC epoch: 6-Jan-1980 00:00:00) |
| Group: /atlas/pcex | | | | |
| Description | (Attribute) | Group contains the Photon Counting Electronics x (PCEx) packet decommutated data | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source PCE Data Packets. (nominally fifty per second.) | | |
| Group: /atlas/pcex/algorithm_science | | | | |
| Description | (Attribute) | The PCE PMF Algorithm Science data group. Contains outputs from the onboard receiver algorithm software. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source PCE Altimetric Data Packets. (nominally fifty per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| amet_time CHUNKED | DOUBLE (:) | AMET seconds at the Major Frame | seconds ATL01/atlas/pcex/a_pmf_algorithm_science | AMET seconds at the Major Frame |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via L1B ATBD | The time of the first TX pulse in the major frame, relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| gps_time CHUNKED | DOUBLE (:) | GPS seconds at the Major Frame | seconds ATL01/atlas/pcex/a_pmf_algorithm_science | GPS seconds at the Major Frame |
| pce_mframe_cnt CHUNKED | UINT_4_LE (:) | PCE Major frame counter | counts ATL01/atlas/pcex/a_pmf_algorithm_science | Major Frame ID - The major frame ID is read from the DFC and starts counting at DFC POR. The counter is used to identify individual major frames across diag and science packets. This counter can go for about 2.7 years before rolling over. |
| useflag CHUNKED | UINT_1_LE (:) | Science Mode Flag | counts ATL01/atlas/pcex/a_alt_sci/ | Science Mode Flag. Used by ATL03 to discard non-science mode data. 0=stby, 1=science_mode, 2=test, 3>manual, 4=radio, 5=unknown, > 10=amcs_not_normal Flag Values: ['0', '1', '2', '3', '4', '5', '6', '7', '8', '9', '10', '11', '12', '13', '14', '15'] Flag Meanings: ['stby', 'science', 'test', 'manual', 'radio', 'unknown', 'unused', 'unused', 'unused', 'unused', 'stby_alt_amcs', 'science_alt_amcs', 'test_alt_amcs', 'unknown_alt_amcs'] |
| Group: /atlas/pcex/algorithm_science/s_w | | | | |
| Description | (Attribute) | The PCE PMF Algorithm Science data group. Contains outputs from the onboard receiver algorithm software. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source PCE Altimetric Data Packets. (nominally fifty per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| daynight_flag CHUNKED | UINT_1_LE (:) | Day/Night flag | counts ATL01/atlas/pcex/a_pmf_algorithm_science | ATLAS flight software Day/Night Flag associated with the major frame. 0= day, 1 =night. Based on an algorithm determination of the background rate, not on the actual position of the sun. Flag Values: ['0', '1'] Flag Meanings: ['day', 'night'] |
| decisionflags CHUNKED | UINT_1_LE (: x 4) | Decision Flags | counts ATL01/atlas/pcex/a_pmf_algorithm_science | ATLAS flight s/w Decision Flags associated with the major frame. indication if there was an error or if no science data is sent and why |
| ds_4bytes CONTIGUOUS | INTEGER_1 (4) | DS for 4 bytes | 1 | Dimension scale for an array of 4 bytes. |
| flywheel CHUNKED | UINT_1_LE (:) | Flywheel | counts ATL01/atlas/pcex/a_pmf_algorithm_science | ATLAS flight software Flywheel associated with the major frame. |
| signalfags CHUNKED | UINT_1_LE (:) | Signal Found Flags | counts ATL01/atlas/pcex/a_pmf_algorithm_science | ATLAS flight s/w signal event flags associated with the major frame. |
| Group: /atlas/pcex/altimetry | | | | |
| Description | (Attribute) | The PCE Altimetry Science Packet data common to both beams (PCEx_ALT_SCI_TLM_MID in APID 1254, 1264, 1274 sequence flag 01 (once per major frame). (see ICESat-2-MEB-SPEC-0875, section 5.12, Spacewire: Major Frame Packet Data Format | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source PCE Altimetric Data Packets. (nominally fifty per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cal_fall_sm | FLOAT | Altimetric Latest | seconds/cell | The smoothed, calibrated value for the falling edge used to convert cell counts to units of time. time per cell count based |

| | | | | |
|---------------------------------------|-----------------------|---|--|---|
| CHUNKED | (:) | Calibration Falling | Derived via L1B ATBD | on USO for each PCE. |
| ca_l_rise_sm CHUNKED | FLOAT (:) | Altimetric Latest Calibration Rising | seconds/cell Derived via L1B ATBD | The smoothed, calibrated value for the rising edge used to convert cell counts to units of time. time per cell count based on USO for each PCE. |
| ch_mask_s CHUNKED | INTEGER_1 (: x 16) | Channel Mask Strong | counts ATL01/atlas/pcex/a_alt_science | Channel Mask for DLBOs. The 16 flags are a logical OR of the two band offset masks for strong beam |
| ch_mask_w CHUNKED | INTEGER_1 (: x 4) | Channel Mask Weak | counts ATL01/atlas/pcex/a_alt_science | Channel Mask for DLBOs. The 4 flags are a logical OR of the two band offset masks for weak beam |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via L1B ATBD | The time of the first TX pulse in the major frame, relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_strong_channel_index CONTIGUOUS | INTEGER_1 (16) | DS for Strong Channels | 1 | Dimension scale for strong channels. |
| ds_weak_channel_index CONTIGUOUS | INTEGER_1 (4) | DS for Weak Channels | 1 | Dimension scale for weak channels. |
| n_bands CHUNKED | INTEGER_1 (:) | Number Downlink Bands | counts ATL01/atlas/pcex/a_alt_science | Number of bands (in addition to the nominal 1 band) selected for downlink. |
| pce_mframe_cnt CHUNKED | UINT_4_LE (:) | PCE Major frame counter | counts ATL02 | Major Frame ID - The major frame ID is read from the DFC and starts counting at DFC POR. The counter is used to identify individual major frames across diag and science packets. This counter can go for about 2.7 years before rolling over. It is in the first time tag science packet. Used as part of the photon ID |
| useflag CHUNKED | UINT_1_LE (:) | Science Mode Flag | counts ATL01/atlas/pcex/a_alt_sci/ | Science Mode Flag. Used by ATL03 to discard non-science mode data. 0=stby, 1=science_mode, 2=test, 3>manual, 4=radio, 5=unknown, > 10=amcs_not_normal Flag Values: ['0', '1', '2', '3', '4', '5', '6', '7', '8', '9', '10', '11', '12', '13', '14', '15'] Flag Meanings: ['stby', 'science', 'test', 'manual', 'radio', 'unknown', 'unused', 'unused', 'unused', 'unused', 'stby_alt_amcs', 'science_alt_amcs', 'test_alt_amcs', 'manual_alt_amcs', 'radio_alt_amcs', 'unknown_alt_amcs'] |

Group: /atlas/pcex/altimetry/s_w

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|-------------------------|--------------------------|--|--|--|
| Description | (Attribute) | The PCE Altimetry Science Packet specific to a beam (PCEX_ALT_SCI_TLM_MID in APID 1254, 1264, 1274 sequence flag 01 (once per major frame). (see ICESat-2-MEB-SPEC-0875, section 5.12, Spacewire: Major Frame Packet Data Format | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source PCE Altimetric Data Packets. (nominally fifty per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| alt_rw_start CHUNKED | FLOAT (:) | Altimetric Range Window Start | seconds ATL01/atlas/pcex/a_pmf_algorithm_science and L1B ATBD conversion | The number of seconds between the transmit pulse and the start of the altimetric range window for the beam |
| alt_rw_width CHUNKED | FLOAT (:) | Altimetric Range Window Width | seconds ATL01/atlas/pcex/a_pmf_algorithm_science and L1B ATBD conversion | The number of seconds from the range window start and range window stop |
| band1_offset CHUNKED | FLOAT (:) | Band1 Offset | seconds L1A ATBD | Downlink band offset (DLBO) for band1. |
| band1_width CHUNKED | FLOAT (:) | Band1 Width | seconds L1A ATBD | Width of downlink band1. |
| band2_offset CHUNKED | FLOAT (:) | Band2 Offset | seconds L1A ATBD | Downlink band offset (DLBO) for band2. |
| band2_width CHUNKED | FLOAT (:) | Band2 Width | seconds L1A ATBD | Width of downlink band2. |
| n_mf_ph CHUNKED | INTEGER (:) | Number of photons | counts Derived | Number of photons within each major frame. |
| ph_ndx_beg CHUNKED | INTEGER_8 (:) | Photon Index Begin | counts Derived | Index (1-based) within the photon-rate data of the first photon within each major frame. |

Group: /atlas/pcex/altimetry/s_w/photons

| | | | | |
|-------------|-------------|---|--|--|
| Description | (Attribute) | Group contains the PCE Altimetric received photon event (ph) decommutated data and its matching Transmit time tag data. Note the Transmit time tag data are repeated for each received photon event. Data is from Altimetry Science Packet (alt_sci_tlm) APID 1254, 1264, 1274 with Sequence Flag = 0 or 2. See ICESat-2-MEB-SPEC-0875, section 5.12, SPACEWIRE: TIME TAG SCIENCE DATA FORMAT | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source photon events. (varies by detection; nominal value is sixty thousand per second, derived from laser_rate * photons_per_shot * beams_per_pce; where laser_rate=10000, photons_per_shot=3, beams_per_pce=2.) | | |

| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
|---------------------------|-----------------------|-----------------------------|---|--|
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via L1B ATBD | The Time of Day for the specific Transmit (TX) pulse associated with the Received (RX) event. (see L1B ATBD section 5 time of flight), relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| pce_mframe_cnt CHUNKED | UINT_4_LE (:) | PCE Major frame counter | counts Retained from latest a_alt_science packet | Major Frame ID - The major frame ID is read from the DFC and starts counting at DFC POR. The counter is used to identify individual major frames across diag and science packets. This counter can go for about 2.7 years before rolling over. It is in the first time tag science packet. Used as part of the photon ID |
| ph_id_channel CHUNKED | UINT_1_LE (:) | Receive channel id | 1 Derived as part of Photon ID | Channel number assigned for each received photon event. This is part of the photon ID. Values range from 1 to 120 to span all channels and rise/fall edges. Values 1 to 60 are for falling edge; PCE1 (1 to 20), PCE 2 (21 to 40) and PCE3 (41 to 60). Values 61 to 120 are for rising edge; PCE1 (61 to 80), PCE 2 (81 to 100) and PC3 (101 to 120). |
| ph_id_count CHUNKED | UINT_1_LE (:) | photon event counter | counts Derived as part of Photon ID | photon event counter is part of photon ID and will count from 1 for each channel until reset by laser pulse counter. If ph_id_count is 0, then there was a transmit pulse without any received photons. In this case, the transmit portion of the alt_science packet is valid, but the receive portion is all 0s and should not be used. |
| ph_id_pulse CHUNKED | UINT_1_LE (:) | laser pulse counter | counts Derived as part of Photon ID | laser pulse counter is part of photon ID and will count from 1 to 200 and reset for each new major frame (major_fram_id). If the corresponding ph_id_count is 0, then there was a transmit pulse without any received photons. |
| ph_tof CHUNKED | DOUBLE (:) | Time of Flight | seconds ATL02 ATBD | Time of flight (TOF); the round trip time in seconds of the received photon relative to the beam's zero range point (ZRP). Computed from the Transmit (Tx) and Receive (Rx) Time-of-flight components and then calibrated to the centroid of the transmit pulse. |
| rx_band_id CHUNKED | INTEGER_1 (:) | rx downlink band id | counts ATL01/atlas/pcex/a_alt_science_ph RX data | Flag to indicate downlink band id associated with the received rx_tof (received photon event). A value of 0 indicates the photon corresponds to band1; A value of 1 indicates the photon corresponds to band2. Corresponding parameters are band_width, band_offset and band_eventcount. Flag Values: ['0', '1'] Flag Meanings: ['band1', 'band2'] |
| tof_flag CHUNKED | INTEGER_1 (:) | TOF Flag | counts L1B ATBD Sect 2.5.4 | Time Of Flight center correction flag. Values indicate what components were used to adjust the TOF to the centroid of the Tx pulse, based on the alignment of Tx components across all 3 PCEs. 1=LL_LU_TU_TL; 2=LL_TU_TL; 3=LL_LU_TL; 4=LL_LU_TU; 5=LL_TL; 6=LL_TU; 7=LL_LU; 8=LL. Values greater than 10 indicate the same sequence of conditions indicated for a potential TEP photon. Flag Values: ['1', '2', '3', '4', '5', '6', '7', '8', '11', '12', '13', '14', '15', '16', '17', '18'] Flag Meanings: ['LL_LU_TU_TL', 'LL_TU_TL', 'LL_LU_TL', 'LL_LU_TU', 'LL_TL', 'LL_TU', 'LL_LU', 'LL', 'TEP_LL_LU_TU_TL', 'TEP_LL_TU_TL', 'TEP_LL_LU_TL', 'TEP_LL_LU_TU', 'TEP_LL_TL', 'TEP_LL_TU', 'TEP_LL_LU', 'TEP_LL'] |
| tx_ll_tof CHUNKED | FLOAT (:) | Transmit LL time from T0 | seconds ATL01/atlas/pcex/a_alt_science_ph TX data L1B ATBD section tof | Transmit (Tx) Leading Lower (LL) time of flight (TOF); the round trip time in seconds from the detected lower leading edge of the transmit pulse relative to the ATLAS T0. Includes all calibrations of coarse and fine counts. |
| tx_other_tof CHUNKED | FLOAT (:) | Other Transmit Time from LL | seconds ATL01/atlas/pcex/a_alt_science_ph TX data L1B ATBD section tof | Time of flight from the PCE-specific leading-lower (LL) threshold (tx_ll_tof) to the detected other transmit pulse edge. For PCE1, this is the time from the PCE1 LL to the Transmit Leading Upper edge (LU) threshold; for PCE2, this is the time from the PCE2 LL to the Transmit Trailing Upper edge (TU) threshold; and for PCE3, this is the time from the PCE3 LL to the Transmit Trailing Lower edge (TL) threshold. |

Group: /atlas/pcex/atmosphere_sw

| Description | (Attribute) | Contains parameters relating to the PCE Atmospheric Data Histograms. Normally 25 hz. (APID 1255, 1259, 1265, 1269, 1275, 1279). P1 S,P1 W, P2 S, P2 W, P3 S, P3 W. | | |
|-----------------------------|------------------------|--|---|--|
| data_rate | (Attribute) | Data in this group is stored at a 25hz (25 per second) rate. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| atm_bins CHUNKED | UINT_2_LE (: x 467) | Atmospheric Science Histogram | counts ATL01/atlas/pcex/a_atm_hist_x | The histogram bins for the Atmospheric beam. Once every 400 shots (laser pulses). Bin 1 (clouds) is nearest to spacecraft .Bin 467 is under ground. |
| atm_rw_start CHUNKED | FLOAT (:) | Atmospheric Range Window Start | seconds ATL01/atlas/pcex/a_atm_hist_x and L1B ATBD section ATM | The number of seconds between the transmit pulse and the start of the Atmospheric range window |
| atm_rw_width CHUNKED | FLOAT (:) | Atmospheric Range Window Width | seconds ATL01/atlas/pcex/a_atm_hist_x and L1B ATBD section ATM | The number of seconds from the Atmospheric range window start and range window stop. |
| atm_shift_amount CHUNKED | INTEGER_2 (:) | Atmospheric Range Window Shift | counts ATL01/atlas/pcex/a_atm_hist_x and L1B ATBD section ATM | The number of bins the range window start of one of the histograms was shifted to align them before they are added together. |
| delta_time | DOUBLE | Elapsed GPS seconds | seconds since 2018-01-01 | The time of the first TX pulse in major frame, relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products |

| | | | | |
|---------------------------------|--------------------|---------------------------|---|--|
| CHUNKED | (:) | time | Derived via L1B ATBD | (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_hist_bin_index CONTIGUOUS | INTEGER_2 (467) | DS for ATM histogram bins | 1 | Dimension scale for atmosphere histogram bins. |
| pce_mframe_cnt CHUNKED | UINT_4_LE (:) | PCE Major frame counter | counts ATL01/atlas/pcex/a_atm_hist_x | Major Frame Counter - The major frame counter is read from the DFC and starts counting at DFC POR. The counter is used to identify individual major frames across diag and science packets. This counter can go for about 2.7 years before rolling over. It is in the first time tag science packet. Used as part of the photon ID |
| useflag CHUNKED | UINT_1_LE (:) | Science Mode Flag | counts ATL01/atlas/pcex/a_alt_sci/ | Science Mode Flag. Used by ATL03 to discard non-science mode data. 0=stby, 1=science_mode, 2=test, 3=manual, 4=radio, 5=unknown, > 10=amcs_not_normal Flag Values: [0, '1', '2', '3', '4', '5', '6', '7', '8', '9', '10', '11', '12', '13', '14', '15'] Flag Meanings: ['stby', 'science', 'test', 'manual', 'radio', 'unknown', 'unused', 'unused', 'unused', 'stby_alt_amcs', 'science_alt_amcs', 'test_alt_amcs', 'unknown_alt_amcs'] |

Group: /atlas/pcex/background

| | | | | |
|----------------------------|--------------------------|---|--|---|
| Description | (Attribute) | The background data is specific to each beam and reported at a 50-shot rate. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source PCE Altimetric Data Packets. (nominally fifty per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| bg_cnt_50shot_s CHUNKED | UINT_2_LE (:) | Strong background counts | counts ATL01/atlas/pcex/a_pmf_algorithm_science | ATLAS flight s/w indicates for the beam the # of counted time tags (BackgroundCounts_50Shot) during the range windows associated with a set of 50 laser pulses of the major frame. |
| bg_cnt_50shot_w CHUNKED | UINT_2_LE (:) | Weak background counts | counts ATL01/atlas/pcex/a_pmf_algorithm_science | ATLAS flight s/w indicates for the beam the # of counted time tags (BackgroundCounts_50Shot) during the range windows associated with a set of 50 laser pulses of the major frame. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via L1B ATBD | The time of the first TX pulse in the 50 laser pulses used for background, in seconds relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| pce_mframe_cnt CHUNKED | UINT_4_LE (:) | PCE Major frame counter | counts Derived | Major Frame ID - The major frame ID is read from the DFC and starts counting at DFC POR. The counter is used to identify individual major frames across diag and science packets. This counter can go for about 2.7 years before rolling over. It is in the first time tag science packet. Used as part of the photon ID |
| useflag CHUNKED | UINT_1_LE (:) | Science Mode Flag | counts ATL01/atlas/pcex/a_alt_sci/ | Science Mode Flag. Used by ATL03 to discard non-science mode data. 0=stby, 1=science_mode, 2=test, 3=manual, 4=radio, 5=unknown, > 10=amcs_not_normal Flag Values: [0, '1', '2', '3', '4', '5', '6', '7', '8', '9', '10', '11', '12', '13', '14', '15'] Flag Meanings: ['stby', 'science', 'test', 'manual', 'radio', 'unknown', 'unused', 'unused', 'unused', 'stby_alt_amcs', 'science_alt_amcs', 'test_alt_amcs', 'unknown_alt_amcs'] |

Group: /atlas/pcex/tep

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|---------------------------|--------------------------|---|---|--|
| Description | (Attribute) | Group contains the PCE TEP (transmit Echo Path) Data. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source photon events. (varies by detection; nominal value is sixty thousand per second, derived from laser_rate * photons_per_shot * beams_per_pce; where laser_rate=10000, photons_per_shot=3, beams_per_pce=2.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via L1B ATBD | The Time of Day associated with the Transmit (TX) pulse, relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| pce_mframe_cnt CHUNKED | UINT_4_LE (:) | PCE Major frame counter | counts Retained from prior a_alt_science_ph packet | The major frame counter is read from the digital flow controller in a given PCE card. The counter identifies individual major frames across diag and science packets. Used as part of the photon ID. |
| ph_id_channel CHUNKED | UINT_1_LE (:) | Receive channel id | 1 Derived as part of Photon ID | Channel number assigned for each received photon event. This is part of the photon ID. Values range from 1 to 120 to span all channels and rise/fall edges. Values 1 to 60 are for falling edge; PCE1 (1 to 20), PCE 2 (21 to 40) and PCE3 (41 to 60). Values 61 to 120 are for rising edge; PCE1 (61 to 80), PCE 2 (81 to 100) and PC3 (101 to 120). |
| ph_id_count CHUNKED | INTEGER_1 (:) | photon event counter | counts Derived as part of Photon ID | The photon event counter is part of photon ID and counts from 1 for each channel until reset by laser pulse counter. |
| ph_id_pulse CHUNKED | UINT_1_LE (:) | laser pulse counter | counts Derived as part of Photon ID | The laser pulse counter is part of photon ID and counts from 1 to 200 and is reset for each new major frame. |
| rx_band_id | UINT_1_LE | rx downlink band id | counts | Flag to indicate downlink band id associated with the received time tag. Note that in order to reconstruct the event time tag, |

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| CHUNKED | (:) | | ATL01/atlas/pcex/a_alt_science_ph RX data | the 10-bit offset even coarse value must be added to the specified downlink band offset relating to that time tag. |
| rx_channel_id CHUNKED | UINT_1_LE (:) | receive PCE channel id | counts ATL01/atlas/pcex/a_alt_science_ph RX data | channel number that Received photon event (as from Telemetry) |
| tep_pulse_num CHUNKED | UINT_1_LE (:) | TEP Pulse Number | counts Derived as part of TEP Detection | The number of laser pulses from the TEP laser pulse to the laser pulse for which ATLAS is currently receiving non-TEP photons. |
| tof_tep CHUNKED | DOUBLE (:) | TEP Time of Flight | seconds ATL01/atlas/pcex/a_alt_science_ph RX data L1B ATBD section tof | Transmit Echo Pulse (TEP) Time of flight (TOF); the round trip time in seconds of the TEP photon relative to the beam's zero range point (ZRP., Computed from the Transmit (Tx) pulse of the TEP and Receive (Rx) Time-of-flight components; then calibrated to the centroid of the transmit pulse. |
| tx_ll_tof_tep CHUNKED | FLOAT (:) | TEP Transmit time from T0 | seconds ATL01/atlas/pcex/a_alt_science_ph TX data L1B ATBD section tof | Transmit Echo Pulse (TEP) Transmit (Tx) Leading Lower (LL) time of flight (TOF); the round trip time in seconds of the detected lower leading edge of the TEP transmit pulse relative to the ATLAS T0; includes all calibrations of coarse and fine counts. Associated with the pulse from which the TEP originates (offset identified by tep_pulse_num.) |
| tx_other_tof_tep CHUNKED | FLOAT (:) | Other TEP Transmit Time from LL | seconds ATL01/atlas/pcex/a_alt_science_ph TX data L1B ATBD section tof | Transmit Echo Pulse (TEP) time of flight from the PCE-specific leading-lower (LL) threshold (tep_ll_tof) to the detected other transmit pulse edge. For PCE1, this is the time from the PCE1 LL to the Transmit Leading Upper edge (LU) threshold; for PCE2, this is the time from the PCE2 LL to the Transmit Trailing Upper edge (TU) threshold. |
| Group: /atlas/tx_pulse_width | | | | |
| Description | (Attribute) | Contains parameters to characterize the ATLAS pulse shape, derived from the Start Pulse Detector data. | | |
| data_rate | (Attribute) | Parameters in this group are stored at the ATLAS shot rate. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Operations | Elapsed seconds since the ATLAS SDP GPS Epoch, associated with the transmit time where data from all 3 PCEs are present and aligned. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| tx_pulse_skew_est CHUNKED | FLOAT (:) | Transmit Pulse Skew Estimate | seconds ATL02 ATBD, Section 7.2 | The difference between the averages of the lower and upper threshold crossing times. This is an estimate of the transmit pulse skew. |
| tx_pulse_width_lower CHUNKED | FLOAT (:) | Transmit Pulse Energy Lower Width | seconds ATL03 ATBD | The distance between the lower threshold crossing times measured by the Start Pulse Detector. Only present when data from all 3 PCEs are available and aligned. |
| tx_pulse_width_upper CHUNKED | FLOAT (:) | Transmit Pulse Energy Upper Width | seconds ATL03 ATBD | The distance between the upper threshold crossing times measured by the Start Pulse Detector. Only present when data from all 3 PCEs are available and aligned. |
| Group: /gpsr | | | | |
| Description | (Attribute) | Contains parameters related to the GPS Receiver. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source GPS Receiver Data Packets. (nominally one per second.) | | |
| Group: /gpsr/carrier_amplitude | | | | |
| Description | (Attribute) | Contains parameters related to Carrier Amplitude Data Record (CADR). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| antenna_id CHUNKED | INTEGER_1 (: x 16) | CADR Antenna Identifier | 1 ATL01/sc3/gpsr/carrier_amplitude | Carrier Amplitude Data Record (CADR) - Antenna Identifier. 0 = First Antenna 1 = Second Antenna (invalid for present receiver) All other values invalid. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['first_antenna', 'second_antenna'] |
| carrier_amp CHUNKED | FLOAT (: x 16) | CADR Carrier Amplitude | dB ATL01/sc3/gpsr/carrier_amplitude converted | Carrier Amplitude Data Record (CADR) - Carrier Amplitude - Multiple Frequency Processing. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| channel_num CHUNKED | INTEGER_1 (: x 16) | CADR Channel Number | counts ATL01/sc3/gpsr/carrier_amplitude | Carrier Amplitude Data Record (CADR) - Channel Number. 0 to 23; All other values invalid. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| constell_id CHUNKED | INTEGER_1 (: x 16) | CADR Constellation ID | counts ATL01/sc3/gpsr/carrier_amplitude | Carrier Amplitude Data Record (CADR) - Constellation ID - Single Frequency Channel 1-24 (0 = GPS Constellation; All other values invalid). Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| delta_time | DOUBLE | Elapsed GPS seconds | seconds since 2018-01-01 | Time, in seconds since the ATLAS SDP GPS Epoch, computed from raw_gps_time_sec and subseconds in the time |

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| CHUNKED | (:) | time | Derived via Time Tagging | correlation group. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_16_slots CONTIGUOUS | INTEGER_1 (16) | DS for 16 slots | 1 | Dimension scale representing each of the 16 slots. |
| noise_ratio CHUNKED | FLOAT (: x 16) | CADR Carrier to Noise Power Density Ratio | dBHz ATL01/sc3/gpsr/carrier_amplitude converted | Carrier Amplitude Data Record (CADR) - Carrier to Noise Power Density Ratio. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| num_valid_slots CHUNKED | INTEGER_1 (:) | Number of slots filled | counts ATL01/sc3/gpsr/carrier_amplitude/dfh/raw_num_recs | Number of the 16 available slots filled by telemetry. Data values after the number of valid slots are filled with 0. Note: Valid data records will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 16, then the remaining unused data fields within the arrays will be zero-filled. |
| signal_type CHUNKED | INTEGER_1 (: x 16) | CADR GPS Signal Type | 1 ATL01/sc3/gpsr/carrier_amplitude | Carrier Amplitude Data Record (CADR) - GPS Signal Type. 0 = GPS L1 C/A 1 = GPS L1 P 2 = GPS L2 C/A (N/A for present receiver) 3 = GPS L2 P 4 = GPS L2 CM 5 = GPS L2 CL (N/A for present receiver) 6 = No signal processing on this channel All other values invalid. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. Flag Values: ['0', '1', '2', '3', '4', '5', '6'] Flag Meanings: ['gps_l1a_ca', 'gps_l1_p', 'gps_l2_ca', 'gps_l2_p', 'gps_l2_cm', 'gps_l2_cl', 'no_signal_processing'] |
| sv_id CHUNKED | INTEGER_1 (: x 16) | CADR Space Vehicle ID | counts ATL01/sc3/gpsr/carrier_amplitude | Carrier Amplitude Data Record (CADR) - Space Vehicle ID. (0 = No signal acquisition or tracking; 1-32 = GPS SVs. All other values invalid). Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |

Group: /gpsr/carrier_phase

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| Description | (Attribute) | Contains parameters related to the GPSR Carrier Phase Data Record (CrPDR). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| antenna_id CHUNKED | INTEGER_1 (: x 24) | CRPDR Antenna Identifier | 1 ATL01/sc3/gpsr/carrier_phase | Carrier Phase Data Record (CrPDR) - Antenna Identifier. 0 = First Antenna 1 = Second Antenna (invalid for present receiver) All other values invalid. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['first_antenna', 'second_antenna'] |
| carrier_c_fract CHUNKED | FLOAT (: x 24) | CRPDR Carrier Cycle Fraction | degrees ATL01/sc3/gpsr/carrier_phase converted | Carrier Phase Data Record (CrPDR) - Carrier Cycle Fraction - Fraction corresponding to 360 degrees divided by 4096. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| carrier_c_int CHUNKED | INTEGER_8 (: x 24) | CRPDR Integer Carrier Cycle Counter | counts ATL01/sc3/gpsr/carrier_phase | Carrier Phase Data Record (CrPDR) - Integer Carrier Cycle Counter - Note: At the beginning of each track the integer carrier cycle count starts with 0. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| channel_num CHUNKED | INTEGER_1 (: x 24) | CRPDR Channel Number | counts ATL01/sc3/gpsr/carrier_phase | Carrier Phase Data Record (CrPDR) - Channel Number. 0 to 23; All other values invalid. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| constell_id CHUNKED | INTEGER_1 (: x 24) | CRPDR Constellation ID | counts ATL01/sc3/gpsr/carrier_phase | Carrier Phase Data Record (CrPDR) - Constellation ID - Single Frequency Channel 1-24 (0 = GPS Constellation; All other values invalid). Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| delta_range CHUNKED | DOUBLE (: x 24) | CRPDR Delta Range | meters/second ATL01/sc3/gpsr/carrier_phase converted | Carrier Phase Data Record (CrPDR) - Delta Range. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time, in seconds since the ATLAS SDP GPS Epoch, computed from raw_gps_time_sec and subseconds in the time correlation group. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| deter_f CHUNKED | INTEGER_1 (: x 24) | CRPDR Deterioration Flag | 1 ATL01/sc3/gpsr/carrier_phase | Carrier Phase Data Record (CrPDR) - Deterioration Flag. 0= Carrier Loop Lock Steady 1 = Carrier Loop Lock Unsteady (Measurement data may be deteriorated). Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the |

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| | | | | ancillary packet will be zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['steady', 'unsteady'] |
| ds_24_slots CONTIGUOUS | INTEGER_1 (24) | DS for 24 slots | 1 | Dimension scale representing each of the 24 slots. |
| num_valid_slots CHUNKED | INTEGER_1 (:) | Number of slots filled | counts ATL01/sc3/gpsr/carrier_phase/dfh_x/raw_num_recs | Number of the 24 available slots filled by telemetry. Data values after the number of valid slots are filled with 0. Note: Valid data records will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused data fields within the arrays will be zero-filled. |
| signal_type CHUNKED | INTEGER_1 (: x 24) | CRPDR GPS Signal Type | 1 ATL01/sc3/gpsr/carrier_phase | Carrier Phase Data Record (CrPDR) - GPS Signal Type. 0 = GPS L1 C/A 1 = GPS L1 P 2 = GPS L2 C/A (N/A for present receiver) 3 = GPS L2 P 4 = GPS L2 CM 5 = GPS L2 CL (N/A for present receiver) 6 = No signal processing on this channel All other values invalid. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. Flag Values: ['0', '1', '2', '3', '4', '5', '6'] Flag Meanings: ['gps_l1a_ca', 'gps_l1_p', 'gps_l2_ca', 'gps_l2_p', 'gps_l2_cm', 'gps_l2_cl', 'no_signal_processing'] |
| sv_id CHUNKED | INTEGER_1 (: x 24) | CRPDR Space Vehicle ID | counts ATL01/sc3/gpsr/carrier_phase | Carrier Phase Data Record (CrPDR) - Space Vehicle ID. (0 = No signal acquisition or tracking; 1-32 = GPS SVs. All other values invalid). Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |

Group: /gpsr/channel_status

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| Description | (Attribute) | Contains parameters related to Channel Status record (CSR). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| antenna_id CHUNKED | INTEGER_1 (: x 24) | CSR Antenna Identifier | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Antenna Identifier. 0 = First Antenna 1 = Second Antenna (invalid for present receiver) All other values invalid. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['first_antenna', 'second_antenna'] |
| carrier_loop_bw CHUNKED | INTEGER_1 (: x 24) | CSR Carrier Loop Bandwidth | counts ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Index of actual carrier loop bandwidth setting - Single Frequency Channel 1-24 Value = 0; Multiple Settings are not applicable for this parameter type. All other values invalid. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. |
| carrier_loop_bw_ff CHUNKED | INTEGER_1 (: x 24) | CSR Carrier Loop Bandwidth Final Flag | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Carrier Loop Bandwidth (CrLB) Final Flag (FF) - Single Frequency Channel 1-24. 0 = Carrier loop bandwidth not final, 1 = Final carrier bandwidth time applied. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_final', 'applied'] |
| carrier_loop_disc_ff CHUNKED | INTEGER_1 (: x 24) | CSR Carrier Loop Discriminator Final Flag | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Carrier Loop Discriminator (CrLD) Final Flag (FF) - Single Frequency Channel 1-24. 0 = Carrier loop discriminator not final, 1 = Final carrier loop discriminator applied. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_final', 'applied'] |
| carrier_loop_int_t CHUNKED | INTEGER_1 (: x 24) | CSR Carrier Loop Int Time | counts ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Index of actual carrier loop integration time setting - Single Frequency Channel 1-24. Value = 0; Multiple Settings are not applicable for this parameter type. All other values invalid. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. |
| carrier_loop_int_t_ff CHUNKED | INTEGER_1 (: x 24) | CSR Carrier Loop Int Time Final Flag | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Carrier Loop Int Time (CrLIT) Final Flag (FF) - Single Frequency Channel 1-24. 0 = Carrier loop integration time not final, 1 = Final carrier loop integration time applied. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_final', 'applied'] |
| carrier_loop_lock CHUNKED | INTEGER_1 (: x 24) | CSR Carrier Loop Lock | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Carrier Loop Lock (CrLL) - Single Frequency Channel 1-24. 0 = Not locked, 1 = Locked. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_locked', 'locked'] |

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| carrier_loop_mode CHUNKED | INTEGER_1 (: x 24) | CSR Carrier Loop Mode | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Carrier Loop Mode) - Single Frequency Channel 1-24. 0 = No carrier loop activities; 1 = Carrier acquisition ongoing; 2 = Carrier tracking ongoing; 3 = Carrier acquisition error. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1', '2', '3'] Flag Meanings: ['no_activities', 'acquisition', 'tracking', 'acq_error'] |
| carrier_loop_thres_ff CHUNKED | INTEGER_1 (: x 24) | CSR Carrier Loop Threshold Final Flag | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Carrier Loop Threshold (CrLT) Final Flag (FF) - Single Frequency Channel 1-24. 0 = Carrier loop threshold not final, 1 = Final carrier loop threshold applied. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_final', 'applied'] |
| carrier_ph_deter CHUNKED | INTEGER_1 (: x 24) | CSR Carrier Phase Deterioration | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Carrier Phase Deterioration; 0 = No deterioration, 1 = Measurement quality deterioration. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['no_deterioration', 'deterioration'] |
| channel_num CHUNKED | INTEGER_1 (: x 24) | CSR Channel Number | counts ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Channel Number. 0 to 23; All other values invalid. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. |
| code_loop_bw CHUNKED | INTEGER_1 (: x 24) | CSR Code Loop Bandwidth | counts ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Index of actual code loop bandwidth setting - Single Frequency Channel 1-24, Value = 0; Multiple Settings are not applicable for this parameter type. All other values invalid |
| code_loop_bw_ff CHUNKED | INTEGER_1 (: x 24) | CSR Code Loop Bandwidth Final Flag | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Code Loop Bandwidth (CdLB) Final Flag (FF) - Single Frequency Channel 1-24. 0 = Code loop bandwidth not final, 1 = Final code bandwidth time applied. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_final', 'applied'] |
| code_loop_corr_ff CHUNKED | INTEGER_1 (: x 24) | CSR Code Loop Correlator Spacing Final Flag | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Code Loop Correlator Spacing (CdLCS) Final Flag (FF) - Single Frequency Channel 1-24. 0 = Code loop correlator not final, 1 = Final code loop correlator applied. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_final', 'applied'] |
| code_loop_int_t CHUNKED | INTEGER_1 (: x 24) | CSR Code Loop Int Time | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Index of actual code loop integration time setting - Single Frequency Channel 1-24. Value = 0; Multiple Settings are not applicable for this parameter type. All other values invalid. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. |
| code_loop_int_t_ff CHUNKED | INTEGER_1 (: x 24) | CSR Code Loop Int Time Final Flag | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Code Loop Int Time Final (CdLIT) Flag (FF) - Single Frequency Channel 1-24. 0 = Code loop integration time not final, 1 = Final code loop integration time applied. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_final', 'applied'] |
| code_loop_lock CHUNKED | INTEGER_1 (: x 24) | CSR Code Loop Lock | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Code Loop Lock (CdLL) - Single Frequency Channel 1-24. 0 = Not locked, 1 = Locked. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_locked', 'locked'] |
| code_loop_mode CHUNKED | INTEGER_1 (: x 24) | CSR Code Loop Mode | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Code Loop Mode - Single Frequency Channel 1-24. 0 = No code loop activities, 1 = Code acquisition ongoing, 2 = Code tracking ongoing, 3 = Code acquisition error. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1', '2', '3'] Flag Meanings: ['no_activities', 'acquisition', 'tracking', 'acq_error'] |
| code_loop_thres_ff CHUNKED | INTEGER_1 (: x 24) | CSR Code Loop Threshold Final Flag | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Code Loop Threshold (CdLT) Final Flag (FF) - Single Frequency Channel 1-24. 0 = Code loop threshold not final, 1 = Final code loop threshold applied. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_final', 'applied'] |
| code_phase_deter CHUNKED | INTEGER_1 (: x 24) | CSR Code Phase Deterioration | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Code Phase Deterioration (CdPD) - Single Frequency Channel 1-24. 0 = No deterioration, 1 = Measurement quality deterioration. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. |

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| | | | | Flag Values: ['0', '1'] Flag Meanings: ['no_deterioration', 'deterioration'] |
| constell_id CHUNKED | INTEGER_1 (: x 24) | CSR Constellation ID | counts ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Constellation ID - Single Frequency Channel 1-24 (0 = GPS Constellation; All other values invalid). Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time, in seconds since the ATLAS SDP GPS Epoch, computed from raw_gps_time_sec and subseconds in the time correlation group. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_24_slots CONTIGUOUS | INTEGER_1 (24) | DS for 24 slots | 1 | Dimension scale representing each of the 24 slots. |
| logical_track_state CHUNKED | UINT_1_LE (: x 24) | CSR Logical Tracking State | counts ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Logical Tracking State - Single Frequency Channel 1-24. See Appendix C within DN-ICESAT2-SYS-024 for enumerated values. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. |
| nav_d_sync CHUNKED | INTEGER_1 (: x 24) | CSR Navigation Data Sync Status | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Navigation Data Sync Status - Single Frequency Channel 1-24. 0 = Nav Data Not Synchronized, 1 = Nav Data Synchronized, Data Stream Not Inverted, 3 = Nav Data Synchronized, Data Stream Inverted. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1', '3'] Flag Meanings: ['not_synced', 'synced_not_inverted', 'synced_inverted'] |
| num_valid_slots CHUNKED | INTEGER_1 (:) | Number of slots filled | counts ATL01/sc4/gpsr/channel_status/dfh/raw_num_recs | Number of the 24 available slots filled by telemetry. Data values after the number of valid slots are filled with 0. Note: Valid data records will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused data fields within the arrays will be zero-filled. |
| signal_type CHUNKED | INTEGER_1 (: x 24) | CSR GPS Signal Type | 1 ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - GPS Signal Type. 0 = GPS L1 C/A 1 = GPS L1 P 2 = GPS L2 C/A (N/A for present receiver) 3 = GPS L2 P 4 = GPS L2 CM 5 = GPS L2 CL (N/A for present receiver) 6 = No signal processing on this channel All other values invalid. Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. Flag Values: ['0', '1', '2', '3', '4', '5', '6'] Flag Meanings: ['gps_l1a_ca', 'gps_l1_p', 'gps_l2_ca', 'gps_l2_p', 'gps_l2_cm', 'gps_l2_cl', 'no_signal_processing'] |
| sv_id CHUNKED | INTEGER_1 (: x 24) | CSR Space Vehicle ID | counts ATL01/sc4/gpsr/channel_status | Channel Status Record (CSR) - Space Vehicle ID. (0 = No signal acquisition or tracking; 1-32 = GPS SVs. All other values invalid). Note: num_valid_slots indicate the number of channel that actual valid to use. the remaining unused data fields are zero-filled. |

Group: /gpsr/code_phase

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| Description | (Attribute) | Contains parameters related to Code Phase Data Record (CdPDR). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| antenna_id CHUNKED | INTEGER_1 (: x 24) | CDPDR Antenna Identifier | 1 ATL01/sc3/gpsr/code_phase | Code Phase Data Record (CdPDR) - Antenna Identifier. 0 = First Antenna 1 = Second Antenna (invalid for present receiver) All other values invalid. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['first_antenna', 'second_antenna'] |
| channel_num CHUNKED | INTEGER_1 (: x 24) | CDPDR Channel Number | counts ATL01/sc3/gpsr/code_phase | Code Phase Data Record (CdPDR) - Channel Number. 0 to 23; All other values invalid. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| code_chip_count CHUNKED | UINT_8_LE (: x 24) | CDPDR Chip Count | counts ATL01/sc3/gpsr/code_phase | Code Phase Data Record (CdPDR) - Number of Code Chips Since Start of GPS Week. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| code_chip_fract CHUNKED | FLOAT (: x 24) | CDPDR Fractional Chip Count | counts ATL01/sc3/gpsr/code_phase converted | Code Phase Data Record (CdPDR) - Fractional Portion of Number of Code Chips Since Start of GPS Week. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| constell_id CHUNKED | INTEGER_1 (: x 24) | CDPDR Constellation ID | counts ATL01/sc3/gpsr/code_phase | Code Phase Data Record (CdPDR) - Constellation ID - Single Frequency Channel 1-24 (0 = GPS Constellation; All other values invalid). Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |
| delta_time | DOUBLE | Elapsed GPS seconds | seconds since 2018-01-01 | Time, in seconds since the ATLAS SDP GPS Epoch, computed from raw_gps_time_sec and subseconds in the time |

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| CHUNKED | (:) | time | Derived via Time Tagging | correlation group. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| deter_f CHUNKED | INTEGER_1 (: x 24) | CDPDR Deterioration Flag | 1 ATL01/sc3/gpsr/code_phase | Code Phase Data Record (CdPDR) - Deterioration Flag. 0= Carrier Loop Lock Steady 1 = Carrier Loop Lock Unsteady (Measurement data may be deteriorated). Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['steady', 'unsteady'] |
| ds_24_slots CONTIGUOUS | INTEGER_1 (24) | DS for 24 slots | 1 | Dimension scale representing each of the 24 slots. |
| num_valid_slots CHUNKED | INTEGER_1 (:) | Number of slots filled | counts ATL01/sc3/gpsr/code_phase/dfh_x/raw_num_recs | Number of the 24 available slots filled by telemetry. Data values after the number of valid slots are filled with 0. Note: Valid data records will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused data fields within the arrays will be zero-filled. |
| signal_type CHUNKED | INTEGER_1 (: x 24) | CDPDR GPS Signal Type | 1 ATL01/sc3/gpsr/code_phase | Code Phase Data Record (CdPDR) - GPS Signal Type. 0 = GPS L1 C/A 1 = GPS L1 P 2 = GPS L2 C/A (N/A for present receiver) 3 = GPS L2 P 4 = GPS L2 CM 5 = GPS L2 CL (N/A for present receiver) 6 = No signal processing on this channel All other values invalid. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. Flag Values: ['0', '1', '2', '3', '4', '5', '6'] Flag Meanings: ['gps_l1a_ca', 'gps_l1_p', 'gps_l2_ca', 'gps_l2_p', 'gps_l2_cm', 'gps_l2_cl', 'no_signal_processing'] |
| smooth_flg CHUNKED | INTEGER_1 (: x 24) | CDPDR Smoothing Flag | 1 ATL01/sc3/gpsr/code_phase | Code Phase Data Record (CdPDR) - Smoothing Flag. 0 = Smoothing Not Applied 1 = Carrier phase-based smoothing applied for the reported code phase. Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. Flag Values: ['0', '1'] Flag Meanings: ['not_applied', 'applied'] |
| sv_id CHUNKED | INTEGER_1 (: x 24) | CDPDR Space Vehicle ID | counts ATL01/sc3/gpsr/code_phase | Code Phase Data Record (CdPDR) - Space Vehicle ID. (0 = No signal acquisition or tracking; 1-32 = GPS SVs. All other values invalid). Note: Valid data records (num_valid_slots) will only be included for the amount of SFCs being tracked by the GPSR. If the tracked SFCs < 24, then the remaining unused CSR data fields within the ancillary packet will be zero-filled. |

Group: /gpsr/hk

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| Description | (Attribute) | Contains parameters related to GPSR housekeeping. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| clock_source CHUNKED | INTEGER_1 (:) | HK Clock Source | 1 ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Clock Source Flag Values: ['0', '1'] Flag Meanings: ['internal_clock', 'value_invalid'] |
| cpu_processor_load CHUNKED | UINT_2_LE (:) | HK CPU Processor Load | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - CPU Load of most recent PPS interval |
| dc_data_error CHUNKED | UINT_1_LE (:) | HK Data Cache Data Error Counter | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Data Cache Data Error Counter |
| dc_tag_error CHUNKED | UINT_1_LE (:) | HK Data Cache Tag Error Counter | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Data Cache Tag Error Counter |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time, in seconds since the ATLAS SDP GPS Epoch, computed from raw_gps_time_sec and subseconds in the time correlation group. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| discarded_tc_packets CHUNKED | UINT_1_LE (:) | HK Discarded TC Packet Counter | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Number of TC packets discarded since start of GPSR (wrapping counter). |
| discarded_tm_packets CHUNKED | UINT_1_LE (:) | HK Discarded TM Packet Counter | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Number of TM packets discarded since start of GPSR (wrapping counter). |
| edac_double_bit_error CHUNKED | INTEGER_1 (:) | HK MilBus I/F EDAC Double Bit Error | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - MilBus I/F EDAC Double Bit Error |

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| edac_single_bit_error CHUNKED | UINT_1_LE (:) | HK MilBus I/F EDAC Single Bit Error | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - MilBus I/F EDAC Single Bit Error |
| front_end_t CHUNKED | UINT_1_LE (:) | DFH Front End Temperature | counts GPSR_DFH | GPSR Data Field Header - R/F Front End Temperature (raw counts; not EU-converted) |
| ic_data_error CHUNKED | UINT_1_LE (:) | HK Instr Cache Data Error Counter | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Instr Cache Data Error Counter |
| ic_tag_error CHUNKED | UINT_1_LE (:) | HK Instr Cache Tag Error Counter | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Instr Cache Tag Error Counter |
| memory_dump_status CHUNKED | UINT_2_LE (:) | HK Memory Dump Status | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Number of TM packets to be generated until the current Memory Dump is finished |
| n_sv_w_all CHUNKED | INTEGER_1 (:) | HK Number of Tracked SVs w All Components in Tracking State | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - GNSS satellites being tracked with all signal components in final tracking state at the most recent PPS |
| n_sv_s_acquired CHUNKED | INTEGER_1 (:) | HK Number of SVs Being Acquired | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - GNSS satellites being acquired at the most recent PPS, i.e. channels with Multi-Frequency Tracking state 2...4 |
| n_sv_s_used CHUNKED | INTEGER_1 (:) | HK Number of SVs Used for PVT | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - GNSS satellites being used for PVT at the PPS before the most recent PPS |
| n_sv_s_wo_all CHUNKED | INTEGER_1 (:) | HK Number of Tracked SVs w/o All Components in Tracking State | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - GNSS satellites being tracked with not all signal components in a final tracking state at the most recent PPS, i.e. channels with Multi-Frequency Tracking state 5...10 (L1 C/A & P(Y)) or Multi-Frequency Tracking state 5...7 (L1 C/A & L2 CM) |
| nsm CHUNKED | INTEGER_1 (:) | GPSR Navigation Solution Method (NSM) | 1 ATL01/sc4/gpsr/hk | GPSR - Navigation Solution Method. 1 = Propagated; 2 = Cold Start - First Nav Fix; 3 = Cold Start - Least Squares Method w/ no GDOP Optimization; 4 = Least Squares Method w/ all Visible SVs; 5 = Kalman Filter Method (Normal Operation); 7 = Invalid Navigation Solution. All other values are invalid. Flag Values: ['0', '1', '2', '3', '4', '5', '7'] Flag Meanings: ['unknown', 'propagated', 'cold_first_nav', 'cold_lsq_no_gdop', 'lsqm_w_sv_s', 'normal_kalman', 'invalid_solution'] |
| prom_edac_status CHUNKED | INTEGER_1 (:) | HK PROM EDAC Status | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - PROM EDAC Single bit or uncorrectable error Flag Values: ['0', '1'] Flag Meanings: ['no_error_detected', 'error_detected'] |
| protocol_selection_f CHUNKED | INTEGER_1 (:) | HK MilBus Protocol Selection Flag | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - MilBus Protocol Selection Flag |
| register_file_errors CHUNKED | INTEGER_1 (:) | HK Corrected Register File Errors | 1 ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Corrected Register File Errors Flag Values: ['0', '1'] Flag Meanings: ['no_error_detected', 'error_detected'] |
| sram_edac_status CHUNKED | INTEGER_1 (:) | HK SRAM EDAC Status | 1 ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - SRAM EDAC Single bit error Flag Values: ['0', '1'] Flag Meanings: ['no_error_detected', 'error_detected'] |
| transient_protocol_errors CHUNKED | UINT_2_LE (:) | HK MilBus Transient Protocol Error Count | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - MilBus Transient Protocol Error Count |
| transmit_buffer_occupancy CHUNKED | UINT_2_LE (:) | HK Transmit Buffer Occupancy | counts ATL01/sc4/gpsr/hk | Housekeeping Parameter Report (HK) - Number of bytes buffered for transmission |

Group: /gpsr/navigation

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| Description | (Attribute) | Contains parameters related to navigation solution. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| clock_freq_error CHUNKED | INTEGER (:) | NAV Receiver Clock Frequency Error | seconds ATL01/sc4/gpsr/navigation | Navigation Solution Data Record (NAV) - Receiver Clock Frequency Error |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time, in seconds since the ATLAS SDP GPS Epoch, computed from raw_gps_time_sec and subseconds in the time correlation group. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |

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| gdop CHUNKED | FLOAT (:) | NAV Geometric Dilution of Precision | meters ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Geometric Dilution of Precision (Values greater than 655.34 m are saturated to 655.34 m.) |
| gnss_time_error CHUNKED | FLOAT (:) | NAV GNSS System Time Error | seconds ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - GNSS System Time Error |
| gps_time_sec CHUNKED | UINT_4_LE (:) | TCDR GPS Time (Seconds) | seconds ATL01/sc4/gpsr/navigation | Time Correlation Data Record (TCDR) - GPS Time (GPST) representation of the synchronization time stamp. Total seconds elapsed since GPS epoch (6-Jan-1980 00:00:00) starting with 0. (Same data that is provided to ATLAS in RT) |
| gps_time_subsec CHUNKED | UINT_4_LE (:) | TCDR GPS Time (Subseconds) | 1/4294967296 seconds ATL01/sc4/gpsr/navigation | Time Correlation Data Record (TCDR) - Subseconds portion of the GPS Time (GPST) representation of the synchronization time stamp. Total seconds elapsed since GPS epoch (6-Jan-1980 00:00:00) starting with 0. (Same data that is provided to ATLAS in RT) |
| h_ell CHUNKED | DOUBLE (:) | NAV Height Above Reference Ellipsoid (WGS84) | meters ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Height Above Reference Ellipsoid (WGS84) |
| latitude CHUNKED | DOUBLE (:) | NAV Latitude (WGS84) | degrees_north ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Latitude (WGS84) |
| longitude CHUNKED | DOUBLE (:) | NAV Longitude (WGS84) | degrees_east ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Longitude (WGS84) |
| max_curve_fit CHUNKED | INTEGER_1 (:) | NAV Maximum Curve Fit | 1 ATL01/sc4/gpsr/navigation | Navigation Solution Data Record (NAV) - Maximum Curve Fit interval taken from all SVs used in current navigation solution Flag Values: ['0', '1', '2', '3', '4', '5', '6', '7', '8', '9', '15'] Flag Meanings: ['4h', '6h', '8h', '14h', '26h', '50h', '74h', '98h', '122h', '146h', 'no_curve_fit'] |
| max_ura CHUNKED | INTEGER_1 (:) | NAV Maximum User Range Accuracy (URA) | counts ATL01/sc4/gpsr/navigation | Navigation Solution Data Record (NAV) - Maximum User Range Accuracy (-16 means that no URA is available) |
| n_sv CHUNKED | INTEGER_1 (:) | NAV Number of SVs in Solution | counts ATL01/sc4/gpsr/navigation | Navigation Solution Data Record (NAV) - The number of SVs the receiver was able to use for the Navigation Solution computation, i.e. SVs for which code and carrier phase measurements and Ephemeris data were available |
| nsm CHUNKED | INTEGER_1 (:) | GPSR Navigation Solution Method (NSM) | 1 ATL01/sc4/gpsr/navigation | GPSR - Navigation Solution Method. 1 = Propagated 2 = Cold Start - First Nav Fix 3 = Cold Start - Least Squares Method w/ no GDOP Optimization 4 = Least Squares Method w/ all Visible SVs 5 = Kalman Filter Method (Normal Operation) 7 = Invalid Navigation Solution All other values invalid Flag Values: ['1', '2', '3', '4', '5', '7'] Flag Meanings: ['propagated', 'cold_lsq_no_gdop', 'lsqm_w_sv', 'normal_kalman', 'invalid_solution'] |
| pdop CHUNKED | FLOAT (:) | NAV Position Dilution of Precision | counts ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Position Dilution of Precision. Values greater than 655.34 are saturated to 655.34; Value set to 655.35 when NSM = 1 or in the case NSM = 5 with fewer than 4 SVs available. |
| position_error_x CHUNKED | FLOAT (:) | NAV Position Error X | meters ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated X position error |
| position_error_y CHUNKED | FLOAT (:) | NAV Position Error Y | meters ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated Y position error |
| position_error_z CHUNKED | FLOAT (:) | NAV Position Error Z | meters ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated Z position error |
| position_qa CHUNKED | INTEGER_2 (:) | NAV Time Quality Index | seconds ATL01/sc4/gpsr/navigation | Navigation Solution Data Record (NAV) - Time Quality Index; Values greater than 4095 ns are saturated to 4095 ns. |
| position_x CHUNKED | DOUBLE (:) | NAV Position X (WGS84) | meters ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated X position of the platform reference point according to the Navigation Solution Method (NSM) at the point in time of GPST (WGS84) |
| position_y CHUNKED | DOUBLE (:) | NAV Position Y (WGS84) | meters ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated Y position of the platform reference point according to the Navigation Solution Method (NSM) at the point in time of GPST (WGS84) |
| position_z CHUNKED | DOUBLE (:) | NAV Position Z (WGS84) | meters ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated Z position of the platform reference point according to the Navigation Solution Method (NSM) at the point in time of GPST (WGS84) |
| tdop CHUNKED | FLOAT (:) | GPSR Time Dilution of Precision | meters ATL01/sc4/gpsr/navigation converted | GPSR - Time Dilution of Precision. Values greater than 655.34 are saturated to 655.34; Value set to 655.35 when NSM = 1 or in the case NSM = 5 with fewer than 4 SVs available. |
| velocity_error_x CHUNKED | FLOAT (:) | NAV Velocity Error X | meters/second ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated X velocity error |
| velocity_error_y CHUNKED | FLOAT (:) | NAV Velocity Error Y | meters/second ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated Y velocity error |
| velocity_error_z CHUNKED | FLOAT (:) | NAV Velocity Error Z | meters/second ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated Z velocity error |
| velocity_x CHUNKED | DOUBLE (:) | NAV Velocity X (WGS84) | meters/second ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated X velocity of the platform reference point according to the Navigation Solution Method (NSM) at the point in time of GPST (WGS84) |

| | | | | |
|---------------------------|---------------|---------------------------|--|---|
| velocity_y CHUNKED | DOUBLE (:) | NAV Velocity Y (WGS84) | meters/second ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated Y velocity of the platform reference point according to the Navigation Solution Method (NSM) at the point in time of GPST (WGS84) |
| velocity_z CHUNKED | DOUBLE (:) | NAV Velocity Z (WGS84) | meters/second ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Estimated Z velocity of the platform reference point according to the Navigation Solution Method (NSM) at the point in time of GPST (WGS84) |
| vertical_speed CHUNKED | DOUBLE (:) | NAV Vertical Speed | meters/second ATL01/sc4/gpsr/navigation converted | Navigation Solution Data Record (NAV) - Vertical Speed |

Group: /gpsr/noise_histogram

| | | | | |
|-----------------------------------|--------------------------|---|--|---|
| Description | (Attribute) | Contains parameters related to the GPS Noise Histogram Data Record (NHDR). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| chain_index CHUNKED | INTEGER_1 (: x 2) | NHDR Chain Index - Chain 1-2 | 1 ATL01/sc3/gpsr/noise_histogram | Noise Histogram Data Record (NHDR) - Chain Index - Down Conversion Chain Identifier 1-2 Flag Values: ['0', '1'] Flag Meanings: ['antenna1_1carrier', 'antenna1_12carrier'] |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time, in seconds since the ATLAS SDP GPS Epoch, computed from raw_gps_time_sec and subseconds in the time correlation group. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_chain CONTIGUOUS | INTEGER_1 (2) | DS for each chain | 1 | Dimension scale representing each of the 2 chains. |
| noise_power CHUNKED | FLOAT (: x 2) | NHDR Noise Power - Chain 1-2 | dB ATL01/sc3/gpsr/noise_histogram converted | Noise Histogram Data Record (NHDR) - Noise Power as seen at the input of the variable gain IF amplifier - Down Conversion Chain Identifier 1-2 |
| norm_neg_in_phase_m1 CHUNKED | UINT_2_LE (: x 2) | NHDR Normalized Negative In-Phase Counts M1 - Chain 1-2 | counts ATL01/sc3/gpsr/noise_histogram | Noise Histogram Data Record (NHDR) - Normalized signal level detector counts of the negative In-phase samples (M1) - Down Conversion Chain Identifier 1-2 |
| norm_neg_in_phase_m3 CHUNKED | UINT_2_LE (: x 2) | NHDR Normalized Negative In-Phase Counts M3 - Chain 1-2 | counts ATL01/sc3/gpsr/noise_histogram | Noise Histogram Data Record (NHDR) - Normalized signal level detector counts of the negative In-phase samples (M3) - Down Conversion Chain Identifier 1-2 |
| norm_neg_quad_phase_m1 CHUNKED | UINT_2_LE (: x 2) | NHDR Normalized Negative Quadrature- Phase Counts M1 - Chain 1-2 | counts ATL01/sc3/gpsr/noise_histogram | Noise Histogram Data Record (NHDR) - Normalized signal level detector counts of the negative Quadrature-phase samples (M1) - Down Conversion Chain Identifier 1-2 |
| norm_neg_quad_phase_m3 CHUNKED | UINT_2_LE (: x 2) | NHDR Normalized Negative Quadrature- Phase Counts M3 - Chain 1-2 | counts ATL01/sc3/gpsr/noise_histogram | Noise Histogram Data Record (NHDR) - Normalized signal level detector counts of the negative Quadrature-phase samples (M3) - Down Conversion Chain Identifier 1-2 |
| norm_pos_in_phase_p1 CHUNKED | UINT_2_LE (: x 2) | NHDR Normalized Positive In-Phase Counts P1 - Chain 1-2 | counts ATL01/sc3/gpsr/noise_histogram | Noise Histogram Data Record (NHDR) - Normalized signal level detector counts of the positive In-phase samples (P1) - Down Conversion Chain Identifier 1-2 |
| norm_pos_in_phase_p3 CHUNKED | UINT_2_LE (: x 2) | NHDR Normalized Positive In-Phase Counts P3 - Chain 1-2 | counts ATL01/sc3/gpsr/noise_histogram | Noise Histogram Data Record (NHDR) - Normalized signal level detector counts of the positive In-phase samples (P3) - Down Conversion Chain Identifier 1-2 |
| norm_pos_quad_phase_p1 CHUNKED | UINT_2_LE (: x 2) | NHDR Normalized Positive Quadrature- Phase Counts P1 - Chain 1-2 | counts ATL01/sc3/gpsr/noise_histogram | Noise Histogram Data Record (NHDR) - Normalized signal level detector counts of the positive Quadrature-phase samples (P1) - Down Conversion Chain Identifier 1-2 |
| norm_pos_quad_phase_p3 CHUNKED | UINT_2_LE (: x 2) | NHDR Normalized Positive Quadrature- Phase Counts P3 - Chain 1-2 | counts ATL01/sc3/gpsr/noise_histogram | Noise Histogram Data Record (NHDR) - Normalized signal level detector counts of the positive Quadrature-phase samples (P3) - Down Conversion Chain Identifier 1-2 |

Group: /gpsr/time_correlation

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|-------------------|--------------------------|---|--------------------------|---|
| Description | (Attribute) | Contains parameters related to GPSR time correlation data record (TCDR). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time | DOUBLE | Elapsed GPS seconds | seconds since 2018-01-01 | Time, in seconds since the ATLAS SDP GPS Epoch, computed from raw_gps_time_sec and subseconds in the time |

| | | | | |
|----------------------------|------------------|--|---|--|
| CHUNKED | (:) | time | Derived via Time Tagging | correlation group. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| gps_time_sec CHUNKED | UINT_4_LE (:) | TCDR GPS Time (Seconds) | seconds ATL01/sc4/gpsr/time_correlation | Time Correlation Data Record (TCDR) - GPS Time (GPST) representation of the synchronization time stamp. Total seconds elapsed since GPS epoch (6-Jan-1980 00:00:00) starting with 0. (Same data that is provided to ATLAS in RT) |
| gps_time_subsec CHUNKED | UINT_4_LE (:) | TCDR GPS Time (Subseconds) | 1/4294967296 seconds ATL01/sc4/gpsr/time_correlation | Time Correlation Data Record (TCDR) - Subseconds portion of the GPS Time (GPST) representation of the synchronization time stamp. Total seconds elapsed since GPS epoch (6-Jan-1980 00:00:00) starting with 0. (Same data that is provided to ATLAS in RT) |
| imt CHUNKED | DOUBLE (:) | TCDR Instrument Measurement Time | seconds ATL01/sc4/gpsr/time_correlation converted | Time Correlation Data Record (TCDR) - Time Correlation Data Record (TCDR) - Instrument Measurement Time (IMT) representation of the synchronization time stamp. IMT precisely describes how the GPSR clock oscillator behaves, and is for internal and maintenance use only. |
| nsm CHUNKED | INTEGER_1 (:) | GPSR Navigation Solution Method (NSM) | 1 ATL01/sc4/gpsr/time_correlation | GPSR - Navigation Solution Method. 1 = Propagated 2 = Cold Start - First Nav Fix 3 = Cold Start - Least Squares Method w/ no GDOP Optimization 4 = Least Squares Method w/ all Visible SVs 5 = Kalman Filter Method (Normal Operation) 7 = Invalid Navigation Solution All other values invalid Flag Values: ['1', '2', '3', '4', '5', '7'] Flag Meanings: ['propagated', 'cold_lsq_no_gdop', 'lsqm_w_svs', 'normal_kalman', 'invalid_solution'] |
| tdop CHUNKED | FLOAT (:) | GPSR Time Dilution of Precision | meters ATL01/sc4/gpsr/time_correlation converted | GPSR - Time Dilution of Precision. Values greater than 655.34 are saturated to 655.34; Value set to 655.35 when NSM = 1 or in the case NSM = 5 with fewer than 4 SVs available. |
| time_qa CHUNKED | INTEGER_2 (:) | TCDR Time Quality Index | nanoseconds ATL01/sc4/gpsr/time_correlation | Time Correlation Data Record (TCDR) - Time Quality Index. Nanoseconds; Values greater than 4095 ns are saturated to 4095 ns. |
| utc_days CHUNKED | UINT_2_LE (:) | TCDR TCDR UTC Time - Days | days ATL01/sc4/gpsr/time_correlation | Time Correlation Data Record (TCDR) - UTC time representation of the synchronization time stamp. Number of days since 1st January 2000, 00:00:00 starting with 0. |
| utc_msec CHUNKED | UINT_4_LE (:) | TCDR TCDR UTC Time - Milliseconds | msec ATL01/sc4/gpsr/time_correlation | Time Correlation Data Record (TCDR) - UTC time representation of the synchronization time stamp. Number of milliseconds of current day. |
| utc_usec CHUNKED | UINT_2_LE (:) | TCDR TCDR UTC Time - Microseconds | usec ATL01/sc4/gpsr/time_correlation | Time Correlation Data Record (TCDR) - UTC time representation of the synchronization time stamp. Number of microseconds of current day. |

Group: /lrs

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|-------------|-------------|---|--|--|
| Description | (Attribute) | Group contains the Laser Reference System (LRS) packet decommutated data | | |
| data_rate | (Attribute) | Data within this group are stored at the nominal rate of the corresponding LRS APIDs (varies per APID). | | |

Group: /lrs/hk_1120

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|-------------|-------------|--|--|--|
| Description | (Attribute) | Contains parameters relating to the Application Housekeeping Packet (LRStmHK)(APID 1120). The (Application Mode) Housekeeping Packet provides all LRS health and safety data. It is normally reported and stored at a 1 Hz rate. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS Housekeeping Data (nominally once per second). | | |

| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
|----------------------------|--------------------------|---|-----------------|---|
| chkstat_e_ad CHUNKED | INTEGER_1 (:) | LRS_HK Checksum Status Register - EEPROM Application Text Checksum | 1 LRS_HK | EEPROM Application Data (AD) checksum (0=PASSED (normal operating condition) 1=FAILED (abnormal condition)) Flag Values: ['0', '1'] Flag Meanings: ['passed', 'failed'] |
| chkstat_e_at CHUNKED | INTEGER_1 (:) | LRS_HK Checksum Status Register - EEPROM Application Text Checksum | 1 LRS_HK | EEPROM Application Text (AT) checksum (0=PASSED (normal operating condition) 1=FAILED (abnormal condition)) Flag Values: ['0', '1'] Flag Meanings: ['passed', 'failed'] |
| chkstat_e_bc CHUNKED | INTEGER_1 (:) | LRS_HK Checksum Status Register - EEPROM Boot Config Checksum | 1 LRS_HK | EEPROM Boot Configuration (BC) checksum (0=PASSED (normal operating condition) 1=FAILED (abnormal condition)) Flag Values: ['0', '1'] Flag Meanings: ['passed', 'failed'] |
| chkstat_e_ld_df CHUNKED | INTEGER_1 (:) | LRS_HK Checksum Status Register - EEPROM Laser Detector Dark Frame Checksum | 1 LRS_HK | EEPROM Laser Detector (LD) Dark Frame data checksum (0=PASSED (normal operating condition) 1=FAILED (abnormal condition)) Flag Values: ['0', '1'] Flag Meanings: ['passed', 'failed'] |
| chkstat_e_sd_df CHUNKED | INTEGER_1 (:) | LRS_HK Checksum Status Register - EEPROM Stellar Detector Dark Frame Checksum | 1 LRS_HK | EEPROM Stellar Detector (SD) Dark Frame data checksum (0=PASSED (normal operating condition) 1=FAILED (abnormal condition)) Flag Values: ['0', '1'] Flag Meanings: ['passed', 'failed'] |

| | | | | |
|----------------------------|------------------|---|--|---|
| chkstat_s_at CHUNKED | INTEGER_1 (:) | LRS_HK Checksum Status Register -SRAM Application Text Checksum | 1 LRS_HK | SRAM Application Text (AT) checksum (0=PASSED (normal operating condition) 1=FAILED (abnormal condition)) Flag Values: ['0', '1'] Flag Meanings: ['passed', 'failed'] |
| chkstat_s_ld_df CHUNKED | INTEGER_1 (:) | LRS_HK Checksum Status Register - SRAM Laser Detector Dark Frame Checksum | 1 LRS_HK | SRAM Laser Detector (LD) Dark Frame data checksum (0=PASSED (normal operating condition) 1=FAILED (abnormal condition)) Flag Values: ['0', '1'] Flag Meanings: ['passed', 'failed'] |
| chkstat_s_sd_df CHUNKED | INTEGER_1 (:) | LRS_HK Checksum Status Register - SRAM Stellar Detector Dark Frame Checksum | 1 LRS_HK | SRAM Stellar Detector (SD) Dark Frame data checksum (0=PASSED (normal operating condition) 1=FAILED (abnormal condition)) Flag Values: ['0', '1'] Flag Meanings: ['passed', 'failed'] |
| cmdcnt CHUNKED | UINT_2_LE (:) | LRS_HK Valid User Command Counter | counts LRS_HK | The Valid User Command Counter is a 16-bit counter that increments each time that the Failsafe Mode processes a valid command of the corresponding command type. A valid command is defined as a command that passes all verification tests. The counter starts at 0x0000, and rolls over to 0x0000 when it increments from 0xFFFF. The counter is reset at power on and by a Failsafe Reset Counters Command (LRSfscmRSTCNT). |
| cmderrcnt CHUNKED | UINT_2_LE (:) | LRS_HK User Command Error Counter | counts LRS_HK | The 16-bit User Command Error Counter is incremented every time the Failsafe Mode has one or more command verification or processing errors with the corresponding command type (abnormal conditions). The counter starts at 0x0000, and rolls over to 0x0000 when it increments from 0xFFFF. The counter increments only once per command when there is at least one verification/processing error for that command. CMDERRCODE will indicate the type of error. The counter is reset at power on and by a Failsafe Reset Counters Command (LRSfscmRSTCNT). |
| cmderrcode CHUNKED | UINT_2_LE (:) | LRS_HK Unique Code for User Command Errors | counts LRS_HK | The 16-bit Command Error Unique Code indicates the last type of command error that occurred in Failsafe Mode. This code will be reset at power on and by a Failsafe Reset Counters Command (LRSfscmRSTCNT). The error codes are defined in Table 19: Command Validation Error Codes in the LRS command and data ICD. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| dmpmemcnt CHUNKED | UINT_4_LE (:) | LRS_HK Number of memory words dumped | counts LRS_HK | This 32-bit counter records the total number of memory words dumped during Failsafe Mode processing of Failsafe Dump Memory Command (LRSfscmDPMEM). It starts at 0x00000000, and rolls over to 0x00000000 when it increments from 0xFFFFFFFF. This counter will be reset at power on and by a Failsafe Reset Counters Command (LRSfscmRSTCNT). |
| dmppktleft CHUNKED | UINT_2_LE (:) | LRS_HK Remaining number of dump packets to go | counts LRS_HK | This 16-bit counter indicates the remaining number of dump packets to send during Failsafe Mode processing of a Failsafe Dump Memory Command (LRSfscmDPMEM). It is 0x0000 whenever no dump command is active. |
| ground1_v CHUNKED | FLOAT (:) | LRS_HK Ground 1 Voltage | volts LRS_HK | Voltage of Ground 1 - 0x0000 = 0.000 V (nominal value); 0xFFFF = +4.000 V : A_LRS_HK.ANALOGHK[0] |
| ground2_v CHUNKED | FLOAT (:) | LRS_HK Ground 2 Voltage | volts LRS_HK | Voltage of Ground 2 - 0x0000 = 0.000 V (nominal value); 0xFFFF = +4.000 V : A_LRS_HK.ANALOGHK[1] |
| laser_barrel1_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #1 (Laser Side Barrel #1 Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #1 (Laser Side Barrel #1) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| laser_barrel2_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #2 (Laser Side Barrel #2 Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #2 (Laser Side Barrel #2) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| laser_barrel3_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #3 (Laser Side Barrel #3 Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #3 (Laser Side Barrel #3) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| ldbackground CHUNKED | UINT_2_LE (:) | LRS_HK LD background | counts LRS_HK | The 16-bit values are measures of the measured detector background for the laser side after subtracting the predicted dark frame. Each is a scaled average of the background levels from all tracking windows on that detector, for all measurements in the preceding one (1) second. Because the search and imaging windows move around, these values should be expected to fluctuate significantly; however, they are an indication of how well the predicted dark frame matches the background (stray light) levels. If they are occasionally very large, there is probably a stray light problem. If they are consistently very large, there is probably error in the dark frame calibration. |
| ldc_t CHUNKED | FLOAT (:) | LRS_HK Laser Detector Card Temperature | degreesC LRS_HK | Temperature of Laser Detector Card - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| ldmemcnt | UINT_4_LE | LRS_HK Number of | counts | This 32-bit counter records the total number of memory words loaded during Failsafe Mode processing of Failsafe Load |

| | | | | |
|----------------------------|------------------|---|--------------------|---|
| CHUNKED | (:) | memory words loaded | LRS_HK | Memory Command (LRSfscmLDMEM). It starts at 0x00000000, and rolls over to 0x00000000 when it increments from 0xFFFFFFFF. This counter will be reset at power on and by a Failsafe Reset Counters Command (LRSfscmRSTCNT) |
| ldmemconflict CHUNKED | UINT_2_LE (:) | LRS_HK LD Memory Conflicts | counts LRS_HK | This 16-bit counter is incremented each time the Application Mode is still accessing Laser-Side shared memory when a new LRS cycle starts. This conflict is an error, which indicates that shared memory access did not complete in the allocated time and may have caused stale or invalid laser centroids. This counter starts at 0x0000, and rolls over to 0x0000 when it increments from 0xFFFF. This counter will be reset at Application Mode initialization and by an Application Reset Counters Command (LRScmRSTCNT). |
| ldoverrun CHUNKED | UINT_2_LE (:) | LRS_HK LD Processing Overruns | counts LRS_HK | This 16-bit counter is incremented each time the Application Mode is still processing Laser-Side data when a new LRS cycle starts. This overrun condition is a warning, which indicates that some processor activity did not complete in the allocated time and may delay reporting of the next laser data packets. This counter starts at 0x0000, and rolls over to 0x0000 when it increments from 0xFFFF. This counter will be reset at Application Mode initialization and by an Application Reset Counters Command (LRScmRSTCNT). |
| m12v_cmon_a CHUNKED | FLOAT (:) | LRS_HK -12VDC Current Monitor | amps LRS_HK | Amperage of -12VDC Current Monitor - 0x0000 = 0.000 A; 0xFFFF = +0.400 A : A_LRS_HK.ANALOGHK[6] |
| m12v_ldc_mon_v CHUNKED | FLOAT (:) | LRS_HK -12VDC LDC Monitor | volts LRS_HK | Voltage of -12VDC LDC Monitor - 0x0000 = 0.000 V; 0xBF9D = -12.000 V (nominal value); 0xFFFF = -16.000 V : A_LRS_HK.ANALOGHK[11] |
| m12v_sdc_mon_v CHUNKED | FLOAT (:) | LRS_HK -12VDC SDC Monitor | volts LRS_HK | Voltage of -12VDC SDC Monitor - 0x0000 = 0.000 V; 0xBF9D = -12.000 V (nominal value); 0xFFFF = -16.000 V : A_LRS_HK.ANALOGHK[10] |
| m12v_supp_mon_v CHUNKED | FLOAT (:) | LRS_HK -12VDC Supply Monitor | volts LRS_HK | Voltage of 112VDC Supply Monitor - 0x0000 = 0.000 V; 0xBF9D = -12.000 V (nominal value); 0xFFFF = -16.000 V : A_LRS_HK.ANALOGHK[14] |
| meter_bar1_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #4 (Metering Bars #1 Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #4 (Metering Bars #1) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| meter_bar2_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #5 (Metering Bars #2 Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #5 (Metering Bars #2) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| meter_bar3_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #6 (Metering Bars #3 Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #6 (Metering Bars #3) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| p12v_ana_mon_v CHUNKED | FLOAT (:) | LRS_HK +12VDC Analog Monitor | volts LRS_HK | Voltage of +12VDC Analog Monitor - 0x0000 = 0.000 V; 0xC000 = +12.000 V (nominal value); 0xFFFF = +16.000 V : A_LRS_HK.ANALOGHK[15] |
| p12v_cmon_a CHUNKED | FLOAT (:) | LRS_HK +12VDC Current Monitor | amps LRS_HK | Amperage of +12VDC Current Monitor - 0x0000 = 0.000 A; 0xFFFF = +0.400 A : A_LRS_HK.ANALOGHK[7] |
| p1_5v_mon_v CHUNKED | FLOAT (:) | LRS_HK +1.5VDC Monitor | volts LRS_HK | Voltage of +1.5VDC Monitor - 0x0000 = 0.000 V; 0x6000 = +1.500 V (nominal value); 0xFFFF = +4.000 V : A_LRS_HK.ANALOGHK[3] |
| p1_8v_mon_v CHUNKED | FLOAT (:) | LRS_HK +1.8VDC Monitor Voltage | volts LRS_HK | Voltage of +1.8VDC Monitor - 0x0000 = 0.000 V; 0x7332 = 1.800 V (nominal); 0xFFFF = +4.000 V : A_LRS_HK.ANALOGHK[19] |
| p3_3v_cmon_a CHUNKED | FLOAT (:) | LRS_HK +3.3VDC Current Monitor | amps LRS_HK | Amperage of +3.3VDC Current Monitor - 0x0000 = 0.000 A; 0xFFFF = +4.000 A : A_LRS_HK.ANALOGHK[9] |
| p3_3v_mon_v CHUNKED | FLOAT (:) | LRS_HK +3.3VDC Monitor | volts LRS_HK | Voltage of +3.3VDC Monitor - 0x0000 = 0.000 V; 0xD333 = +3.300 V (nominal value); 0xFFFF = +4.000 V : A_LRS_HK.ANALOGHK[18] |
| p5v_ana_mon_v CHUNKED | FLOAT (:) | LRS_HK +5VDC Analog Monitor | volts LRS_HK | Voltage of +5VDC Analog Monitor - 0x0000 = 0.000 V; 0xA000 = +5.000 V (nominal value); 0xFFFF = +8.000 V : A_LRS_HK.ANALOGHK[16] |
| p5v_cmon_a CHUNKED | FLOAT (:) | LRS_HK +5VDC Current Monitor | amps LRS_HK | Amperage of +5VDC Current Monitor - 0x0000 = 0.000 A; 0xFFFF = +0.400 A : A_LRS_HK.ANALOGHK[8] |
| p5v_ldc_mon_v CHUNKED | FLOAT (:) | LRS_HK +5VDC LDC Monitor | volts LRS_HK | Voltage of +5VDC LDC Monitor - 0x0000 = 0.000 V; 0xA000 = +5.000 V (nominal value); 0xFFFF = +8.000 V : A_LRS_HK.ANALOGHK[12] |
| p5v_sdc_mon_v CHUNKED | FLOAT (:) | LRS_HK +5VDC SDC Monitor | volts LRS_HK | Voltage of +5VDC SDC Monitor - 0x0000 = 0.000 V; 0xA000 = +5.000 V (nominal value); 0xFFFF = +8.000 V : A_LRS_HK.ANALOGHK[13] |
| p5v_supp_mon_v CHUNKED | FLOAT (:) | LRS_HK +5VDC Supply Monitor | volts LRS_HK | Voltage of +5VDC Supply Monitor - 0x0000 = 0.000 V; 0xA000 = +5.000 V (nominal value); 0xFFFF = +8.000 V : A_LRS_HK.ANALOGHK[16] |
| pc_t CHUNKED | FLOAT (:) | LRS_HK Processor Card Thermistor | degreesC LRS_HK | Temperature of Processor Card - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| pcc_t CHUNKED | FLOAT (:) | LRS_HK Power Converter Card | degreesC LRS_HK | Temperature of Power Converter Card - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |

| | | Temperature | | |
|----------------------------|--------------------|--|------------------|--|
| ppscount CHUNKED | UINTEG_4_LE (:) | LRS_HK 1PPS sync counter | counts LRS_HK | A 32-bit count of sync pulses registered by the LRS FPGA. The value of the pulse counter starts at 0x00000000, and rolls over to 0x00000000 when it increments from 0xFFFFFFFF. |
| ppsoffset_ms CHUNKED | UINTEG_4_LE (:) | LRS_HK Oscillator Offset | ms LRS_HK | Oscillator Offset (milliseconds) for TOD (time of day) correction. |
| ppsoffset_ticks CHUNKED | UINTEG_4_LE (:) | LRS_HK Oscillator Offset Ticks | counts LRS_HK | Oscillator Offset (ticks) for TOD (time of day) correction. |
| ppsoscvl CHUNKED | UINTEG_4_LE (:) | LRS_HK Latched oscillator value at 1PPS sync | counts LRS_HK | The 32-bit count of internal 27 MHz oscillator ticks at the time when the last 1 PPS sync pulse was registered by the LRS FPGA. |
| reference_v CHUNKED | FLOAT (:) | LRS_HK Reference Voltage | volts LRS_HK | Reference Voltage - 0x0000 = 0.000 V; 0x8000 = +2.000 V (nominal value); 0xFFFF = +4.000 V : A_LRS_HK.ANALOGHK[2] |
| sdbackground CHUNKED | UINTEG_2_LE (:) | LRS_HK SD background | counts LRS_HK | The 16-bit values are measures of the measured detector background of the stellar side after subtracting the predicted dark frame. Each is a scaled average of the background levels from all tracking windows on that detector, for all measurements in the preceding one (1) second. Because the search and imaging windows move around, these values should be expected to fluctuate significantly; however, they are an indication of how well the predicted dark frame matches the background (stray light) levels. If they are occasionally very large, there is probably a stray light problem. If they are consistently very large, there is probably error in the dark frame calibration. |
| sdc_t CHUNKED | FLOAT (:) | LRS_HK Stellar Detector Card Temperature | counts LRS_HK | Temperature of Stellar Detector Card - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| sdmemconflict CHUNKED | UINTEG_2_LE (:) | LRS_HK SD Memory Conflicts | counts LRS_HK | This 16-bit counter is incremented each time the Application Mode is still accessing Stellar-Side shared memory when a new LRS cycle starts that includes new Stellar-Side data collection. This conflict is an error, which indicates that shared memory access did not complete in the allocated time and may have caused stale or invalid stellar centroids. This counter starts at 0x0000, and rolls over to 0x0000 when it increments from 0xFFFF. This counter will be reset at Application Mode initialization and by an Application Reset Counters Command (LRScmRSTCNT). |
| sdoerrun CHUNKED | UINTEG_2_LE (:) | LRS_HK SD Processing Overruns | counts LRS_HK | This 16-bit counter is incremented each time the Application Mode is still processing Stellar-Side data when a new LRS cycle starts that should include new Stellar-Side data collection. This overrun condition is a warning, which indicates that some processor activity did not complete in the allocated time and may delay reporting of the next stellar data packets. This counter starts at 0x0000, and rolls over to 0x0000 when it increments from 0xFFFF. This counter will be reset at Application Mode initialization and by an Application Reset Counters Command (LRScmRSTCNT). |
| spwdiscardbkup CHUNKED | UINTEG_4_LE (:) | LRS_HK Spacewire tlm packets dropped due to buffer not being empty | counts LRS_HK | This 32-bit counter is incremented every time a spacewire telemetry packet is dropped by Failsafe Mode while waiting for the transmission buffer to empty (an abnormal condition). It starts at 0x00000000, and rolls over to 0x00000000 when it increments from 0xFFFFFFFF. This counter will be reset at power on and by a Failsafe Reset Counters Command (LRScmRSTCNT). |
| spwdiscardcmd CHUNKED | UINTEG_4_LE (:) | LRS_HK Spacewire words dropped due to timeout waiting for full CCSDS packet | counts LRS_HK | This 32-bit counter is incremented each time a spacewire command word is dropped by Failsafe Mode due to a timeout while waiting for a full CCSDS packet (an abnormal condition). It starts at 0x00000000, and rolls over to 0x00000000 when it increments from 0xFFFFFFFF. This counter will be reset at power on and by a Failsafe Reset Counters Command (LRScmRSTCNT). |
| spwdiscardlink CHUNKED | UINTEG_4_LE (:) | LRS_HK Spacewire tlm packets dropped due to link not available | counts LRS_HK | This 32-bit counter is incremented every time a spacewire telemetry packet is dropped by Failsafe Mode while waiting for a valid spacewire link between the LRS and MEB (an abnormal condition). It starts at 0x00000000, and rolls over to 0x00000000 when it increments from 0xFFFFFFFF. This counter will be reset at power on and by a Failsafe Reset Counters Command (LRScmRSTCNT). |
| spwoutofsync CHUNKED | UINTEG_4_LE (:) | LRS_HK Spacewire words skipped to find sync | counts LRS_HK | This 32-bit counter is incremented each time a spacewire command word is skipped by Failsafe Mode to reach a valid packet sync (an abnormal condition). It starts at 0x00000000, and rolls over to 0x00000000 when it increments from 0xFFFFFFFF. This counter will be reset at power on and by a Failsafe Reset Counters Command (LRScmRSTCNT). |
| spwstat_ll_err CHUNKED | INTEG_1 (:) | LRS_HK Spacewire Status Register - Last Link Error | 1 LRS_HK | This is the Last Link Error Code portion of the LRS spacewire interface register. Flag Values: [0, '1', '2', '3'] Flag Meanings: ['disconnected', 'parity_err', 'esc_rec', 'credit_err'] |
| spwstat_lp_err CHUNKED | INTEG_1 (:) | LRS_HK Spacewire Status Register - Last Packet Error | 1 LRS_HK | This is the Last Packet Error Code portion of the LRS spacewire interface register. Flag Values: [0, '1', '2', '3'] Flag Meanings: ['no_error', 'eep_rec', 'incomplete_sw', 'invalid'] |
| spwstat_pec CHUNKED | UINTEG_1_LE (:) | LRS_HK Spacewire Status Register - Packet Error Counter | counts LRS_HK | This is the 6-bit Packet Error Counter portion of the LRS spacewire interface status register |
| spwstat_st_f CHUNKED | INTEG_1 (:) | LRS_HK Spacewire Status Register - Status | 1 LRS_HK | This is the status flag portion of the LRS spacewire interface status register. Flag Values: [0, '1'] Flag Meanings: ['not_running', 'running'] |

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| srate_x CHUNKED | FLOAT (:) | LRS_HK Stellar Pattern Rate X | pixels/sec LRS_HK | X component (tip/tilt) of the stellar rate pattern estimate. |
| srate_y CHUNKED | FLOAT (:) | LRS_HK Stellar Pattern Rate Y | pixels/second LRS_HK | Y component (tip/tilt) of the stellar rate pattern estimate |
| srate_z CHUNKED | FLOAT (:) | LRS_HK Stellar Pattern Rate Z | radians/second LRS_HK | Z (rotation) component of the stellar rate pattern estimate |
| stellar_barrel1_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #7 (Stellar Side Barrel #1 Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #7 (Stellar Side Barrel #1) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| stellar_barrel2_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #8 (Stellar Side Barrel #2 Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #8 (Stellar Side Barrel #2) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| stellar_barrel3_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #9 (Stellar Side Barrel #3 Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #9 (Stellar Side Barrel #3) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| stellar_shroud_t CHUNKED | FLOAT (:) | LRS_HK Optics Thermistor #10 (Stellar Side Shroud Temperature) | degreesC LRS_HK | Temperature of Optics Thermistor #10 (Stellar Side Shroud) - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| sysstat_ac_en CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - Analog Converter Status | 1 LRS_HK | The current status of the LRS FPGA Analog Converter. (0 =DISABLED (abnormal condition); 1 = ENABLED (normal operating condition)) Flag Values: ['0', '1'] Flag Meanings: ['disabled', 'enabled'] |
| sysstat_hk CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register HK Working | 1 LRS_HK | The current status of the Housekeeping working (0 = Finished Execution; 1 = Executing). Note: The FPGA toggles these values based on what logic is executing, so they may show up as 0 or 1 based on when the packet is generated Flag Values: ['0', '1'] Flag Meanings: ['finished', 'executing'] |
| sysstat_j1 CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - Jumper 1 | 1 LRS_HK | Jumper 1 status (no planned use on ATLAS). 0 = Jumper is DISCONNECTED (normal operating condition) Flag Values: ['0', '1'] Flag Meanings: ['disconnected', 'connected'] |
| sysstat_j2 CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - Jumper 2 | 1 LRS_HK | Jumper 2 status (no planned use on ATLAS). 0 = Jumper is DISCONNECTED (normal operating condition) Flag Values: ['0', '1'] Flag Meanings: ['disconnected', 'connected'] |
| sysstat_ldc CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - LDC Status | 1 LRS_HK | The current status of the Laser Detector Card (LDC) working (0 = Finished Execution; 1 = Executing). Note: The FPGA toggles these values based on what logic is executing, so they may show up as 0 or 1 based on when the packet is generated Flag Values: ['0', '1'] Flag Meanings: ['finished', 'executing'] |
| sysstat_ldc_en CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - LDC Power and Signals Enable Status | 1 LRS_HK | The current status of the LRS FPGA LDC (Laser Detector Card) Power and Signals. (0 = DISABLED (abnormal condition); 1 = ENABLED (normal operating condition)) Flag Values: ['0', '1'] Flag Meanings: ['disabled', 'enabled'] |
| sysstat_ldca_cable CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - LDC Analog Cable Status | 1 LRS_HK | The current status of the LRS FPGA LDCA (Laser Detector Card Analog) Cable. (0 = DISCONNECTED (abnormal condition); 1 = CONNECTED (normal operating condition)) Flag Values: ['0', '1'] Flag Meanings: ['disconnected', 'connected'] |
| sysstat_ldcd_cable CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - LDC Digital Cable Status | 1 LRS_HK | The current status of the LRS FPGA LCD (Laser Detector Card Digital Cable). (0 = DISCONNECTED (abnormal condition); 1 = CONNECTED (normal operating condition)) Flag Values: ['0', '1'] Flag Meanings: ['disconnected', 'connected'] |
| sysstat_lsync CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - Laser | 1 LRS_HK | The current validity of the Laser Sync (0 = INVALID (abnormal condition); 1 = VALID (normal operating condition)) |

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| | | Sync validity Status | | Flag Values: ['0', '1'] Flag Meanings: ['invalid', 'valid'] |
| sysstat_sdc CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - SDC Status | 1 LRS_HK | The current status of the Stellar Detector Card (SDC) working (0 = Finished Execution; 1 = Executing). Note: The FPGA toggles these values based on what logic is executing, so they may show up as 0 or 1 based on when the packet is generated Flag Values: ['0', '1'] Flag Meanings: ['finished', 'executing'] |
| sysstat_sdc_en CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - SDC Power and Signals Enable Status | 1 LRS_HK | The current status of the LRS FPGA SDC (Stellar Detector Card) Power and Signals. (0 = DISABLED (abnormal condition); 1 = ENABLED (normal operating condition)) Flag Values: ['0', '1'] Flag Meanings: ['disabled', 'enabled'] |
| sysstat_sdca_cable CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - SDC Analog Cable Status | 1 LRS_HK | The current status of the LRS FPGA SDCD (Stellar Detector Card Digital Cable). (0 = DISCONNECTED (abnormal condition); 1 = CONNECTED (normal operating condition)) Flag Values: ['0', '1'] Flag Meanings: ['disconnected', 'connected'] |
| sysstat_sdc_d_cable CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - SDC Digital Cable Status | 1 LRS_HK | The current status of the LRS FPGA SDCD (Stellar Detector Card Digital Cable). (0 = DISCONNECTED (abnormal condition); 1 = CONNECTED (normal operating condition)) Flag Values: ['0', '1'] Flag Meanings: ['disconnected', 'connected'] |
| sysstat_sw CHUNKED | INTEGER_1 (:) | LRS_HK System Status Register - Spacewire Module Status | 1 LRS_HK | The current status of the Spacewire Module (0 = NOT RUNNING (abnormal condition); 1 = RUNNING (normal operating condition)) Flag Values: ['0', '1'] Flag Meanings: ['not_running', 'running'] |
| therm_gnd_ref_v CHUNKED | FLOAT (:) | LRS_HK Thermistor Reference (ground) | volts LRS_HK | Voltage of Thermistor Reference (ground) - 0x0000 = 0.000 V (nominal value); 0xFFFF = +4.000 V : A_LRS_HK.ANALOGHK[20] |
| therm_open_ref_v CHUNKED | FLOAT (:) | LRS_HK Thermistor Reference (open) | volts LRS_HK | Voltage of Thermistor Reference (open) - 0x0000 = 0.000 V; 0xFFFF = +4.000 V (nominal value) : A_LRS_HK.ANALOGHK[21] |
| timecnt CHUNKED | UINT_2_LE (:) | LRS_HK Valid Time Sync Command Counter | counts LRS_HK | The Valid Time Sync Command Counter is a 16-bit counter that increments each time that the Failsafe Mode processes a valid command of the corresponding command type. A valid command is defined as a command that passes all verification tests. The counter starts at 0x0000, and rolls over to 0x0000 when it increments from 0xFFFF. The counter is reset at power on and by a Failsafe Reset Counters Command (LRSfscmRSTCNT). |
| timeerrcnt CHUNKED | UINT_2_LE (:) | LRS_HK Time Sync Command Error Counter | counts LRS_HK | The 16-bit Time Sync Command error Counter is incremented every time the Failsafe Mode has one or more command verification or processing errors with the corresponding command type (abnormal conditions). The counter starts at 0x0000, and rolls over to 0x0000 when it increments from 0xFFFF. The counter increments only once per command when there is at least one verification/processing error for that command. TIMEERRCODE will indicate the type of error. The counter is reset at power on and by a Failsafe Reset Counters Command (LRSfscmRSTCNT). |
| timeerrcode CHUNKED | UINT_2_LE (:) | LRS_HK Time Sync Command Error Code | counts LRS_HK | The 16-bit Time Sync Error Code indicates the last type of time sync error that occurred in Failsafe Mode. This code will be reset at power on and by a Failsafe Reset Counters Command (LRSfscmRSTCNT). The error codes are defined in Table 19: Command Validation Error Codes. |

Group: /lrs/laser_centroid

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| Description | (Attribute) | Contains parameters relating to the Application Laser Centroid (LCENT) Data. The (Application Mode) Laser Centroid Data Packet contains reported Laser-Side Centroids, which are part of the core LRS data output. This packet normally will contain 10 valid centroids, reported and stored at a nominally 50 Hz rate and is available through all data channels (SSR, real time telemetry, and onboard to the spacecraft ACS). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS Application Laser Centroid Data (nominally fifty per second). | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cent_h CHUNKED | FLOAT (:) | LRS_LCENT centroid H | pixels LRS_LCENT | The centroid H value. The centroids are the Transmit Laser Centroids and TAMS Centroids. |
| cent_mag CHUNKED | INTEGER_2 (:) | LRS_LCENT centroid magnitude | counts LRS_LCENT | The 12-bit centroid magnitude. The centroids are the Transmit Laser Centroids and TAMS Centroids. |
| cent_v CHUNKED | FLOAT (:) | LRS_LCENT centroid V | pixels LRS_LCENT | The centroid V value. The centroids are the Transmit Laser Centroids and TAMS Centroids. |
| centofintbase CHUNKED | UINT_4_LE (:) | Center of integration base | counts LRS | Base age of centroids relative to secondary header timestamp. This 32-bit value indicates how many 843.75 kHz time ticks of offset should be applied between the secondary header timestamp and the center_of_integration for the laser centroids reported. This time offset assumes that the secondary header timestamp represents an exact milli-second (that is, is accurate beyond the precision expressed in the timestamp). The offset is based on the LRS internal 27 MHz oscillator |

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| | | | | (divided by 32), and it can express offset from zero to more than 84 minutes with about 1.185 micro second resolution. Under normal operating conditions, the offset should never exceed 20 milli seconds (about 16875 counts). Centroid timetags offset with this value alone should be adequate for coarse geo-location, but not precision geo-location knowledge as expected for science (individual centroid offsets are required for that purpose). |
| coi_offset CHUNKED | INTEGER_2 (:) | Center of integration offset | counts LRS | The signed 16-bit center of integration offset for this specific centroid. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time values retrieved from the CCSDS header timestamps, relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| quality_f CHUNKED | INTEGER_1 (:) | LRS_LCENT Centroid quality | 1 LRS_LCENT | Flag indicates centroids pass basic validity checks in the LRS software. 0 = valid centroids; 1 = the corresponding centroid is considered questionable (that is, the corresponding centroid should not be expected to report a valid target with full accuracy). The win parameter within this group correlates the flags to tams/laser windows. However, the correlation of the windows to the actual tams/laser spots is not guaranteed. Flag Values: ['0', '1'] Flag Meanings: ['valid', 'questionable'] |
| trackstat_f CHUNKED | INTEGER_1 (:) | LRS_LCENT Tracking status | 1 LRS_LCENT | Flag indicates tracking status for centroid; 1 = valid tracking of that centroid window; 0 = the corresponding window is in a searching or acquiring state (that is, the corresponding centroid should not be considered to report a valid target). The win parameter within this group correlates the flags to tams/laser windows. However, the correlation of the windows to the actual tams/laser spots is not guaranteed. Flag Values: ['0', '1'] Flag Meanings: ['acq_state', 'track_state'] |
| win CHUNKED | INTEGER_1 (:) | Window | 1 LRS_LCENT | Indicates the window corresponding to each component of the centmagtime and corresponding flags. Values of 1-4 correspond to TAMS windows; values of 5-10 correspond to laser windows. Assignment of a window to a particular spot is not guaranteed. Flag Values: ['0', '1', '2', '3', '4', '5', '6', '7', '8', '9', '10'] Flag Meanings: ['none', 'tams0', 'tams1', 'tams2', 'tams3', 'laser1', 'laser2', 'laser3', 'laser4', 'laser5', 'laser6'] |

Group: /lrs/laser_image

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| Description | (Attribute) | The (Application Mode) Laser Image Data Packet contains measured pixel data from a Laser-Side image dump. This SSR packet is only reported when requested by command, and is normally used only for diagnostic purposes. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS Laser Image Data Packet. (This packet is dumped only when commanded.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| centofintbase CHUNKED | UINT_4_LE (:) | Center of integration base | counts LRS | Base age of centroids relative to secondary header timestamp. This 32-bit value indicates how many 843.75 kHz time ticks of offset should be applied between the secondary header timestamp and the center_of_integration for the laser centroids reported. This time offset assumes that the secondary header timestamp represents an exact milli-second (that is, is accurate beyond the precision expressed in the timestamp). The offset is based on the LRS internal 27 MHz oscillator (divided by 32), and it can express offset from zero to more than 84 minutes with about 1.185 micro second resolution. Under normal operating conditions, the offset should never exceed 20 milli seconds (about 16875 counts). Centroid timetags offset with this value alone should be adequate for coarse geo-location, but not precision geo-location knowledge as expected for science (individual centroid offsets are required for that purpose). |
| datatype CHUNKED | UINT_2_LE (:) | LRS_xIMG Type of pixel data | 1 LRS_SIMG | This 16-bit value contains a code indicating the type of pixel data being reported in the packet. The valid codes are defined as follows (other codes are invalid): 0 Raw Pixel Data (no compensation), 4369 Dark Frame Corrected Data, 8738 Data Corrected for both Dark Frame and Local Dark Flag Values: ['0', '4369', '8738'] Flag Meanings: ['raw', 'dark', 'adj'] |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | The base age of the centroids in GPS seconds relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ldc_t CHUNKED | FLOAT (:) | LRS_HK Laser Detector Card Temperature | degrees LRS_HK | Temperature of Laser Detector Card - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| nread CHUNKED | UINT_2_LE (:) | LRSxLIMG Window read count | counts LRS_xIMG | This 16-bit value is the number of reads performed on the window. This value will count up to the requested number of reads on successive packets. The detector has a settling behavior when read on successive cycles, so it may be necessary to perform multiple back-to-back reads to mimic the behavior that will occur when windows are tracked. |

Group: /lrs/laser_image/window_nn

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| Description | (Attribute) | This group contains five of the laser image windows reported within the LRStmLIMG packet. This SSR packet is only reported when requested by command, and is normally used only for diagnostic purposes. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS Laser Image Data Packet. This packet is dumped only when commanded.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| ds_pixel_64_index CONTIGUOUS | INTEGER_1 (64) | Pixel Index for 64 pixel arrays | 1 | Dimension scale for 64-pixel arrays. |
| hloc CHUNKED | UINT_2_LE (:) | LRS_LIMG Horizontal location of window | pixels LRS_LIMG | Horizontal location of window. The 16-bit values for the coordinates of the minimum column contained within the window. The TAMS window uses 8 x 8 pixels, so the coordinates of the center will be 3.5 pixels greater in each axis. |
| pixeldata CHUNKED | UINT_2_LE (: x 64) | LRS_LIMG pixel data | counts LRS_LIMG | Pixel data for window- The arrays contains the 64 pixels of a TAMS window. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], then [HLOC+7, VLOC], then [HLOC, VLOC+1], and ending with [HLOC+7, VLOC+7]). |
| vloc CHUNKED | UINT_2_LE (:) | LRS_LIMG Vertical location of window | pixels LRS_LIMG | Vertical location of window. The 16-bit values for the coordinates of the minimum row contained within the window. The TAMS window uses 8 x 8 pixels, so the coordinates of the center will be 3.5 pixels greater in each axis. |
| Group: /lrs/laser_window | | | | |
| Description | (Attribute) | The (Application Mode) Transmit Laser Window Data Packet (LRStmLWIN) contains measured pixel data from a Transmit Laser (Laser-Side) centroid window. This SSR packet is only reported when requested by command, and is normally used only for diagnostic purposes. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS Transmit Laser Window Data Packet. (This packet is dumped only when commanded.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| adjdata CHUNKED | UINT_2_LE (: x 25) | LRS_LWIN Adjusted Pixel data for window | counts LRS_LWIN | Adjusted Pixel data for window - The array contains 25 pixels of the window corrected for both the predicted dark frame and the LOCALDARK bias. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], , then [HLOC+4, VLOC], then [HLOC, VLOC+1], and ending with [HLOC+4, VLOC+4]). |
| cent_h CHUNKED | FLOAT (:) | LRS_LCENT centroid H | pixels LRS_LCENT | The centroid H value (in 256ths of a pixel) |
| cent_mag CHUNKED | INTEGER_2 (:) | LRS_LCENT centroid magnitude | counts LRS_LCENT | The 12-bit centroid magnitude. From Word 2, bits 15 (MSB) to 4 |
| cent_v CHUNKED | FLOAT (:) | LRS_LCENT centroid V | pixels LRS_LCENT | The centroid V value (in 256ths of a pixel). |
| centofintbase CHUNKED | UINT_4_LE (:) | Center of integration base | counts LRS | Base age of centroids relative to secondary header timestamp. This 32-bit value indicates how many 843.75 kHz time ticks of offset should be applied between the secondary header timestamp and the center_of_integration for the laser centroids reported. This time offset assumes that the secondary header timestamp represents an exact milli-second (that is, is accurate beyond the precision expressed in the timestamp). The offset is based on the LRS internal 27 MHz oscillator (divided by 32), and it can express offset from zero to more than 84 minutes with about 1.185 micro second resolution. Under normal operating conditions, the offset should never exceed 20 milli seconds (about 16875 counts). Centroid timetags offset with this value alone should be adequate for coarse geo-location, but not precision geo-location knowledge as expected for science (individual centroid offsets are required for that purpose). |
| coi_offset CHUNKED | INTEGER_2 (:) | Center of integration offset | counts LRS | The signed 16-bit center of integration offset for this specific centroid. |
| darkdata CHUNKED | UINT_2_LE (: x 25) | LRS_LWIN Dark pixel data for window | counts LRS_LWIN | Dark pixel data for window- The array contains 25 pixels corrected for the predicted dark frame. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], , then [HLOC+4, VLOC], then [HLOC, VLOC+1], and ending with [HLOC+4, VLOC+4]). |
| darkfactor CHUNKED | UINT_2_LE (:) | LRS_xWIN Dark Factor | counts LRS_TWING | Dark Factor - This 16-bit value is the scale factor applied when correcting the window reading for dark frame. |
| darkoff_next CHUNKED | UINT_2_LE (:) | LRS_xWIN Next Frame Dark Offset | counts LRS_TWING | This 16-bit value contains the dark offset value that will be used for processing this window in the next frame. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time of the centroids in seconds since the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_pixel_25_index CONTIGUOUS | INTEGER_1 (25) | Pixel Index for 25 pixel arrays | 1 | Dimension scale for 25-pixel arrays. |
| hdot_avg CHUNKED | FLOAT (:) | LRS_xWIN Average Horizontal Velocity | pixels/second LRS_xWIN | This 32-bit value contains the average horizontal velocity for the target in pixels per frame, 1:23:8 fixed point format. |
| hloc | UINT_2_LE | LRS_LWIN Horizontal | pixels | Horizontal location of window. The 16-bit values for the coordinates of the minimum column contained within the window. |

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| CHUNKED | (:) | location of window | LRS_LWIN | The Transmit Laser window uses 5 x 5 pixels, so the coordinates of the center will be 2.5 pixels greater in each axis. |
| ldc_t CHUNKED | FLOAT (:) | LRS_HK Laser Detector Card Temperature | Degrees LRS_HK | Temperature of Laser Detector Card - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| localdark CHUNKED | UINT_2_LE (:) | LRS_xWIN Local Dark | counts LRS_xWIN | Local Dark - This 16-bit value is the local dark correction applied when correcting the window reading for stray light and/or residual dark frame bias. |
| max_mag CHUNKED | UINT_2_LE (:) | LRS_xWIN Maximum Magnitude | counts LRS_xWIN | This 16-bit value contains the maximum magnitude value for the target. |
| min_mag CHUNKED | UINT_2_LE (:) | LRS_xWIN Minimum Magnitude | counts LRS_xWIN | This 16-bit value contains the minimum magnitude value for the target. |
| quality_f CHUNKED | INTEGER_1 (:) | LRS_LCENT Centroid quality | 1 LRS_LCENT | This 16-bit value contains a single bit for the quality of this image only. Flag Values: ['0', '1'] Flag Meanings: ['valid', 'questionable'] |
| rawdata CHUNKED | UINT_2_LE (: x 25) | LRS_LWIN Raw pixel data for window | counts LRS_LWIN | Raw pixel data for window- The array contains 25 uncorrected pixel values. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], then [HLOC+4, VLOC], then [HLOC, VLOC+1], and ending with [HLOC+4, VLOC+4]). |
| status_f CHUNKED | UINT_2_LE (:) | LRS_xWIN Target status | 1 LRS_xWIN | Target status-This 16-bit value contains a code indicating the target status applicable to the window reported in this packet. The valid codes are defined as follows (other codes are invalid): 65531 Dimmest Spot (not currently used), 65532 Invalid Rate, 65533 Collided with Another Window, 65534 Violated Minimum Area Limit, 65535 Violated Image Bound, 0 Empty, 1 Acquire1, 2 Acquire2, 3 Tracking Flag Values: ['0', '1', '2', '3', '65532', '65534', '65535'] Flag Meanings: ['empty', 'acq1', 'acq2', 'track', 'not_allowed', 'collided', 'violated'] |
| tickattime CHUNKED | UINT_4_LE (:) | LRS_xWIN Oscillator Tick Value | counts LRS_xWIN | Oscillator tick value at last time pulse. This 32-bit value is the reading from the internal 27 MHz oscillator at the last 1 PPS time tick. |
| tickfirst CHUNKED | UINT_4_LE (:) | LRS_xWIN Oscillator ticks when first pixel is read | counts LRS_xWIN | Oscillator ticks when first pixel is read. The 32-bit value reading from the internal 27 MHz oscillator when the first pixel of the window was read. They can be used to confirm the calculation of the center of integration offsets. |
| ticklast CHUNKED | UINT_4_LE (:) | LRS_xWIN Oscillator ticks when last pixel is read | counts LRS_xWIN | Oscillator ticks when last pixel is read. The 32-bit value reading from the internal 27 MHz oscillator when the last pixel of the window was read. They can be used to confirm the calculation of the center of integration offsets. |
| use_f CHUNKED | INTEGER_1 (:) | LRS_xWIN Window Use Flag | 1 LRS_xWIN | Window Use - This 16-bit value reports the way that the window is currently being used by the search and tracking algorithms. The valid codes are defined as follows (other codes are invalid): 0 = Inactive, 1 = Image Generation, 2 = Searching, 3 = Tracking Flag Values: ['0', '1', '2', '3'] Flag Meanings: ['inactive', 'image_gen', 'search', 'track'] |
| vdot_avg CHUNKED | FLOAT (:) | LRS_LWIN Average Vertical Velocity | pixels/second LRS_LWIN | This 32-bit value contains the average vertical velocity for the target in pixels per frame, 1:23:8 fixed point format. |
| vloc CHUNKED | UINT_2_LE (:) | LRS_LWIN Vertical location of window | pixels LRS_LWIN | Vertical location of window. The 16-bit values for the coordinates of the minimum row contained within the window. The Transmit Laser window uses 5 x 5 pixels, so the coordinates of the center will be 2.5 pixels greater in each axis. |
| windex CHUNKED | UINT_2_LE (:) | LRS_xWIN Window Index | counts LRSxTWIN | Window Index- The 16-bit value contains the window index reported in this packet. |

Group: /lrs/stellar_centroid

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|--------------------------|-----------------------|--|---------------------|---|
| Description | (Attribute) | The (Application Mode) Stellar Centroid Data Packet contains reported Stellar-Side Centroids, which are part of the core LRS data output. This packet is normally reported and stored at a nominally 10 Hz rate with a variable number of stars reported and is available through all data channels (SSR, real time telemetry, and onboard to the spacecraft ACS). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS Stellar Centroid Data Packet. (nominally 10 per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cent_h CHUNKED | FLOAT (:) | LRS_LCENT centroid H | pixels LRS_LCENT | The centroid H value. |
| cent_mag CHUNKED | INTEGER_2 (:) | LRS_LCENT centroid magitude | counts LRS_LCENT | The 12-bit centroid magnitude. From Word 2, bits 15 (MSB) to 4 |
| cent_v CHUNKED | FLOAT (:) | LRS_LCENT centroid V | pixels LRS_LCENT | The centroid V value. |
| centofintbase CHUNKED | UINT_4_LE (:) | Center of integration base | counts LRS | Base age of centroids relative to secondary header timestamp. This 32-bit value indicates how many 843.75 kHz time ticks of offset should be applied between the secondary header timestamp and the center_of_integration for the laser centroids |

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| | | | | reported. This time offset assumes that the secondary header timestamp represents an exact milli-second (that is, is accurate beyond the precision expressed in the timestamp). The offset is based on the LRS internal 27 MHz oscillator (divided by 32), and it can express offset from zero to more than 84 minutes with about 1.185 micro second resolution. Under normal operating conditions, the offset should never exceed 20 milli seconds (about 16875 counts). Centroid timetags offset with this value alone should be adequate for coarse geo-location, but not precision geo-location knowledge as expected for science (individual centroid offsets are required for that purpose). |
| coi_offset CHUNKED | INTEGER_2 (:) | Center of integration offset | counts LRS | The signed 16-bit center of integration offset for this specific centroid. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Retrieved times from the CCSDS header timestamps, in seconds relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| quality_f CHUNKED | INTEGER_1 (:) | LRS_LCENT Centroid quality | 1 LRS_LCENT | Flag indicates centroids pass basic validity checks in the LRS software. 0 indicate valid centroids; 1 indicate the corresponding centroid is considered questionable (that is, the corresponding centroid should not be expected to report a valid target with full accuracy). Flag Values: ['0', '1'] Flag Meanings: ['valid', 'questionable'] |
| trackstat_f CHUNKED | INTEGER_1 (:) | LRS_LCENT Tracking status | 1 LRS_LCENT | Flag indicates tracking status for centroid. 1 indicate valid tracking of that centroid window; 0 indicate the corresponding window is in a searching or acquiring state (that is, the corresponding centroid should not be considered to report a valid target). Flag Values: ['0', '1'] Flag Meanings: ['acq_state', 'track_state'] |

Group: /lrs/stellar_image

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|--------------------------|--------------------------|---|--|--|
| Description | (Attribute) | The (Application Mode) Laser Image Data Packet contains measured pixel data from a Laser-Side image dump. This SSR packet is only reported when requested by command, and is normally used only for diagnostic purposes. Packets contain pixel data in the form of 6x8 windows. Each 'pixeldata' array contains 64 pixels of an image. All 6 images are put together to make a 1024 by 1024 image. During the image dump, no spots are tracked (the LCENT packets are not telemetered to ground while dumping the image). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS Laser Image Data Packet. (This packet is dumped only when commanded.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| centofintbase CHUNKED | UINT_4_LE (:) | Center of integration base | counts LRS | Base age of centroids relative to secondary header timestamp. This 32-bit value indicates how many 843.75 kHz time ticks of offset should be applied between the secondary header timestamp and the center_of_integration for the laser centroids reported. This time offset assumes that the secondary header timestamp represents an exact milli-second (that is, is accurate beyond the precision expressed in the timestamp). The offset is based on the LRS internal 27 MHz oscillator (divided by 32), and it can express offset from zero to more than 84 minutes with about 1.185 micro second resolution. Under normal operating conditions, the offset should never exceed 20 milli seconds (about 16875 counts). Centroid timetags offset with this value alone should be adequate for coarse geo-location, but not precision geo-location knowledge as expected for science (individual centroid offsets are required for that purpose). |
| cycle CHUNKED | UINT_2_LE (:) | cycle LRS_SIMG Cycle | counts LRS_SIMG | This 16-bit value is the number (0 to 4 are valid) of the cycle within the 100 millisecond integration period on which this packet was generated. The actual window used for the pixel data will be window (6*CYCLE + n). |
| datatype CHUNKED | UINT_2_LE (:) | LRS_xIMG Type of pixel data | 1 LRS_SIMG | This 16-bit value contains a code indicating the type of pixel data being reported in the packet. The valid codes are defined as follows (other codes are invalid): 0 Raw Pixel Data (no compensation), 4369 Dark Frame Corrected Data, 8738 Data Corrected for both Dark Frame and Local Dark Flag Values: ['0', '4369', '8738'] Flag Meanings: ['raw', 'dark', 'adj'] |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time computed from the base age of the centroids, in seconds since the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| nread CHUNKED | UINT_2_LE (:) | LRSxLIMG Window read count | counts LRS_xLIMG | This 16-bit value is the number of reads performed on the window. This value will count up to the requested number of reads on successive packets. The detector has a settling behavior when read on successive cycles, so it may be necessary to perform multiple back-to-back reads to mimic the behavior that will occur when windows are tracked. |
| sd_c_t CHUNKED | FLOAT (:) | LRS_HK Stellar Detector Card Temperature | Degrees LRS_HK | Temperature of Stellar Detector Card - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |

Group: /lrs/stellar_image/window_nn

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| Description | (Attribute) | This group contains five of the laser image windows reported within the LRStmLIMG packet. This SSR packet is only reported when requested by command, and is normally used only for diagnostic purposes. Window 0 is a vertical slice of 8 pixels starting at 1, windows step 48 verticals, the next image starts at vertical 49, Window 1 is a vertical slice of 8 pixels starting at 9, windows step 48 verticals, | | |
|-------------|-------------|--|--|--|

| | | the next image starts at vertical 57, | | |
|-----------------------------------|-----------------------|--|---|--|
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS Stellar Image Data Packet. This packet is dumped only when commanded.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| ds_pixel_64_index CONTIGUOUS | INTEGER_1 (64) | Pixel Index for 64 pixel arrays | 1 | Dimension scale for 64-pixel arrays. |
| hloc CHUNKED | UINT_2_LE (:) | LRS_LIMG Horizontal location of window | pixels LRS_LIMG | Horizontal location of window. The 16-bit values for the coordinates of the minimum column contained within the window. All windows are 8 x 8 pixels (same size as TAMS), so the coordinates of the center will be 3.5 pixels greater in each axis. |
| pixeldata CHUNKED | UINT_2_LE (: x 64) | LRS_LIMG pixel data | counts LRS_LIMG | Pixel data for window- The arrays contains the 64 pixels of a TAMS window. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], then [HLOC+7, VLOC], then [HLOC, VLOC+1], and ending with [HLOC+7, VLOC+7]). |
| vloc CHUNKED | UINT_2_LE (:) | LRS_LIMG Vertical location of window | pixels LRS_LIMG | Vertical location of window. The 16-bit values for the coordinates of the minimum row contained within the window. All windows are 8 x 8 pixels (same size as TAMS), so the coordinates of the center will be 3.5 pixels greater in each axis. |
| Group: /lrs/stellar_window | | | | |
| Description | (Attribute) | The (Application Mode) Stellar Window Data Packet contains measured pixel data from a Stellar-Side centroid window. This SSR packet is only reported when requested by command, and is normally used only for diagnostic purposes. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS Stellar Window Data Packet. (This packet is dumped only when commanded.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| adjdata CHUNKED | UINT_2_LE (: x 64) | LRS_SWIN Adjusted Pixel data for window | counts LRS_SWIN | Adjusted Pixel data for window - The array contains the 64 pixels of the window containing the pixel readings after they are corrected for both the predicted dark frame and the LOCALDARK bias. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], , then [HLOC+7, VLOC], then [HLOC, VLOC+1], , and ending with [HLOC+7, VLOC+7]). |
| cent_h CHUNKED | FLOAT (:) | LRS_SWIN centroid H | pixels LRS_SWIN | The centroid H value (in 256ths of a pixel). |
| cent_mag CHUNKED | INTEGER_2 (:) | LRS_SWIN centroid magitude | counts LRS_SWIN | The 12-bit centroid magnitude. From Word 2, bits 15 (MSB) to 4. This is a copy of the word that should be reported in the (Application mode) Stellar Centroid Data Packet for the window reported here. |
| cent_v CHUNKED | FLOAT (:) | LRS_SWIN centroid V | pixels LRS_SWIN | The centroid V value (in 256ths of a pixel). |
| centofintbase CHUNKED | UINT_4_LE (:) | Center of integration base | counts LRS | Base age of centroids relative to secondary header timestamp. This 32-bit value indicates how many 843.75 kHz time ticks of offset should be applied between the secondary header timestamp and the center_of_integration for the laser centroids reported. This time offset assumes that the secondary header timestamp represents an exact milli-second (that is, is accurate beyond the precision expressed in the timestamp). The offset is based on the LRS internal 27 MHz oscillator (divided by 32), and it can express offset from zero to more than 84 minutes with about 1.185 micro second resolution. Under normal operating conditions, the offset should never exceed 20 milli seconds (about 16875 counts). Centroid timetags offset with this value alone should be adequate for coarse geo-location, but not precision geo-location knowledge as expected for science (individual centroid offsets are required for that purpose). |
| coi_offset CHUNKED | INTEGER_2 (:) | Center of integration offset | counts LRS | The signed 16-bit center of integration offset for this specific centroid. |
| darkdata CHUNKED | UINT_2_LE (: x 64) | LRS_SWIN Dark pixel data for window | counts LRS_SWIN | Dark pixel data for window- The array contains the 64 pixels of the window contain the pixel readings after they are corrected for the predicted dark frame. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], , then [HLOC+7, VLOC], then [HLOC, VLOC+1], , and ending with [HLOC+7, VLOC+7]). |
| darkfactor CHUNKED | UINT_2_LE (:) | LRS_xWIN Dark Factor | counts LRS_TWING | Dark Factor - This 16-bit value is the scale factor applied when correcting the window reading for dark frame. |
| darkoff_next CHUNKED | UINT_2_LE (:) | LRS_xWIN Next Frame Dark Offset | counts LRS_TWING | This 16-bit value contains the dark offset value that will be used for processing this window in the next frame. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time of the centroid, in seconds since the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_pixel_64_index CONTIGUOUS | INTEGER_1 (64) | Pixel Index for 64 pixel arrays | 1 | Dimension scale for 64-pixel arrays. |
| hdot_avg CHUNKED | FLOAT (:) | LRS_xWIN Average Horizontal Velocity | pixels/second LRS_xWIN | This 32-bit value contains the average horizontal velocity for the target in pixels per frame, 1:23:8 fixed point format. |
| hloc CHUNKED | UINT_2_LE (:) | LRS_SWIN Horizontal location of window | pixels LRS_SWIN | Horizontal location of window. The 16-bit values for the coordinates of the minimum column contained within the window. The Stellar window uses 8 x 8 pixels, so the coordinates of the center will be 3.5 pixels greater in each axis. |

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| localdark CHUNKED | UINT_2_LE (:) | LRS_xWIN Local Dark | counts LRS_xWIN | Local Dark - This 16-bit value is the local dark correction applied when correcting the window reading for stray light and/or residual dark frame bias. |
| max_mag CHUNKED | UINT_2_LE (:) | LRS_xWIN Maximum Magnitude | counts LRS_xWIN | This 16-bit value contains the maximum magnitude value for the target. |
| min_mag CHUNKED | UINT_2_LE (:) | LRS_xWIN Minimum Magnitude | counts LRS_xWIN | This 16-bit value contains the minimum magnitude value for the target. |
| quality_f CHUNKED | INTEGER_1 (:) | LRS_SWIN Centroid quality flag | 1 LRS_SWIN | Flag indicates centroids pass basic validity checks in the LRS software. 0 indicate valid centroids; 1 indicate the corresponding centroid is considered questionable (that is, the corresponding centroid should not be expected to report a valid target with full accuracy). Flag Values: [0, '1'] Flag Meanings: ['valid', 'questionable'] |
| rawdata CHUNKED | UINT_2_LE (: x 64) | LRS_SWIN Raw pixel data for window | counts LRS_SWIN | Raw pixel data for window- The array contains the 64 pixels of the window contain the ADC readings for the pixels without onboard corrections. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], , then [HLOC+7, VLOC], then [HLOC, VLOC+1], , and ending with [HLOC+7, VLOC+7]). |
| sdct CHUNKED | FLOAT (:) | LRS_HK Stellar Detector Card Temperature | degrees LRS_HK | Temperature of Stellar Detector Card - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| status_f CHUNKED | UINT_2_LE (:) | LRS_xWIN Target status | 1 LRS_xWIN | Target status-This 16-bit value contains a code indicating the target status applicable to the window reported in this packet. The valid codes are defined as follows (other codes are invalid): 65531 Dimmest Spot (not currently used), 65532 Invalid Rate, 65533 Collided with Another Window, 65534 Violated Minimum Area Limit, 65535 Violated Image Bound, 0 Empty, 1 Acquire1, 2 Acquire2, 3 Tracking Flag Values: [0, '1', '2', '3', '65532', '65534', '65535'] Flag Meanings: ['empty', 'acq1', 'acq2', 'track', 'not_allowed', 'collided', 'violated'] |
| tickatime CHUNKED | UINT_4_LE (:) | LRS_xWIN Oscillator Tick Value | counts LRS_xWIN | Oscillator tick value at last time pulse. This 32-bit value is the reading from the internal 27 MHz oscillator at the last 1 PPS time tick. |
| tickfirst CHUNKED | UINT_4_LE (:) | LRS_xWIN Oscillator ticks when first pixel is read | counts LRS_xWIN | Oscillator ticks when first pixel is read. The 32-bit value reading from the internal 27 MHz oscillator when the first pixel of the window was read. They can be used to confirm the calculation of the center of integration offsets. |
| ticklast CHUNKED | UINT_4_LE (:) | LRS_xWIN Oscillator ticks when last pixel is read | counts LRS_xWIN | Oscillator ticks when last pixel is read. The 32-bit value reading from the internal 27 MHz oscillator when the last pixel of the window was read. They can be used to confirm the calculation of the center of integration offsets. |
| tickoverlap CHUNKED | UINT_4_LE (:) | LRS_SWIN Oscillator ticks when last pixel is read | counts LRS_SWIN | Oscillator ticks at the start or end of a pixel row overlap. The 32-bit value reading from the internal 27 MHz oscillator when the overlap started/ended. They can be used to confirm the calculation of the center of integration offsets. |
| use_f CHUNKED | INTEGER_1 (:) | LRS_xWIN Window Use Flag | 1 LRS_xWIN | Window Use - This 16-bit value reports the way that the window is currently being used by the search and tracking algorithms. The valid codes are defined as follows (other codes are invalid): 0 = Inactive, 1= Image Generation, 2 = Searching, 3 = Tracking Flag Values: [0, '1', '2', '3'] Flag Meanings: ['inactive', 'image_gen', 'search', 'track'] |
| vdot_avg CHUNKED | FLOAT (:) | LRS_LWIN Average Vertical Velocity | pixels/second LRS_LWIN | This 32-bit value contains the average vertical velocity for the target in pixels per frame, 1:23:8 fixed point format. |
| vloc CHUNKED | UINT_2_LE (:) | LRS_SWIN Vertical location of window | pixels LRS_SWIN | Vertical location of window. The 16-bit values for the coordinates of the minimum row contained within the window. The Stellar window uses 8 x 8 pixels, so the coordinates of the center will be 3.5 pixels greater in each axis. |
| windex CHUNKED | UINT_2_LE (:) | LRS_xWIN Window Index | counts LRSxTWIN | Window Index- The 16-bit value contains the window index reported in this packet. |

Group: /lrs/tams_window

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|--------------------|--------------------------|--|--------------------|---|
| Description | (Attribute) | The (Application Mode) TAMS Window Data Packet contains measured pixel data from a TAMS (Laser-Side) centroid window. This SSR packet is only reported when requested by command, and is normally used only for diagnostic purposes. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source LRS TAMS Window Data Packet. (This packet is dumped only when commanded.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| adjdata CHUNKED | UINT_2_LE (: x 64) | LRS_TWIN Adjusted Pixel data for window | counts LRS_TWIN | Adjusted Pixel data for window - The array contains the 64 pixels of the window containing the pixel readings after they are corrected for both the predicted dark frame and the LOCALDARK bias. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], , then [HLOC+7, VLOC], then [HLOC, VLOC+1], , and ending with [HLOC+7, VLOC+7]). |
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|---------------------------------|-----------------------|--|--|--|
| cent_h CHUNKED | FLOAT (:) | LRS_LCENT centroid H | pixels LRS_LCENT | The centroid H value (in 256ths of a pixel). |
| cent_mag CHUNKED | INTEGER_2 (:) | LRS_LCENT centroid magnitude | counts LRS_LCENT | The 12-bit centroid magnitude. From Word 2, bits 15 (MSB) to 4 |
| cent_v CHUNKED | FLOAT (:) | LRS_LCENT centroid V | pixels LRS_LCENT | The centroid V value (in 256ths of a pixel). |
| centofintbase CHUNKED | UINT_4_LE (:) | Center of integration base | counts LRS | Base age of centroids relative to secondary header timestamp. This 32-bit value indicates how many 843.75 kHz time ticks of offset should be applied between the secondary header timestamp and the center_of_integration for the laser centroids reported. This time offset assumes that the secondary header timestamp represents an exact milli-second (that is, is accurate beyond the precision expressed in the timestamp). The offset is based on the LRS internal 27 MHz oscillator (divided by 32), and it can express offset from zero to more than 84 minutes with about 1.185 micro second resolution. Under normal operating conditions, the offset should never exceed 20 milli seconds (about 16875 counts). Centroid timetags offset with this value alone should be adequate for coarse geo-location, but not precision geo-location knowledge as expected for science (individual centroid offsets are required for that purpose). |
| coi_offset CHUNKED | INTEGER_2 (:) | Center of integration offset | counts LRS | The signed 16-bit center of integration offset for this specific centroid. |
| darkdata CHUNKED | UINT_2_LE (: x 64) | LRS_TWIN Dark pixel data for window | counts LRS_TWIN | Dark pixel data for window- The array contains the 64 pixels of the window contain the pixel readings after they are corrected for the predicted dark frame. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], , then [HLOC+7, VLOC], then [HLOC, VLOC+1], , and ending with [HLOC+7, VLOC+7]). |
| darkfactor CHUNKED | UINT_2_LE (:) | LRS_xWIN Dark Factor | counts LRS_TWIN | Dark Factor - This 16-bit value is the scale factor applied when correcting the window reading for dark frame. |
| darkoff_next CHUNKED | UINT_2_LE (:) | LRS_xWIN Next Frame Dark Offset | counts LRS_TWIN | This 16-bit value contains the dark offset value that will be used for processing this window in the next frame. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time of the centroid, in seconds since the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_pixel_64_index CONTIGUOUS | INTEGER_1 (64) | Pixel Index for 64 pixel arrays | 1 | Dimension scale for 64-pixel arrays. |
| hdot_avg CHUNKED | FLOAT (:) | LRS_xWIN Average Horizontal Velocity | pixels/second LRS_xWIN | This 32-bit value contains the average horizontal velocity for the target in pixels per frame, 1:23:8 fixed point format. |
| hloc CHUNKED | UINT_2_LE (:) | LRS_TWIN Horizontal location of window | pixels LRS_TWIN | Horizontal location of window. The 16-bit values for the coordinates of the minimum column contained within the window. The TAMS window uses 8 x 8 pixels, so the coordinates of the center will be 3.5 pixels greater in each axis. |
| ldc_t CHUNKED | FLOAT (:) | LRS_HK Laser Detector Card Temperature | Degrees LRS_HK | Temperature of Laser Detector Card - 0x0000 = 0.000 V (nominal short); 0xFFFF = +4.000 V (nominal open) [see thermistor scaling section later for temperature scaling] |
| localdark CHUNKED | UINT_2_LE (:) | LRS_xWIN Local Dark | counts LRS_xWIN | Local Dark - This 16-bit value is the local dark correction applied when correcting the window reading for stray light and/or residual dark frame bias. |
| max_mag CHUNKED | UINT_2_LE (:) | LRS_xWIN Maximum Magnitude | counts LRS_xWIN | This 16-bit value contains the maximum magnitude value for the target. |
| min_mag CHUNKED | UINT_2_LE (:) | LRS_xWIN Minimum Magnitude | counts LRS_xWIN | This 16-bit value contains the minimum magnitude value for the target. |
| quality_f CHUNKED | INTEGER_1 (:) | LRS_LCENT Centroid quality | 1 LRS_LCENT | This 16-bit value contains a single bit for the quality of this image only. Flag Values: ['0', '1'] Flag Meanings: ['valid', 'questionable'] |
| rawdata CHUNKED | UINT_2_LE (: x 64) | LRS_TWIN Raw pixel data for window | counts LRS_TWIN | Raw pixel data for window- The array contains the 64 pixels of the window contain the ADC readings for the pixels without onboard corrections. The values are transmitted in raster scan order, starting with the minimum row and column values (that is, the first transmitted 16-bit word will be from [HLOC, VLOC], then [HLOC+1, VLOC], , then [HLOC+7, VLOC], then [HLOC, VLOC+1], , and ending with [HLOC+7, VLOC+7]). |
| status_f CHUNKED | UINT_2_LE (:) | LRS_xWIN Target status | 1 LRS_xWIN | Target status-This 16-bit value contains a code indicating the target status applicable to the window reported in this packet. The valid codes are defined as follows (other codes are invalid): 65531 Dimmest Spot (not currently used), 65532 Invalid Rate, 65533 Collided with Another Window, 65534 Violated Minimum Area Limit, 65535 Violated Image Bound, 0 Empty, 1 Acquire1, 2 Acquire2, 3 Tracking Flag Values: ['0', '1', '2', '3', '65532', '65534', '65535'] Flag Meanings: ['empty', 'acq1', 'acq2', 'track', 'not_allowed', 'collided', 'violated'] |
| tickatime CHUNKED | UINT_4_LE (:) | LRS_xWIN Oscillator Tick Value | counts LRS_xWIN | Oscillator tick value at last time pulse. This 32-bit value is the reading from the internal 27 MHz oscillator at the last 1 PPS time tick. |

| | | | | |
|----------------------|------------------|--|---------------------------|--|
| tickfirst CHUNKED | UINT_4_LE (:) | LRS_xWIN Oscillator ticks when first pixel is read | counts LRS_xWIN | Oscillator ticks when first pixel is read. The 32-bit value reading from the internal 27 MHz oscillator when the first pixel of the window was read. They can be used to confirm the calculation of the center of integration offsets. |
| ticklast CHUNKED | UINT_4_LE (:) | LRS_xWIN Oscillator ticks when last pixel is read | counts LRS_xWIN | Oscillator ticks when last pixel is read. The 32-bit value reading from the internal 27 MHz oscillator when the last pixel of the window was read. They can be used to confirm the calculation of the center of integration offsets. |
| use_f CHUNKED | INTEGER_1 (:) | LRS_xWIN Window Use Flag | 1 LRS_xWIN | Window Use - This 16-bit value reports the way that the window is currently being used by the search and tracking algorithms. The valid codes are defined as follows (other codes are invalid): 0 = Inactive, 1= Image Generation, 2 = Searching, 3 = Tracking Flag Values: ['0', '1', '2', '3'] Flag Meanings: ['inactive', 'image_gen', 'search', 'track'] |
| vdot_avg CHUNKED | FLOAT (:) | LRS_LWIN Average Vertical Velocity | pixels/second LRS_LWIN | This 32-bit value contains the average vertical velocity for the target in pixels per frame, 1:23:8 fixed point format. |
| vloc CHUNKED | UINT_2_LE (:) | LRS_TWIN Vertical location of window | pixels LRS_TWIN | Vertical location of window. The 16-bit values for the coordinates of the minimum row contained within the window. The TAMS window uses 8 x 8 pixels, so the coordinates of the center will be 3.5 pixels greater in each axis. |
| windex CHUNKED | UINT_2_LE (:) | LRS_xWIN Window Index | counts LRSxTWIN | Window Index- The 16-bit value contains the window index reported in this packet. |

Group: /orbit_info

| | | | | |
|-------------------------|--------------------------|---|--|---|
| Description | (Attribute) | Contains orbit information. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source PCE Altimetric Data Packets. (nominally fifty per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| cycle_number CHUNKED | INTEGER_1 (:) | Cycle Number | 1 Operations | A count of the number of exact repeats of this reference orbit. |
| delta_time CHUNKED | DOUBLE (:) | Granule Start Time time | seconds since 2018-01-01 Operations | Number of GPS seconds since the ATLAS SDP epoch at the start of the granule. At the time of ATL02 creation, the equator crossing time is not precisely known.. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| orbit_number CHUNKED | UINT_2_LE (:) | Orbit Number | 1 Operations | Unique identifying number for each planned ICESat-2 orbit. |
| rgt CHUNKED | INTEGER_2 (:) | Reference Ground track | 1 Operations | The reference ground track (RGT) is the track on the earth at which a specified unit vector within the observatory is pointed. Under nominal operating conditions, there will be no data collected along the RGT, as the RGT is spanned by GT3 and GT4. During slews or off-pointing, it is possible that ground tracks may intersect the RGT. The ICESat-2 mission has 1387 RGTs. |

Group: /quality_assessment

| | | | | |
|-----------------------------------|--------------------------|---|-------------------|---|
| Description | (Attribute) | Contains quality assessment data. This may include QA counters, QA along-track data and/or QA summary data. | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| ds_statistics CONTIGUOUS | INTEGER_1 (5) | Dimension scale for QA statistics | 1 Derived (QA) | QA statistics array index Flag Values: ['1', '2', '3', '4', '5'] Flag Meanings: ['number_of_points', 'minimum', 'maximum', 'average', 'standard_deviation'] |
| qa_granule_fail_reason COMPACT | INTEGER (1) | Granule Failure Reason | 1 Operations | Flag indicating granule failure reason. 0=no failure; 1=processing error; 2=Insufficient output data was generated; 3=TBD Failure; 4=TBD_Failure; 5=other failure. Flag Values: ['0', '1', '2', '3', '4', '5'] Flag Meanings: ['no_failure', 'PROCESS_ERROR', 'INSUFFICIENT_OUTPUT', 'failure_3', 'failure_4', 'OTHER_FAILURE'] |
| qa_granule_pass_fail COMPACT | INTEGER (1) | Granule Pass Flag | 1 Operations | Flag indicating granule quality. 0=granule passes automatic QA. 1=granule fails automatic QA. Flag Values: ['0', '1'] Flag Meanings: ['PASS', 'FAIL'] |

Group: /quality_assessment/along_track

| | | | | |
|-------------------|--------------------------|------------------------------|-----------------|-------------|
| Description | (Attribute) | Along-track statistics | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| | | | | |

| | | | | |
|-----------------------------|---------------|-----------------------------|--|---|
| delta_time_end CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of seconds since the ATLAS SDP epoch at the end of the QA interval. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| delta_time_start CHUNKED | DOUBLE (:) | Elapsed UTC seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of seconds since the ATLAS SDP epoch at the start of the QA interval. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |

Group: /quality_assessment/along_track/pcex

| Description | (Attribute) | Along-track statistics | | |
|--------------------------------|--------------------------|-------------------------------|------------------------|---|
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| qa_at_n_dupe CHUNKED | INTEGER (:) | Number of duplicates | counts Derived (QA) | The number of duplicate Rx events detected in the along-track interval. |
| qa_at_n_rx_s CHUNKED | INTEGER (:) | Number of Strong Rx Events | counts Derived (QA) | The number of Strong Rx events in the along-track interval. |
| qa_at_n_rx_w CHUNKED | INTEGER (:) | Number of Weak Rx Events | counts Derived (QA) | The number of Weak Rx events in the along-track interval. |
| qa_at_n_tep CHUNKED | INTEGER (:) | Number of TEPs | counts Derived (QA) | The number of TEP events detected in the along-track interval. |
| qa_at_n_tx CHUNKED | INTEGER (:) | Number of Tx Pulses | counts Derived (QA) | The number of Tx Pulses in the along-track interval. |
| qa_at_tx_ll_stat CHUNKED | DOUBLE (: x 5) | QA Tx LL Stat | counts Derived (QA) | Along-track statistic of Transmit Leading Lower time of flight. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_at_tx_other_stat CHUNKED | DOUBLE (: x 5) | QA Tx Other Stat | counts Derived (QA) | Along-track statistic of the Other Transmit time of flight measurement. For PCE1, this is Transmit Leading Upper edge (LU) time; for PCE2 this is Transmit Trailing Upper edge (TU) time; and for PCE3 this is Transmit Trailing Lower edge (TL) time. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |

Group: /quality_assessment/record_counts

| Description | (Attribute) | Packet count statistics | | |
|------------------------------|--------------------------|--------------------------------------|--|---|
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time_end COMPACT | DOUBLE (1) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of seconds since the ATLAS SDP epoch at the end of the interval. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| delta_time_start COMPACT | DOUBLE (1) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of seconds since the ATLAS SDP epoch at the start of the QA interval. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| qa_n_a_hkt_a COMPACT | INTEGER (1) | Number of A_HKT_A inputs. | counts Derived (QA) | The number of A_HKT_A inputs processed. |
| qa_n_a_hkt_b COMPACT | INTEGER (1) | Number of A_HKT_B inputs. | counts Derived (QA) | The number of A_HKT_B inputs processed. |
| qa_n_a_hkt_c COMPACT | INTEGER (1) | Number of A_HKT_C inputs. | counts Derived (QA) | The number of A_HKT_C inputs processed. |
| qa_n_a_hkt_d COMPACT | INTEGER (1) | Number of A_HKT_D inputs. | counts Derived (QA) | The number of A_HKT_D inputs processed. |
| qa_n_a_hkt_e COMPACT | INTEGER (1) | Number of A_HKT_E inputs. | counts Derived (QA) | The number of A_HKT_E inputs processed. |
| qa_n_a_hkt_status COMPACT | INTEGER (1) | Number of A_HKT_STATUS inputs. | counts Derived (QA) | The number of A_HKT_STATUS inputs processed. |
| qa_n_a_mce_pos COMPACT | INTEGER (1) | Number of A_MCE_POS inputs. | counts Derived (QA) | The number of A_MCE_POS inputs processed. |
| qa_n_a_sc_pon COMPACT | INTEGER (1) | Number of A_SC_PON inputs. | counts Derived (QA) | The number of A_SC_PON inputs processed. |

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|------------------------------------|----------------|--|------------------------|--|
| qa_n_a_sc_pos COMPACT | INTEGER (1) | Number of A_SC_POS inputs. | counts Derived (QA) | The number of A_SC_POS inputs processed. |
| qa_n_a_sc_tat COMPACT | INTEGER (1) | Number of A_SC_TAT inputs. | counts Derived (QA) | The number of A_SC_TAT inputs processed. |
| qa_n_a_sla_hk COMPACT | INTEGER (1) | Number of A_SLA_HK inputs. | counts Derived (QA) | The number of A_SLA_HK inputs processed. |
| qa_n_lrs_hk COMPACT | INTEGER (1) | Number of LRS HK inputs. | counts Derived (QA) | The number of LRS HK inputs processed. |
| qa_n_lrs_laser_cent COMPACT | INTEGER (1) | Number of LRS Laser Centroid inputs. | counts Derived (QA) | The number of LRS Laser Centroid inputs processed. |
| qa_n_lrs_laser_image COMPACT | INTEGER (1) | Number of LRS Laser Image inputs. | counts Derived (QA) | The number of LRS Laser Image inputs processed. |
| qa_n_lrs_laser_window COMPACT | INTEGER (1) | Number of LRS Laser Window inputs. | counts Derived (QA) | The number of LRS Laser Window inputs processed. |
| qa_n_lrs_stellar_cent COMPACT | INTEGER (1) | Number of LRS Stellar Centroid inputs. | counts Derived (QA) | The number of LRS Stellar Centroid inputs processed. |
| qa_n_lrs_stellar_image COMPACT | INTEGER (1) | Number of LRS Stellar Image inputs. | counts Derived (QA) | The number of LRS Stellar Image inputs processed. |
| qa_n_lrs_stellar_window COMPACT | INTEGER (1) | Number of LRS Stellar Window inputs. | counts Derived (QA) | The number of LRS Stellar Window inputs processed. |
| qa_n_lrs_tams_window COMPACT | INTEGER (1) | Number of LRS TAMS Window inputs. | counts Derived (QA) | The number of LRS TAMS Window inputs processed. |
| qa_n_sc1 COMPACT | INTEGER (1) | Number of SC1 inputs. | counts Derived (QA) | The number of SC1 inputs processed. |
| qa_n_sc2 COMPACT | INTEGER (1) | Number of SC2 inputs. | counts Derived (QA) | The number of SC2 inputs processed. |
| qa_n_sc3 COMPACT | INTEGER (1) | Number of SC3 inputs. | counts Derived (QA) | The number of SC3 inputs processed. |
| qa_n_sc4 COMPACT | INTEGER (1) | Number of SC4 inputs. | counts Derived (QA) | The number of SC4 inputs processed. |
| qa_n_sim_hk COMPACT | INTEGER (1) | Number of SIM_HK inputs. | counts Derived (QA) | The number of SIM_HK inputs processed. |

Group: /quality_assessment/record_counts/pcex

| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
|---------------------------------------|--------------------------|---|------------------------|---|
| qa_n_a_dfc_hk COMPACT | INTEGER (1) | Number of DFC HK Inputs | counts Derived (QA) | The number of A_DFC_HK inputs processed. |
| qa_n_alt_mframe COMPACT | INTEGER (1) | Number of major frame inputs. | counts Derived (QA) | The number of major frame inputs processed. |
| qa_n_atm_hist_s COMPACT | INTEGER (1) | Number of ATM Strong inputs. | counts Derived (QA) | The number of ATM strong inputs processed. |
| qa_n_atm_hist_w COMPACT | INTEGER (1) | Number of ATM weak inputs. | counts Derived (QA) | The number of ATM weak inputs processed. |
| qa_n_pmf_algorithm_science COMPACT | INTEGER (1) | Number of PMF Algorithm Science inputs. | counts Derived (QA) | The number of PMF Algorithm Science inputs processed. |
| qa_n_pmf_timekeeping COMPACT | INTEGER (1) | Number of PMF Timekeeping inputs. | counts Derived (QA) | The number of PMF Timekeeping inputs processed. |

Group: /quality_assessment/summary

| Description | (Attribute) | Summary statistics | | |
|---------------------------|--------------------------|------------------------------|--|--|
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time_end COMPACT | DOUBLE (1) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of seconds since the ATLAS SDP epoch at the end of the QA interval. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within |

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|-------------------------------------|--------------------|-------------------------------|--|---|
| | | | | atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| delta_time_start COMPACT | DOUBLE (1) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| qa_amet_r1 COMPACT | INTEGER (1) | AMET Increment OOB | counts Derived (QA) | Number of instances where the difference between external AMET counter and the GPS 1PPS exceeds the limit of 1.0. |
| qa_amet_r2 COMPACT | INTEGER (1) | AMET Increment OOB | counts Derived (QA) | Number of instances where the difference between internal AMET at 1PPS and GPS 1PPS exceed the limit of 100.e6. |
| qa_bias_offset_x COMPACT | INTEGER (1) | Num Bias Offset X OOB | counts Derived (QA) | Number of instances where the bias offset X value is outside the limit of -70 to 70 microradians. |
| qa_bias_offset_y COMPACT | INTEGER (1) | Num Bias Offset Y OOB | counts Derived (QA) | Number of instances where the bias offset Y value is outside the limit of -70 to 70 microradians. |
| qa_cal47_temp COMPACT | INTEGER (1) | CAL47 temperature OOB | counts Derived (QA) | Number of instances where the CAL-47 temperature is outside the limit of -20 to 50 degC. |
| qa_fw_flag COMPACT | INTEGER (1) | Freewheel Indicated | counts Derived (QA) | Number of instances where the freewheel flag is non-zero. |
| qa_hvpc_mod_1 COMPACT | INTEGER (1) | Num HVPC Bias Mod 1 OOB | counts Derived (QA) | Number of instances where the HVPC Bias Mod1 value is outside the limit of -2000 to 0 counts. |
| qa_hvpc_mod_2 COMPACT | INTEGER (1) | Num HVPC Bias Mod 2 OOB | counts Derived (QA) | Number of instances where the HVPC Bias Mod2 value is outside the limit of -2000 to 0 counts. |
| qa_hvpc_mod_3 COMPACT | INTEGER (1) | Num HVPC Bias Mod 3 OOB | counts Derived (QA) | Number of instances where the HVPC Bias Mod3 value is outside the limit of -2000 to 0 counts. |
| qa_hvpc_mod_4 COMPACT | INTEGER (1) | Num HVPC Bias Mod 4 OOB | counts Derived (QA) | Number of instances where the HVPC Bias Mod4 value is outside the limit of -2000 to 0 counts. |
| qa_hvpc_mod_5 COMPACT | INTEGER (1) | Num HVPC Bias Mod 5 OOB | counts Derived (QA) | Number of instances where the HVPC Bias Mod5 value is outside the limit of -2000 to 0 counts. |
| qa_hvpc_mod_6 COMPACT | INTEGER (1) | Num HVPC Bias Mod 6 OOB | counts Derived (QA) | Number of instances where the HVPC Bias Mod6 value is outside the limit of -2000 to 0 counts. |
| qa_int_e_tx COMPACT | INTEGER (1) | Num Internal Energy OOB | counts Derived (QA) | Number of instances where the computed total internal laser energy is outside the limit of 130 to 2700 microjoules. |
| qa_internal_energy COMPACT | INTEGER (1) | Num Internal Energy OOB | counts Derived (QA) | Number of instances where input internal laser energy values exceed the limit of 0 to 200 counts. |
| qa_internal_temp COMPACT | INTEGER (1) | Num Internal Temp OOB | counts Derived (QA) | Number of instances where input laser temperature values exceed the limit of 20 to 40 degC. |
| qa_lrs_e_tx COMPACT | INTEGER (1) | Num LRS Energy OOB | counts Derived (QA) | Number of instances where the computed total LRS laser energy is outside the limit of 130 to 2700 microjoules. |
| qa_lrs_inv_mag COMPACT | INTEGER (1 x 6) | Num LRS Mag Invalid | counts Derived (QA) | Number of instances where an LRS laser magnitude is outside the limit of 0-500. |
| qa_lrs_inv_spot COMPACT | INTEGER (1) | Num LRS Spots Missing | counts Derived (QA) | Number of instances where not all 6 laser spots are valid when computing LRS laser energy. |
| qa_lrs_inv_sum COMPACT | INTEGER (1) | Num LRS Sums Invalid | counts Derived (QA) | Number of instances where the sum of the 6 LRS laser spots is outside the limit of 0 to 2000. |
| qa_lrs_temp COMPACT | INTEGER (1) | Num LRS Temp OOB | counts Derived (QA) | Number of instances where the LRS temperature is outside the limit of -20 to 50 degC. |
| qa_s_tod_a_sla_hk COMPACT | DOUBLE (1 x 5) | QA for a_sla_hk TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive A_SLA_HK time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_gpsr COMPACT | DOUBLE (1 x 5) | QA for gpsr TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /gpsr time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_hk_laser_energy COMPACT | DOUBLE (1 x 5) | QA for hk_laser_energy TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/housekeeping/laser_energy time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_hk_meb COMPACT | DOUBLE (1 x 5) | QA for hk_pdu TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/housekeeping/meb time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_hk_pdu COMPACT | DOUBLE (1 x 5) | QA for hk_pdu TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/housekeeping/pdu time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |

| | | | | |
|--|--------------------------|--------------------------------------|--------------------------------|---|
| qa_s_tod_hk_pointing COMPACT | DOUBLE (1 x 5) | QA for hk_pointing TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/housekeeping/pointing time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_hk_pos_vel COMPACT | DOUBLE (1 x 5) | QA for hk_pos_vel TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/housekeeping/position_velocity time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_hk_tat COMPACT | DOUBLE (1 x 5) | QA for hk_tat TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/housekeeping/time_at_the_tone time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_hk_thermal COMPACT | DOUBLE (1 x 5) | QA for hk_therm TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/housekeeping/hk_thermal time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_mce_position COMPACT | DOUBLE (1 x 5) | QA for mce_position TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/housekeeping/mce_position time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_sc_acs COMPACT | DOUBLE (1 x 5) | QA for acs TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /sc/attitude_control_system time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_sc_ephemeris COMPACT | DOUBLE (1 x 5) | QA for sc_ephemeris TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /sc/ephemeris time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_sc_hk COMPACT | DOUBLE (1 x 5) | QA for sc_hk TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /sc/hk time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_sc_imu COMPACT | DOUBLE (1 x 5) | QA for sc_imu TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /sc/inertial_measurement_unit time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_sc_st COMPACT | DOUBLE (1 x 5) | QA for sc_star_tracker TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /sc/star_tracker time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_sc_stoh1 COMPACT | DOUBLE (1 x 5) | QA for sc_star_tracker_oh1 TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /sc/star_tracker/optical_head1 time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_sc_stoh2 COMPACT | DOUBLE (1 x 5) | QA for sc_star_tracker_oh2 TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /sc/star_tracker/optical_head2 time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_spd_e_tx COMPACT | INTEGER (1) | Num SPD Energy OOB | counts Derived (QA) | Number of instances where the computed total SPD laser energy is outside the limit of 130 to 2700 microjoules. |
| qa_spd_energy COMPACT | INTEGER (1) | Num SPD Energy OOB | counts Derived (QA) | Number of instances where input SPD laser energy values exceed the limit of -30000 to 0 counts. |
| qa_spd_temp COMPACT | INTEGER (1) | Num SPD Temp OOB | counts Derived (QA) | Number of instances where SPD temperature values exceed the limit of -20 to 50 degC. |
| qa_time_corr COMPACT | INTEGER (1) | Shot Time correlation OOB | counts Derived (QA) | Where the ratio of unaligned shots/aligned shots exceeds the limit of 0.9; 0=Doesn't Exceed Limit, 1=Exceeds Limit |
| Group: /quality_assessment/summary/pcex | | | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| qa_bg_sens_s COMPACT | INTEGER (1) | Num Strong Bg Sensitivity OOB | counts Derived (QA) | Number of instances where the computed strong background sensitivity value is outside the limit of 5e17 to 2e18. |
| qa_bg_sens_w COMPACT | INTEGER (1) | Num Weak Bg Sensitivity OOB | counts Derived (QA) | Number of instances where the computed weak background sensitivity value is outside the limit of 5e17 to 2e18. |
| qa_dupe_percent COMPACT | INTEGER (1 x 20) | Channel Dupe Percent OOB | counts Derived (QA) | Number of instances where the per-channel number of duplicates is greater than 10% of the total number of per-channel events. |
| qa_ph_tx_ll COMPACT | INTEGER (1) | Tx LL OOB | counts Derived (QA) | Where the maximum minus minimum Tx leading lower exceeds the limit of 39 ns. |
| qa_ret_sens_s COMPACT | INTEGER (1) | Num Strong Return Sensitivity OOB | counts Derived (QA) | Number of instances where the computed strong return sensitivity value is outside the limit of 0 to 2e18. |
| qa_ret_sens_w COMPACT | INTEGER (1) | Num Weak Return Sensitivity OOB | counts Derived (QA) | Number of instances where the computed weak return sensitivity value is outside the limit of 0 to 2e18. |
| qa_rx_channel_id COMPACT | INTEGER (1) | Rx Channel ID OOB | counts Derived (QA) | Number of instances where the Rx channel ID contains an unexpected value. |
| qa_rx_coarse_count COMPACT | INTEGER (1) | Rx Coarse Count OOB | counts Derived (QA) | Number of instances where the Rx coarse count value exceeds the limit of 10000 counts. |
| qa_rx_fine_count COMPACT | INTEGER (1) | Rx Fine Count OOB | counts Derived (QA) | Number of instances where the Rx fine count value exceeds the limit of 75 counts. |

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| qa_s_alt_cal_fall COMPACT | DOUBLE (1 x 5) | QA alt_cal_fall | counts Derived (QA) | Summary statistic of the full-rate (before interpolation) alt_cal_fall computation. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_alt_cal_rise COMPACT | DOUBLE (1 x 5) | QA alt_cal_rise | counts Derived (QA) | Summary statistic of the full-rate (before interpolation) alt_cal_rise computation. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_n_1pps_skip COMPACT | INTEGER (1) | QA 1PPS missed | counts Derived via L1B ATBD | Number of times 1 pps was not consecutive. |
| qa_s_n_dupe COMPACT | INTEGER (1) | Number of duplicates | counts Derived (QA) | The number of duplicate Rx events detected in the granule. |
| qa_s_n_mf_skip COMPACT | INTEGER (1) | QA 1P MF missed | counts Derived via L1B ATBD | The number of times major frame counter was not consecutive. |
| qa_s_n_missed_thres COMPACT | INTEGER_8 (1) | Number of Missed Tx Threshold Crossings | counts Derived (QA) | The number of Tx pulses in which a missed threshold crossing was detected. The condition occurs if the Tx leading and trailing fine raw counts are the exact same value. |
| qa_s_n_rx_s COMPACT | INTEGER_8 (1) | Number of Strong Rx Events | counts Derived (QA) | The number of Strong Rx events in the granule. |
| qa_s_n_rx_w COMPACT | INTEGER_8 (1) | Number of Weak Rx Events | counts Derived (QA) | The number of Weak Rx events in the granule. |
| qa_s_n_swapped_txfine COMPACT | INTEGER_8 (1) | Number of Tx Fine Swaps | counts Derived (QA) | The number of Tx pulses for which a PCE anomaly forced the Tx fine count values to be swapped. |
| qa_s_n_tep COMPACT | INTEGER (1) | Number of TEPs | counts Derived (QA) | The number of TEP events detected in the granule. |
| qa_s_n_tx COMPACT | INTEGER_8 (1) | Number of Tx Pulses | counts Derived (QA) | The number of Tx Pulses in the granule. |
| qa_s_n_tx_oob COMPACT | INTEGER (1) | QA number of instances TX out of bounds | counts Derived via L1B ATBD | The number of times the Tx count is out of bounds (oob); i.e.: 199 to 201 TX pulses were not reported in a major frame. |
| qa_s_tod_alt COMPACT | DOUBLE (1 x 5) | QA for pcex_alt TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/pcex/altimetry time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_atm_hist_s COMPACT | DOUBLE (1 x 5) | QA for atm_his_st TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/pcex/atmosphere_strong time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_atm_hist_w COMPACT | DOUBLE (1 x 5) | QA for atm_hist_w TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/pcex/atmosphere_weak time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_background COMPACT | DOUBLE (1 x 5) | QA for pcex_background TOD | counts Derived via L1B ATBD | Summary statistics on the differences between successive /atlas/pcex/background time of day values. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tod_method COMPACT | DOUBLE (1 x 5) | QA from TOD Methods | counts Derived via L1B ATBD | Summary statistics on the differences between Time_T0_Method1 and Time_T0_Method2. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tx_ll_stat COMPACT | DOUBLE (1 x 5) | QA Tx LL Stat | counts Derived (QA) | Summary statistic of Transmit Leading Lower time of flight. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_s_tx_other_stat COMPACT | DOUBLE (1 x 5) | QA Tx Other Stat | counts Derived (QA) | Summary statistic of the Other Transmit time of flight measurement. For PCE1, this is Transmit Leading Upper edge (LU) time; for PCE2 this is Transmit Trailing Upper edge (TU) time; and for PCE3 this is Transmit Trailing Lower edge (TL) time. Values are in the order number_of_points, minimum, maximum, average, standard_deviation. |
| qa_tep_tof COMPACT | INTEGER (1) | Num TEP OOB | counts Derived (QA) | Number of instances where TEP TOF values exceed the limit of 0 to 110ns. |
| qa_tx_coarse_count COMPACT | INTEGER (1) | Tx Coarse Count OOB | counts Derived (QA) | Number of instances where the Tx coarse count value exceeds the limit of 10000 counts. |
| qa_tx_leading_fine COMPACT | INTEGER (1) | Tx Leading Fine Count OOB | counts Derived (QA) | Number of instances where the Tx leading fine count value exceeds the limit of 75 counts. |
| qa_tx_trailing_fine COMPACT | INTEGER (1) | Tx Trailing Fine Count OOB | counts Derived (QA) | Number of instances where the Tx trailing fine count value exceeds the limit of 75 counts. |
| Group: /sc | | | | |
| Description | (Attribute) | Group contains the Spacecraft (SC) Ancillary Science packet #1 decommutated data | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| acs_time_sec CHUNKED | UINT_4_LE (:) | ACS time (sec) | seconds ATL01/sc | SC time at the initiation of the ACS task (seconds since SC epoch: 6-Jan-1980 00:00:00) (Same time provided within the Attitude/Rate message to ATLAS in RT at 1Hz) |

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| acs_time_subsec CHUNKED | UINT_4_LE (:) | ACS time (subsec) | 100 nanoseconds ATL01/sc | Subsecond portion of the SC time at the initiation of the ACS task (seconds since SC epoch: 6-Jan-1980 00:00:00) (Same time provided within the Attitude/Rate message to ATLAS in RT at 1Hz) |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Number of GPS seconds since the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS Standard Data Product (SDP) epoch. By adding atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch time can be computed. |
| sc_time_1pps_sec CHUNKED | UINT_4_LE (:) | SC time at 1 pps (sec) | seconds ATL01/sc | SC time at the reception of the last 1PPS signal from the GPSR (seconds since SC epoch: 6-Jan-1980 00:00:00) |
| sc_time_1pps_subsec CHUNKED | UINT_4_LE (:) | SC time at 1 pps (subsec) | 100 nanoseconds ATL01/sc | Subsecond portion of the SC time at the reception of the last 1PPS signal from the GPSR (seconds since SC epoch: 6-Jan-1980 00:00:00) |
| Group: /sc/attitude_control_system | | | | |
| Description | (Attribute) | Contains parameters related to spacecraft ACS (attitude control system) software. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| acs_mode CHUNKED | UINT_1_LE (:) | ACS Software Mode | counts ATL01/sc1/attitude_control_system | ACS Active ACS Software Mode 0 = Idle 1 = Rate Capture 2 = Sun Acquisition 3 = (Reserved - N/A for ICESat-2) 4 = Slew 5 = Inertial Sun Point 6 = Earth Pointing 7 = ACS Calibration 8 = Inertial Pointing 9 = Reference Ground Track (RGT) 10 = Roll Off-Point (ROP) 11 = Instrument Calibration (ICAL) 12 = DV Wheel Standby 13 = DV Thruster Standby 14 = DV Burn Flag Values: ['0', '1', '2', '3', '4', '5', '6', '7', '8', '9', '10', '11', '12', '13', '14'] Flag Meanings: ['idle', 'rate_capture', 'sun_acquisition', 'reserved', 'slew', 'inertial_sun_point', 'earth_pointing', 'acs_calibration', 'inertial_pointing', 'reference_ground_track', 'roll_off_point', 'instrument_calibration', 'dv_wheel_standby', 'dv_thruster_standby', 'dv_burn'] |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | The time tag of the data computed from raw_acs_time_sec and subseconds in the L1A Attitude_control_group, relative to the ATLAS SDP epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| sc_body_rate_x CHUNKED | DOUBLE (:) | SC Body Rate (X) | radians/second ATL01/sc1/attitude_control_system and L1B ATBD conversion | ACS Fine Rate Estimate - SC Body X axis. (Same data provided to ATLAS in RT at 1Hz) |
| sc_body_rate_y CHUNKED | DOUBLE (:) | SC Body Rate (Y) | radians/second ATL01/sc1/attitude_control_system and L1B ATBD conversion | ACS Fine Rate Estimate - SC Body Y axis. (Same data provided to ATLAS in RT at 1Hz) |
| sc_body_rate_z CHUNKED | DOUBLE (:) | SC Body Rate (Z) | radians/second ATL01/sc1/attitude_control_system and L1B ATBD conversion | ACS Fine Rate Estimate - SC Body Z axis. (Same data provided to ATLAS in RT at 1Hz) |
| sc_to_lrs_quat_1 CHUNKED | DOUBLE (:) | SC Inertial to LRS Frame Quaternions 1 | counts ATL01/sc1/attitude_control_system and L1B ATBD conversion | ACS Spacecraft Inertial frame to Laser Reference System (LRS) reference frame quaternion1. (Same data provided to ATLAS in RT at 1Hz). |
| sc_to_lrs_quat_2 CHUNKED | DOUBLE (:) | SC Inertial to LRS Frame Quaternions 2 | counts ATL01/sc1/attitude_control_system and L1B ATBD conversion | ACS Spacecraft Inertial frame to Laser Reference System (LRS) reference frame quaternion 2. (Same data provided to ATLAS in RT at 1Hz). |
| sc_to_lrs_quat_3 CHUNKED | DOUBLE (:) | SC Inertial to LRS Frame Quaternions 3 | counts ATL01/sc1/attitude_control_system and L1B ATBD conversion | ACS Spacecraft Inertial frame to Laser Reference System (LRS) reference frame quaternion 3. (Same data provided to ATLAS in RT at 1Hz). |
| sc_to_lrs_quat_4 CHUNKED | DOUBLE (:) | SC Inertial to LRS Frame Quaternions 4 | counts ATL01/sc1/attitude_control_system and L1B ATBD conversion | ACS Spacecraft Inertial frame to Laser Reference System (LRS) reference frame quaternion4. (Same data provided to ATLAS in RT at 1Hz). |
| Group: /sc/ephemeris | | | | |
| Description | (Attribute) | Contains parameters related to spacecraft Ephemeris Propagator. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | The time tag of the data by using raw_prop_time_sec and subsecs in the L1A ephemeris group, relative to the ATLAS SDP GSP epoch. The ATLAS Standard Data Products (SDP) GPS epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |

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| eci_position_res_x CHUNKED | FLOAT (:) | SC ECI Position residual X | meters ATL01/sc1/ephemeris | ACS Orbit Determination Filter position of X frame residual. |
| eci_position_res_y CHUNKED | FLOAT (:) | SC ECI Position residualY | meters ATL01/sc1/ephemeris | ACS Orbit Determination Filter position of Y frame residual. |
| eci_position_res_z CHUNKED | FLOAT (:) | SC ECI Position residual Z | meters ATL01/sc1/ephemeris | ACS Orbit Determination Filter position of Z frame residual. |
| eci_position_x CHUNKED | DOUBLE (:) | SC ECI Position X | meters ATL01/sc1/ephemeris converted | ACS SC X position in the ECI coordinate frame. (Same data that is provided to ATLAS in RT) |
| eci_position_y CHUNKED | DOUBLE (:) | SC ECI Position Y | meters ATL01/sc1/ephemeris converted | ACS SC Y position in the ECI coordinate frame. (Same data that is provided to ATLAS in RT) |
| eci_position_z CHUNKED | DOUBLE (:) | SC ECI Position Z | meters ATL01/sc1/ephemeris converted | ACS SC Z position in the ECI coordinate frame. (Same data that is provided to ATLAS in RT) |
| eci_velocity_res_x CHUNKED | FLOAT (:) | SC ECI velocity residual X | meters/second ATL01/sc1/ephemeris | ACS Orbit Determination Filter velocity of X frame residual. |
| eci_velocity_res_y CHUNKED | FLOAT (:) | SC ECI velocity residual Y | meters/second ATL01/sc1/ephemeris | ACS Orbit Determination Filter velocity of Y frame residual. |
| eci_velocity_res_z CHUNKED | FLOAT (:) | SC ECI velocity residual Z | meters/second ATL01/sc1/ephemeris | ACS Orbit Determination Filter velocity of Z frame residual. |
| eci_velocity_x CHUNKED | DOUBLE (:) | SC ECI Velocity X | meters/second ATL01/sc1/ephemeris converted | ACS SC X velocity in the ECI coordinate frame. (Same data that is provided to ATLAS in RT) |
| eci_velocity_y CHUNKED | DOUBLE (:) | SC ECI Velocity Y | meters/second ATL01/sc1/ephemeris converted | ACS SC Y velocity in the ECI coordinate frame. (Same data that is provided to ATLAS in RT) |
| eci_velocity_z CHUNKED | DOUBLE (:) | SC ECI Velocity Z | meters/second ATL01/sc1/ephemeris converted | ACS SC Z velocity in the ECI coordinate frame. (Same data that is provided to ATLAS in RT) |

Group: /sc/hk

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| Description | (Attribute) | Contains parameters related to spacecraft housekeeping data. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| at_det_p CHUNKED | FLOAT (: x 2) | ATLAS Currents - Detector Power (Sides A, B) | amps ATL01/sc1/hk converted | ATLAS Detector power feed current measured by the SC PDU (7.5A; Sides A, B) |
| at_det_sw CHUNKED | INTEGER_1 (: x 2) | ATLAS Switch Status - Detector (Sides A, B) | 1 ATL01/sc1/hk | ATLAS Detector power feed status measured by the SC PDU (Sides A, B) Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| at_heater_1_c CHUNKED | FLOAT (: x 2) | ATLAS Currents - Survival Heater 1 (Sides A, B) | amps ATL01/sc1/hk converted | ATLAS Survival Heater 1 power feed current measured by the SC PDU (10A; Sides A, B) |
| at_heater_1_sw CHUNKED | INTEGER_1 (: x 2) | ATLAS Switch Status - Survival Heater 1 (Sides A, B) | 1 ATL01/sc1/hk | ATLAS Survival Heater 1 power feed status measured by the SC PDU (Sides A, B) Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| at_heater_2_c CHUNKED | FLOAT (: x 2) | ATLAS Currents - Survival Heater 2 (Sides A, B) | amps ATL01/sc1/hk converted | ATLAS Survival Heater 2 power feed current measured by the SC PDU (10A; Sides A, B) |
| at_heater_2_sw CHUNKED | INTEGER_1 (: x 2) | ATLAS Switch Status - Survival Heater 2 (Sides A, B) | 1 ATL01/sc1/hk | ATLAS Survival Heater 2 power feed status measured by the SC PDU (Sides A, B) Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| at_heater_3_c CHUNKED | FLOAT (: x 2) | ATLAS Currents - Survival Heater 3 (Sides A, B) | amps ATL01/sc1/hk converted | ATLAS Survival Heater 3 power feed current measured by the SC PDU (10A; Sides A, B) |
| at_heater_3_sw CHUNKED | INTEGER_1 (: x 2) | ATLAS Switch Status - Survival Heater 3 (Sides A, B) | 1 ATL01/sc1/hk | ATLAS Survival Heater 3 power feed status measured by the SC PDU (Sides A, B) Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |

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| at_heater_4_c CHUNKED | FLOAT (: x 2) | ATLAS Currents - Survival Heater 4 (Sides A, B) | amps ATL01/sc1/hk converted | ATLAS Survival Heater 4 power feed current measured by the SC PDU (10A; Sides A, B) |
| at_heater_4_sw CHUNKED | INTEGER_1 (: x 2) | ATLAS Switch Status - Survival Heater 4 (Sides A, B) | 1 ATL01/sc1/hk | ATLAS Survival Heater 4 power feed status measured by the SC PDU (Sides A, B) Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| at_laser_a_c CHUNKED | FLOAT (:) | ATLAS Currents - Laser A | amps ATL01/sc1/hk converted | ATLAS Laser A power feed current measured by the SC PDU (20A) |
| at_laser_sw CHUNKED | INTEGER_1 (: x 2) | ATLAS Switch Status - Laser (Sides A, B) | 1 ATL01/sc1/hk | ATLAS Laser power feed status measured by the SC PDU (Sides A, B) Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| at_lhp_sdhttr_c CHUNKED | FLOAT (: x 2) | ATLAS Currents - LHP Shutdown HTR (Sides A, B) | amps ATL01/sc1/hk converted | ATLAS Loop Heat Pipe Shutdown power feed current measured by the SC PDU (7.5A; Sides A, B) |
| at_lhp_sdhttr_sw CHUNKED | INTEGER_1 (: x 2) | ATLAS Switch Status - LHP Shutdown HTR (Sides A, B) | 1 ATL01/sc1/hk | ATLAS LHP Shutdown Heater power feed status measured by the SC PDU (Sides A, B) Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| at_main_c CHUNKED | FLOAT (: x 2) | ATLAS Currents - ATLAS Main (Sides A, B) | amps ATL01/sc1/hk converted | ATLAS Main power feed current measured by the SC PDU (20A; Sides A, B) |
| at_main_sw CHUNKED | INTEGER_1 (: x 2) | ATLAS Switch Status - Main (Sides A, B) | 1 ATL01/sc1/hk | ATLAS Main power feed status measured by the SC PDU (Sides A, B) Flag Values: ['0', '1'] Flag Meanings: ['on', 'off'] |
| at_t CHUNKED | FLOAT (: x 15) | ATLAS Temperatures (1-15) | degreesC ATL01/sc1/hk converted | SC Monitored ATLAS Temperatures (1 to 15) |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | The derived time tag of the data, relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| ds_ab_index CONTIGUOUS | INTEGER_1 (2) | Dimension scale for Side A or B | 1 | Dimension scale for Side A or B Flag Values: ['1', '2'] Flag Meanings: ['side_a', 'side_b'] |
| ds_flexure_index CONTIGUOUS | INTEGER_1 (3) | Dimension scale for flexure thermistors | 1 | Dimension scale for flexure thermistor temperatures. |
| ds_temp_index CONTIGUOUS | INTEGER_1 (15) | Dimension scale for ATLAS Temperatures | 1 | Dimension scale for ATLAS temperatures. |
| sa_1_in_bk_t CHUNKED | FLOAT (:) | Solar Array Panel 1 (Inboard) Back-Side Temperature | degreesC ATL01/sc1/hk converted | SC Monitored Temperature of the Back-Side of Solar Panel 1 (Inboard Panel) |
| sa_1_in_cell_t CHUNKED | FLOAT (:) | Solar Array Panel 1 (Inboard) Cell-Side Temp | degreesC ATL01/sc1/hk converted | SC Monitored Temperature of the Cell-Side of Solar Panel 1 (Inboard Panel) |
| sa_4_ot_bk_t CHUNKED | FLOAT (:) | Solar Array Panel 4 (Outboard) Back- Side Temperature | degreesC ATL01/sc1/hk converted | SC Monitored Temperature of the Back-Side of Solar Panel 4 (Outboard Panel) |
| sa_4_ot_cell_t CHUNKED | FLOAT (:) | Solar Array Panel 4 (Outboard) Cell- Side Temperature | degreesC ATL01/sc1/hk converted | SC Monitored Temperature of the Cell-Side of Solar Panel 4 (Outboard Panel) |
| sc_at_flex_t CHUNKED | FLOAT (: x 3) | SC-to-ATLAS Flexure Temperature | degreesC ATL01/sc1/hk converted | SC Monitored Temperature of Mechanical I/F Flexure 1, 2 and 3 |
| sc_e_bus_v CHUNKED | FLOAT (: x 2) | SC Essential Bus Voltage (Sides A, B) | volts ATL01/sc1/hk converted | SC Essential Bus Voltage measured by the SC PDU. (Sides A, B) |

Group: /sc/inertial_measurement_unit

Description (Attribute) Contains parameters related to spacecraft IMU (Inertial Measurement Unit).

| data_rate | (Attribute) | Data within this main group are stored at the data rate of the source IMU within the Spacecraft Ancillary Science Data Packet. (nominally fifty per second.) | | |
|---|-----------------------|---|---|---|
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | IMU delta time tag at the end of the IDL frame over which the integrated gyro angle data was collected, relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| sync_event_ttag CHUNKED | DOUBLE (:) | IMU Sync Event Time Tag | seconds ATL01/sc1/inertial_measurement_unit/hi_rate converted | IMU Time remaining on the countdown timer which triggers the IDL interrupt (between the event strobe and the timetag of the next IDL data packet). IMU time at the reception of the last IMU time sync pulse. This word contains the time stamp that is recorded when the Event Strobe input to the SSIRU transitions to the active (low) state. |
| Group: /sc/inertial_measurement_unit/gyro_abcd | | | | |
| Description | (Attribute) | Contains parameters related to spacecraft IMU (Inertial Measurement Unit) gyros. | | |
| data_rate | (Attribute) | Data within this main group are stored at the data rate of the source IMU high_rate data within the Spacecraft Ancillary Science Data Packet. (nominally fifty per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| gyro_angle CHUNKED | FLOAT (:) | IMU Gyro Integrated Angle Counter (Gyros A, B, C, D) | arcseconds ATL01/sc1/inertial_measurement_unit/hi_rate converted | IMU integrated angle sensed by the SSIRU Gyro. The data word shall increment from 0 to full scale (0xFFFF) and roll over to zero for positive input rates about the Gyro input axis. The data word shall decrement from full scale to 0 and roll over to 0xFFFF for negative input rates about the Gyro input axis. |
| gyro_rate_f CHUNKED | INTEGER_1 (:) | IMU Gyro Rate Valid (Gyros A, B, C, D) | 1 ATL01/sc1/inertial_measurement_unit/hi_rate | IMU Gyro Integrated Angular Rate data validity status. 0=invalid, 1=valid. Flag Values: ['0', '1'] Flag Meanings: ['invalid', 'valid'] |
| gyro_sat_f CHUNKED | INTEGER_1 (:) | IMU Gyro Saturation Bit (Gyros A, B, C, D) | 1 ATL01/sc1/inertial_measurement_unit/hi_rate | IMU Gyro saturation mode: Force to Rebalance (FTR) Mode (The gyro operates in this mode during low inertial rates) or Whole Angle Saturation (WAS) Mode (The gyro operates in this mode during high inertial rates). Flag Values: ['0', '1'] Flag Meanings: ['ftr_mode', 'was_mode'] |
| gyro_scal_f CHUNKED | INTEGER_1 (:) | IMU Gyro Scaling Factor (Gyros A, B, C, D) | 1 ATL01/sc1/inertial_measurement_unit/hi_rate | IMU Gyro scale factor mode: low scaling factor mode with the corresponding Integrated Angle word being 0.05 arc-sec/LSB or high scaling factor with the corresponding Integrated Angle word being 1.6 arc-sec/LSB. Flag Values: ['0', '1'] Flag Meanings: ['low_scale_factor', 'high_scale_factor'] |
| Group: /sc/solar_array | | | | |
| Description | (Attribute) | Contains parameters related to solar array driver assembly. | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Spacecraft Ancillary Science Data Packets. (nominally one per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| azimuth_est CHUNKED | FLOAT (:) | SADA Azimuth Estimated Position | degrees ATL01/sc1/solar_array | Solar Array Drive Assembly (SADA) - Estimated Azimuth position used for ACS control |
| azimuth_meas_1 CHUNKED | FLOAT (:) | SADA Azimuth Measured Position (Pot 1) | degrees ATL01/sc1/solar_array | Solar Array Drive Assembly (SADA) - Estimated Azimuth angle based on Potentiometer 1 (as reported by ACS software). |
| azimuth_meas_2 CHUNKED | FLOAT (:) | SADA Azimuth Measured Position (Pot 2) | degrees ATL01/sc1/solar_array | Solar Array Drive Assembly (SADA) - Estimated Azimuth angle based on Potentiometer 2 (as reported by ACS software). |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | SC time at the initiation of the ACS task, relative to the ATLAS SDP GPS Epoch. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| elev_est CHUNKED | FLOAT (:) | SADA Elevation Estimated Position | degrees ATL01/sc1/solar_array | Solar Array Drive Assembly (SADA) - Estimated Elevation position used for ACS control |
| elev_meas_1 CHUNKED | FLOAT (:) | SADA Elevation Measured Position (Pot 1) | degrees ATL01/sc1/solar_array | Solar Array Drive Assembly (SADA) - Estimated Elevation angle based on Potentiometer 1 (as reported by ACS software). |
| elev_meas_2 CHUNKED | FLOAT (:) | SADA Elevation Measured Position (Pot 2) | degrees ATL01/sc1/solar_array | Solar Array Drive Assembly (SADA) - Estimated Elevation angle based on Potentiometer 2 (as reported by ACS software). |

| Group: /sc/star_tracker | | | | |
|------------------------------|-----------------------|--|--|--|
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Star Tracker data within the Spacecraft Ancillary Science Data Packets. (nominally ten per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| atm_etr_counter CHUNKED | UINT_2_BE (:) | ATM ETR Counter | counts ATL01/sc2/star_tracker | Star Tracker Electronics (STE) [ATM TM#1: Subaddress 13] - External Time Reference (ETR) delay ticks - Used to determine measurement time of reported ATM TLM with respect to SC-provided sync pulse; Additional delay of quaternion measurement time in ticks of 20 usec from ETR. |
| atm_frame_counter CHUNKED | UINT_2_BE (:) | ATM Frame Counter | counts ATL01/sc2/star_tracker | Star Tracker Electronics (STE) [ATM TM#1: Subaddress 13] - External Time Reference (ETR) counter - Used to determine measurement time of reported ATM TLM with respect to SC-provided sync pulse; This item increments upon the reception of the SC-provided sync pulse. |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Time of the Star track subaddress 1 data, relative to the ATLAS SDP GPS Epoch and computed from raw_ace_time_sec/subseconds and etr_delay_tm1. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| etr_counter CHUNKED | UINT_2_BE (:) | STE Star Tracker ETR Counter | counts ATL01/sc2/star_tracker | Star Tracker Electronics (STE) [Star Tracker Status TM#1: Subaddress 1] - External Time Reference (ETR) counter - Used to determine measurement time of reported STE/OH mode status with respect to SC-provided sync pulse; This item increments upon the reception of the SC-provided sync pulse - Sample 1-10 |
| mode_status CHUNKED | UINT_2_BE (:) | STE Star Tracker Mode Status | 1 ATL01/sc2/star_tracker | Star Tracker Electronics (STE) [Star Tracker Status TM#1: Subaddress 1] - Mode Status - Represents the current mode of the STE software . 0 = Initialization 1 = Standby 2 = Memory Read 3 = Memory Write 4 = Self Test 5 = Photo 9 = Angular Rate 10 = Attitude Acquisition 11 = Attitude Tracking 14 = AOM/Attitude Acquisition Phase 15 = AOM/Attitude Tracking Phase All other values invalid Flag Values: ['0', '1', '2', '3', '4', '5', '9', '10', '11', '14', '15'] Flag Meanings: ['init', 'stby', 'mem_read', 'mem_write', 'self_test', 'photon', 'angular_rate', 'att_acq', 'att_track', 'aom_acq', 'aom_track'] |

| Group: /sc/star_tracker/optical_head_1 | | | | |
|--|-----------------------|--|---|--|
| Description | (Attribute) | Contains parameters related to spacecraft Star Tracker Optical Head 1 (STOH1). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Star Tracker data within the Spacecraft Ancillary Science Data Packets. (nominally ten per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| atm_etr_counter CHUNKED | UINT_2_LE (:) | ATM ETR Counter | counts ATL01/sc2/star_tracker/optical_head_1 | Star Tracker Optical Head (STOH) 1 [ATM TM#7: Subaddress 19] - External Time Reference (ETR) counter - Used to determine measurement time of reported quaternions with respect to SC- provided sync pulse; This item increments upon the reception of the SC-provided sync pulse. |
| atm_frame_counter CHUNKED | UINT_2_LE (:) | STOH1 ATM Frame Counter | counts ATL01/sc2/star_tracker/optical_head_1 | Star Tracker Optical Head (STOH) 1 [ATM TM#7: Subaddress 19] - Frame Counter |
| att_qa_x CHUNKED | FLOAT (:) | STOH Attitude Quality (X) | arcsec ATL01/sc2/star_tracker/optical_head_1 converted | Star Tracker Optical Head (STOH) Quality measurement of STOH computed quaternion (X) |
| att_qa_y CHUNKED | FLOAT (:) | STOH Attitude Quality (Y) | arcsec ATL01/sc2/star_tracker/optical_head_1 converted | Star Tracker Optical Head (STOH) Quality measurement of STOH computed quaternion (Y) |
| att_qa_z CHUNKED | FLOAT (:) | STOH Attitude Quality (Z) | arcsec ATL01/sc2/star_tracker/optical_head_1 converted | Star Tracker Optical Head (STOH) Quality measurement of STOH computed quaternion (Z) |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Elapsed GPS seconds since the ATLAS SDP GPS Epoch, computed from raw_ace_time_sec and subseconds and atm_etr_delay_tm7. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| n_stars CHUNKED | INTEGER_1 (:) | STOHx Number of Coherent Stars | counts ATL01/sc2/star_tracker/optical_head_1 | Star Tracker Electronics (STE) [ATM TM#1: Subaddress 13] - Number of coherent stars used in STOH attitude calculation. |
| quaternion1 CHUNKED | DOUBLE (:) | STOH1 Quaternion1 | counts ATL01/sc2/star_tracker/optical_head_1 | Star Tracker Optical Head (STOH) [ATM TM#7: Subaddress 19] - Attitude quaternion 1 - STOH reference frame to Earth-Centered Inertial (ECI) reference frame |
| quaternion2 CHUNKED | DOUBLE (:) | STOH1 Quaternion2 | counts ATL01/sc2/star_tracker/optical_head_1 | Star Tracker Optical Head (STOH) [ATM TM#7: Subaddress 19] - Attitude quaternion 2 - STOH reference frame to Earth-Centered Inertial (ECI) reference frame |
| quaternion3 CHUNKED | DOUBLE (:) | STOH1 Quaternion3 | counts ATL01/sc2/star_tracker/optical_head_1 | Star Tracker Optical Head (STOH) [ATM TM#7: Subaddress 19] - Attitude quaternion 3 - STOH reference frame to Earth-Centered Inertial (ECI) reference frame |
| quaternion4 CHUNKED | DOUBLE (:) | STOH1 Quaternion4 | counts ATL01/sc2/star_tracker/optical_head_1 | Star Tracker Optical Head (STOH) [ATM TM#7: Subaddress 19] - Attitude quaternion 4 - STOH reference frame to Earth-Centered Inertial (ECI) reference frame |

| seq_mode_st CHUNKED | INTEGER_1 (:) | Sequencing Mode Status | counts ATL01/sc2/star_tracker/optical_head_1 | Star Tracker Optical Head (STOH) [Star Tracker Status TM#1: Subaddress 1] - Sequencing (Mode) Status Flag Values: ['0', '1', '2', '3', '4', '5', '6', '7'] Flag Meanings: ['off', 'standby', 'photo', 'acquire', 'track', 'autotest', 'win_acq', 'powered'] |
|---|--------------------------|--|--|---|
| Group: /sc/star_tracker/optical_head_2 | | | | |
| Description | (Attribute) | Contains parameters related to spacecraft Star Tracker Optical Head 2 (STOH2). | | |
| data_rate | (Attribute) | Data within this group are stored at the data rate of the source Star Tracker data within the Spacecraft Ancillary Science Data Packets. (nominally ten per second.) | | |
| Label (Layout) | Datatype (Dimensions) | long_name (standard_name) | units source | description |
| atm_etr_counter CHUNKED | UINT_2_LE (:) | ATM ETR Counter | counts ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) 2 [ATM TM#8: Subaddress 20] - External Time Reference (ETR) counter - Used to determine measurement time of reported quaternions with respect to SC- provided sync pulse; This item increments upon the reception of the SC-provided sync pulse |
| atm_frame_counter CHUNKED | UINT_2_LE (:) | STOH2 ATM Frame Counter | counts ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) 2 [ATM TM#8: Subaddress 20] - Frame Counter |
| att_qa_x CHUNKED | FLOAT (:) | STOH Attitude Quality (X) | arcsec ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) Quality measurement of STOH computed quaternion (X) |
| att_qa_y CHUNKED | FLOAT (:) | STOH Attitude Quality (Y) | arcsec ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) Quality measurement of STOH computed quaternion (Y) |
| att_qa_z CHUNKED | FLOAT (:) | STOH Attitude Quality (Z) | arcsec ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) Quality measurement of STOH computed quaternion (Z) |
| delta_time CHUNKED | DOUBLE (:) | Elapsed GPS seconds time | seconds since 2018-01-01 Derived via Time Tagging | Elapsed GPS seconds from the ATLAS SDP GPS Epoch, computed from raw_ace_time_sec and subseconds and atm_etr_delay_tm8. The ATLAS Standard Data Products (SDP) epoch offset is defined within /ancillary_data/atlas_sdp_gps_epoch as the number of GPS seconds between the GPS epoch (1980-01-06T00:00:00.000000Z UTC) and the ATLAS SDP epoch. By adding the offset contained within atlas_sdp_gps_epoch to delta time parameters, the time in gps_seconds relative to the GPS epoch can be computed. |
| n_stars CHUNKED | INTEGER_1 (:) | STOHx Number of Coherent Stars | counts ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Electronics (STE) [ATM TM#1: Subaddress 13] - Number of coherent stars used in STOH attitude calculation |
| quaternion1 CHUNKED | DOUBLE (:) | STOH1 Quaternion1 | counts ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) [ATM TM#7: Subaddress 19] - Attitude quaternion 1 - STOH reference frame to Earth-Centered Inertial (ECI) reference frame |
| quaternion2 CHUNKED | DOUBLE (:) | STOH1 Quaternion2 | counts ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) [ATM TM#7: Subaddress 19] - Attitude quaternion 2 - STOH reference frame to Earth-Centered Inertial (ECI) reference frame |
| quaternion3 CHUNKED | DOUBLE (:) | STOH1 Quaternion3 | counts ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) [ATM TM#7: Subaddress 19] - Attitude quaternion 3 - STOH reference frame to Earth-Centered Inertial (ECI) reference frame |
| quaternion4 CHUNKED | DOUBLE (:) | STOH1 Quaternion4 | counts ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) [ATM TM#7: Subaddress 19] - Attitude quaternion 4 - STOH reference frame to Earth-Centered Inertial (ECI) reference frame |
| seq_mode_st CHUNKED | INTEGER_1 (:) | Sequencing Mode Status | counts ATL01/sc2/star_tracker/optical_head_2 | Star Tracker Optical Head (STOH) [Star Tracker Status TM#1: Subaddress 1] - Sequencing (Mode) Status. A value of 127 indicates that the data could not be filled from the vc5 packets. Flag Values: ['0', '1', '2', '3', '4', '5', '6', '7'] Flag Meanings: ['off', 'standby', 'photo', 'acquire', 'track', 'autotest', 'win_acq', 'powered'] |